
From Wobbles to Worlds:

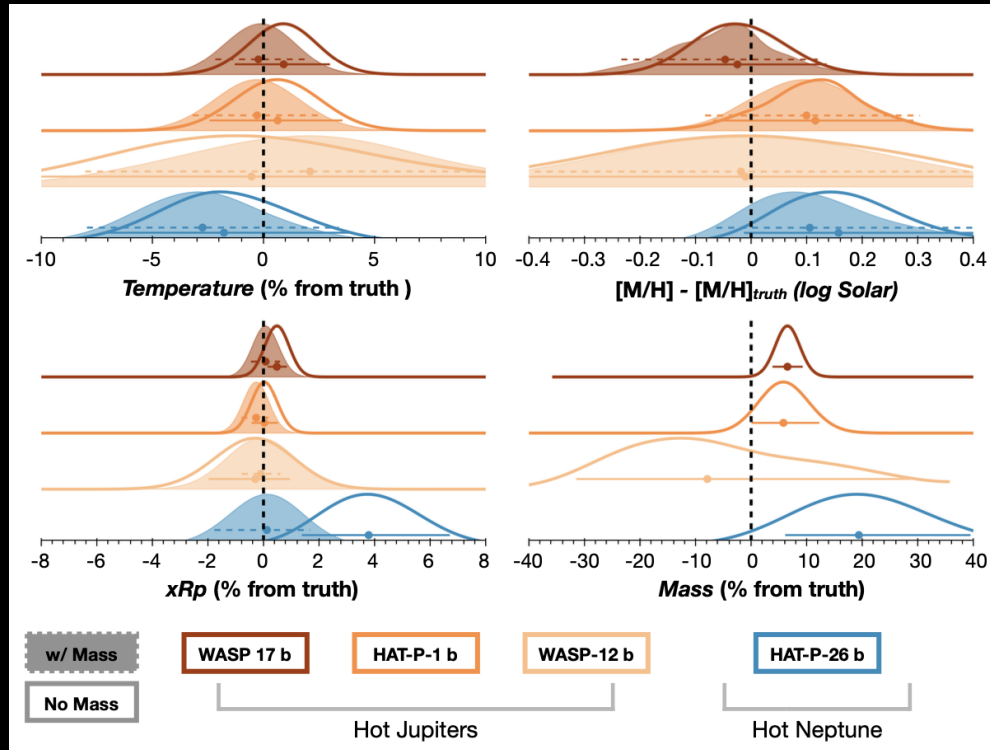
The role of precision
radial velocities in
exoplanet discovery
and characterization

Dr. Jennifer Burt
Exoplanet Exploration Program Office

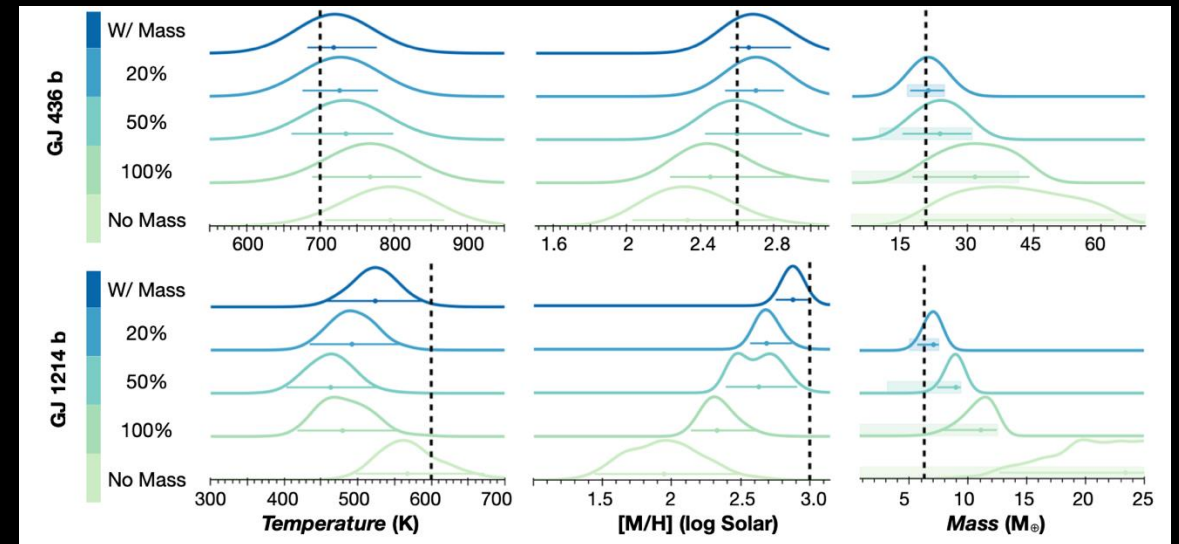
“Mass is the most fundamental property of a planet, and knowledge of a planet’s mass (along with a knowledge of its radius) is essential to understand its bulk composition and to interpret spectroscopic features in its atmosphere”

**--2018 National Academy of Sciences
Exoplanet Science Strategy report**

Mass is crucial to accurate interpretations of a planet's atmospheric transmission spectrum

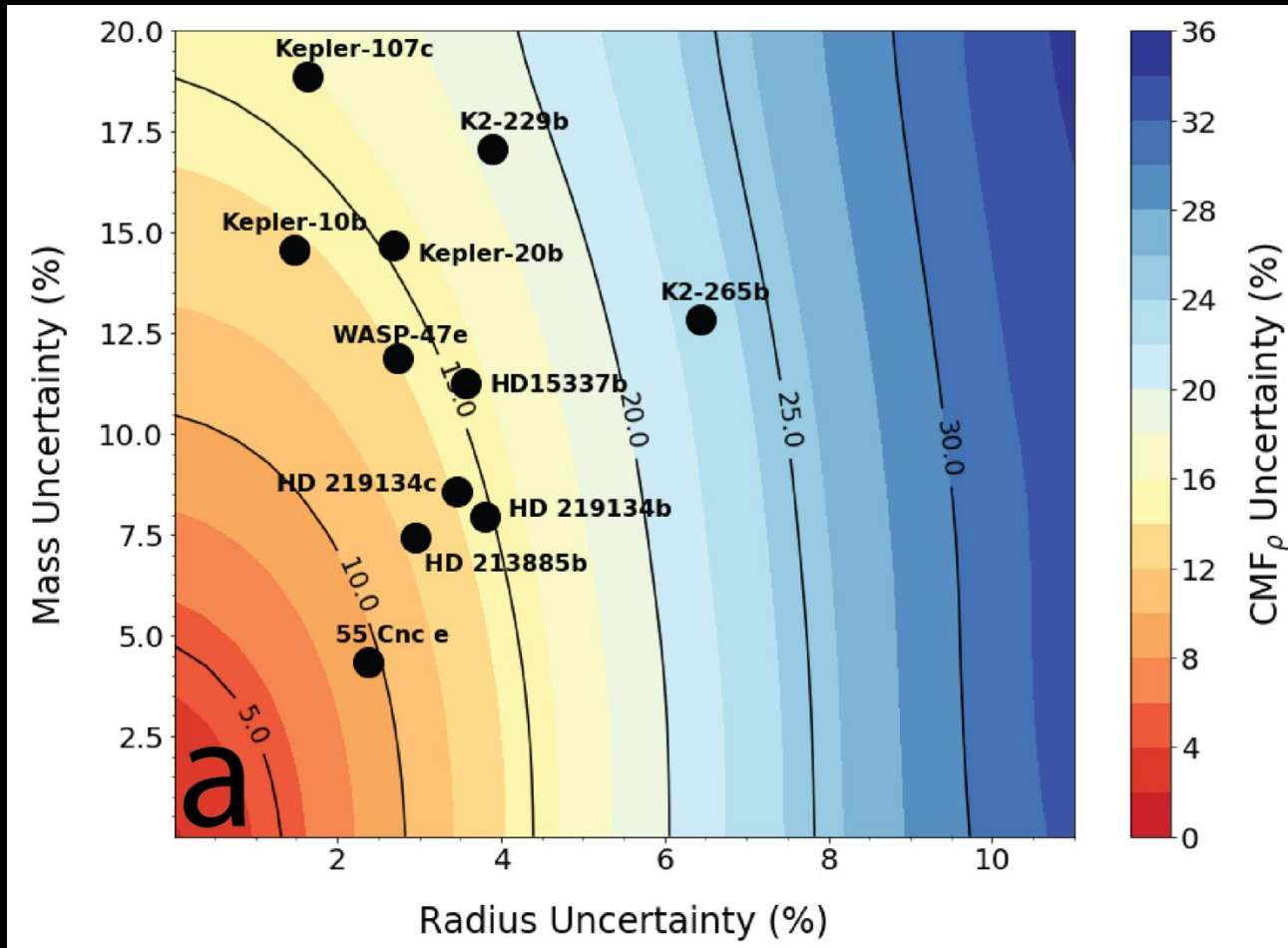


Hot Jupiters and Neptunes require
 2σ mass measurements



Temperate planets smaller than
Neptune require 5σ mass measurements

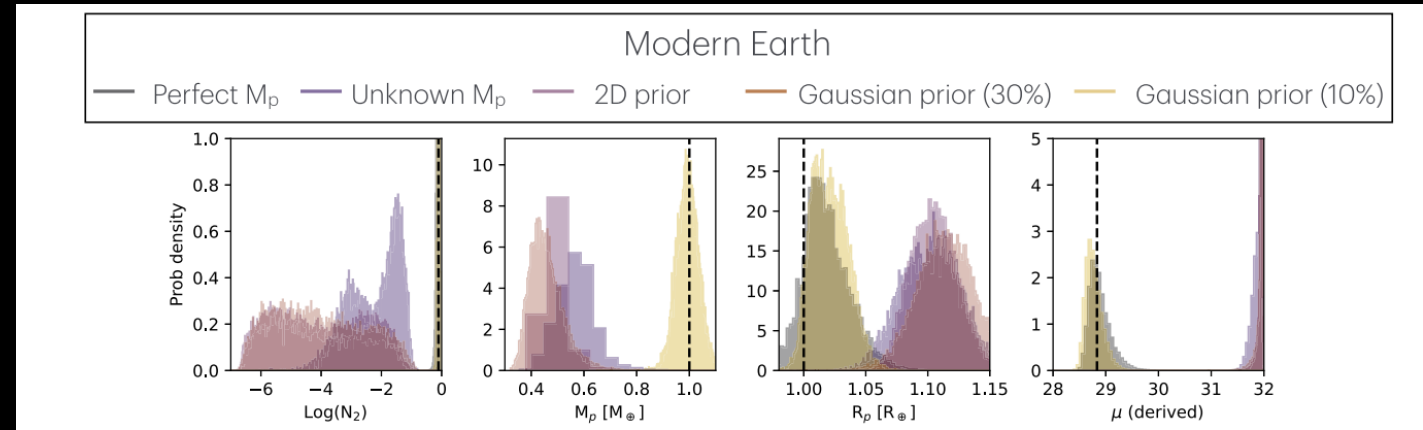
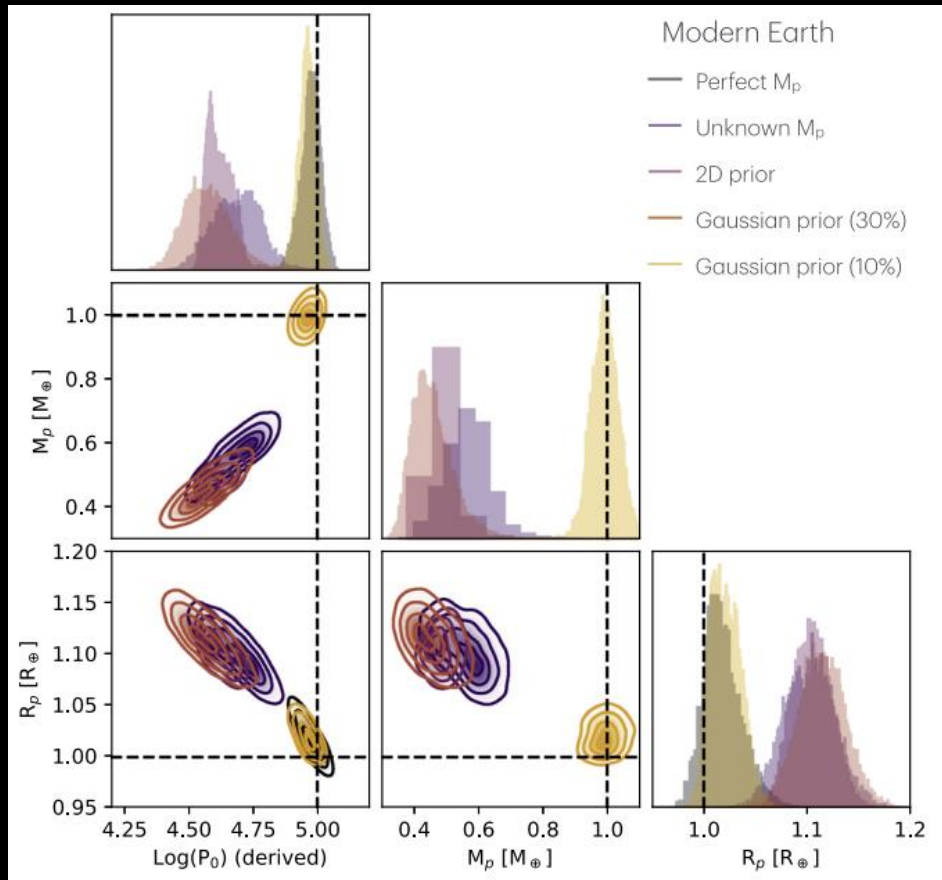
As well as to interpretations of its interior composition



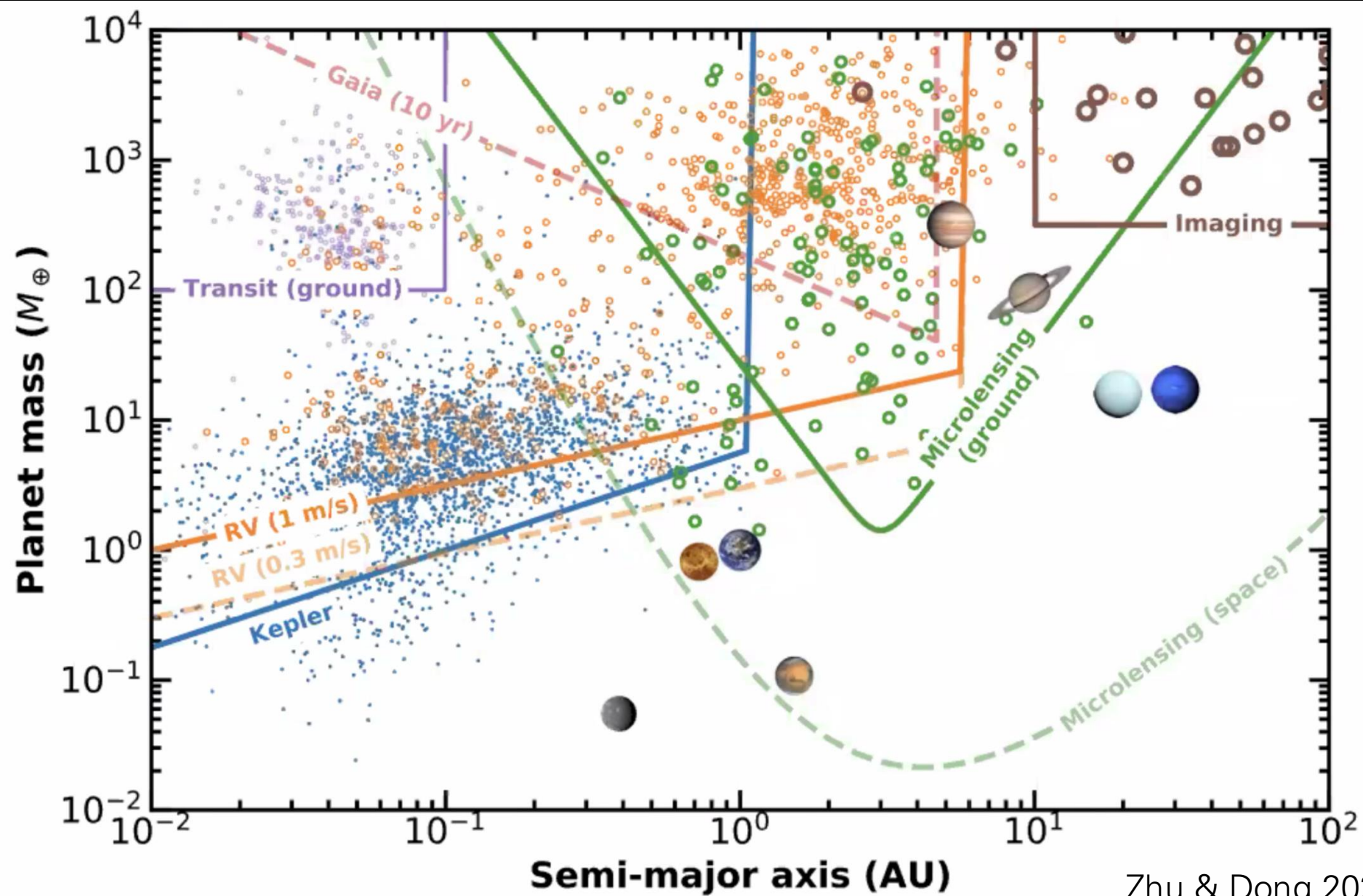
Mass uncertainties better than 5σ are also sufficient to characterize the interiors of small, transiting, planets

(Assuming you also know the Fe, Mg, and Si abundances of the star to better than 0.01 dex)

This is likely also true for reflected light spectra (HWO)



Mass uncertainties better than 10σ are necessary to accurately identify secondary gasses in the atmospheres of Earth-like planets

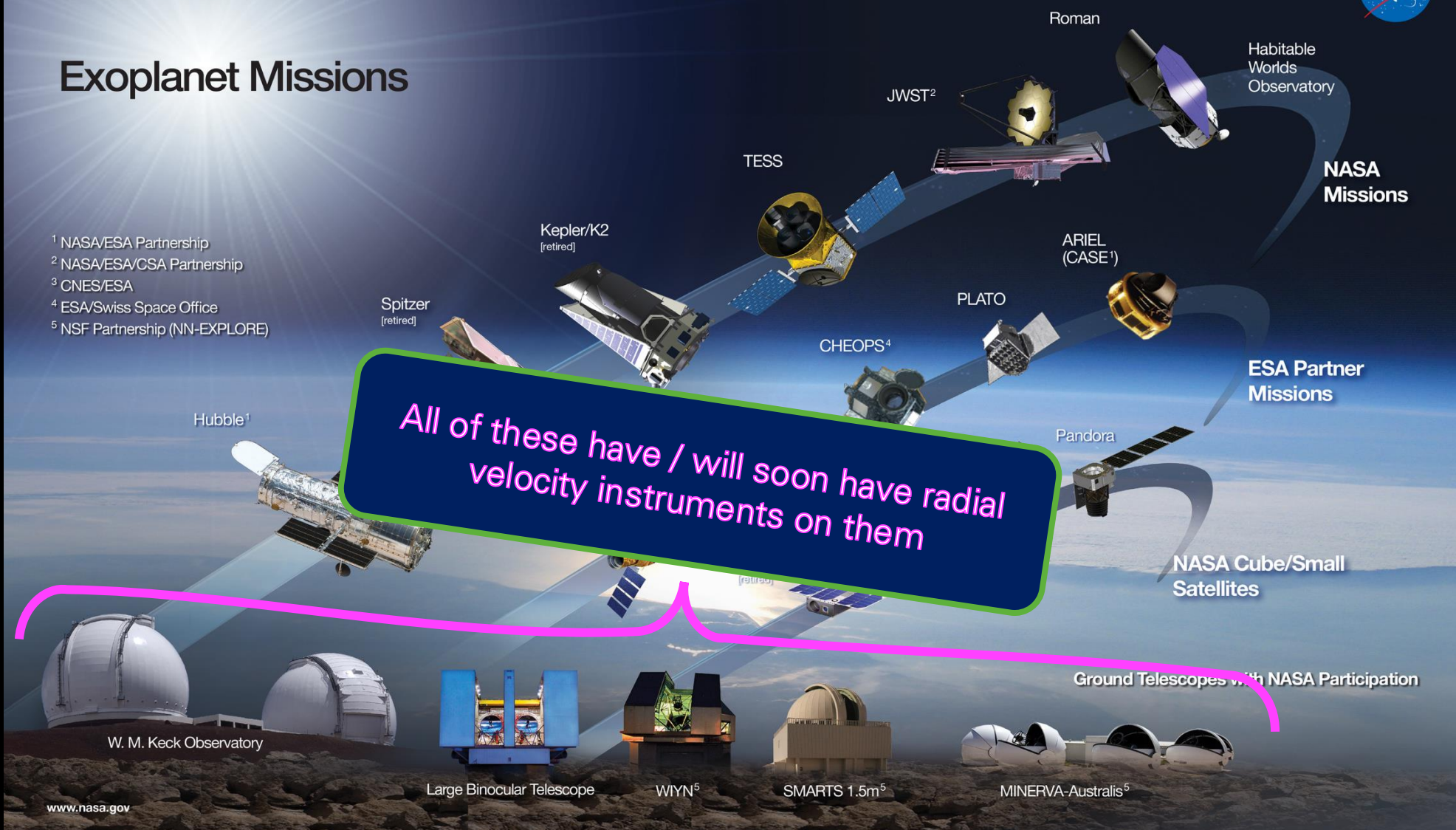


National Aeronautics and Space Administration



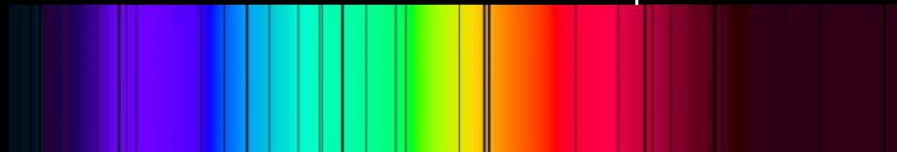
Exoplanet Missions

- ¹ NASA/ESA Partnership
- ² NASA/ESA/CSA Partnership
- ³ CNES/ESA
- ⁴ ESA/Swiss Space Office
- ⁵ NSF Partnership (NN-EXPLORE)



Radial Velocities are an indirect detection technique

Spectrum as seen from Earth, imprinted
with solar and telluric absorption lines

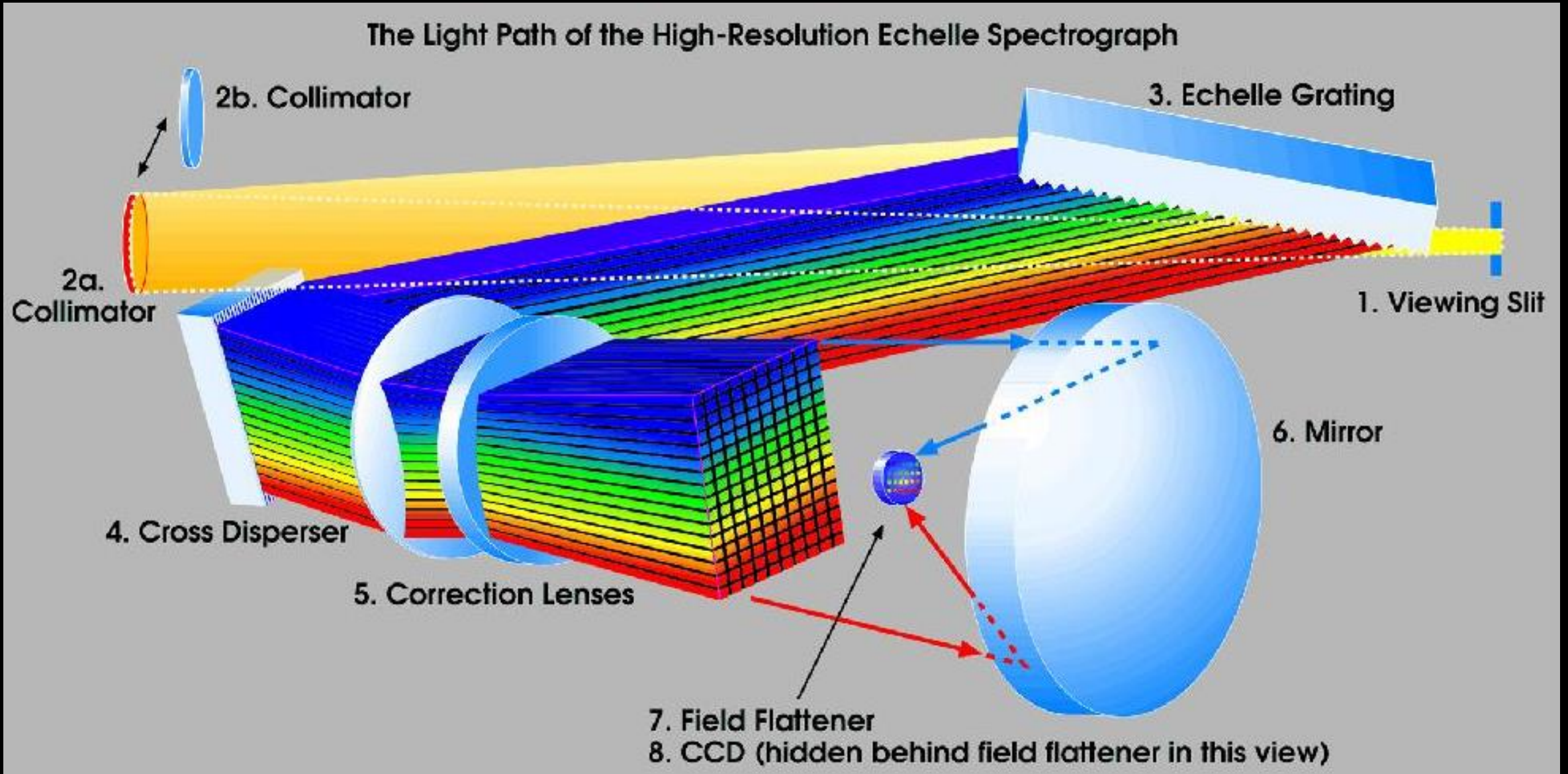


Cooler outer layers that
contain atomic elements

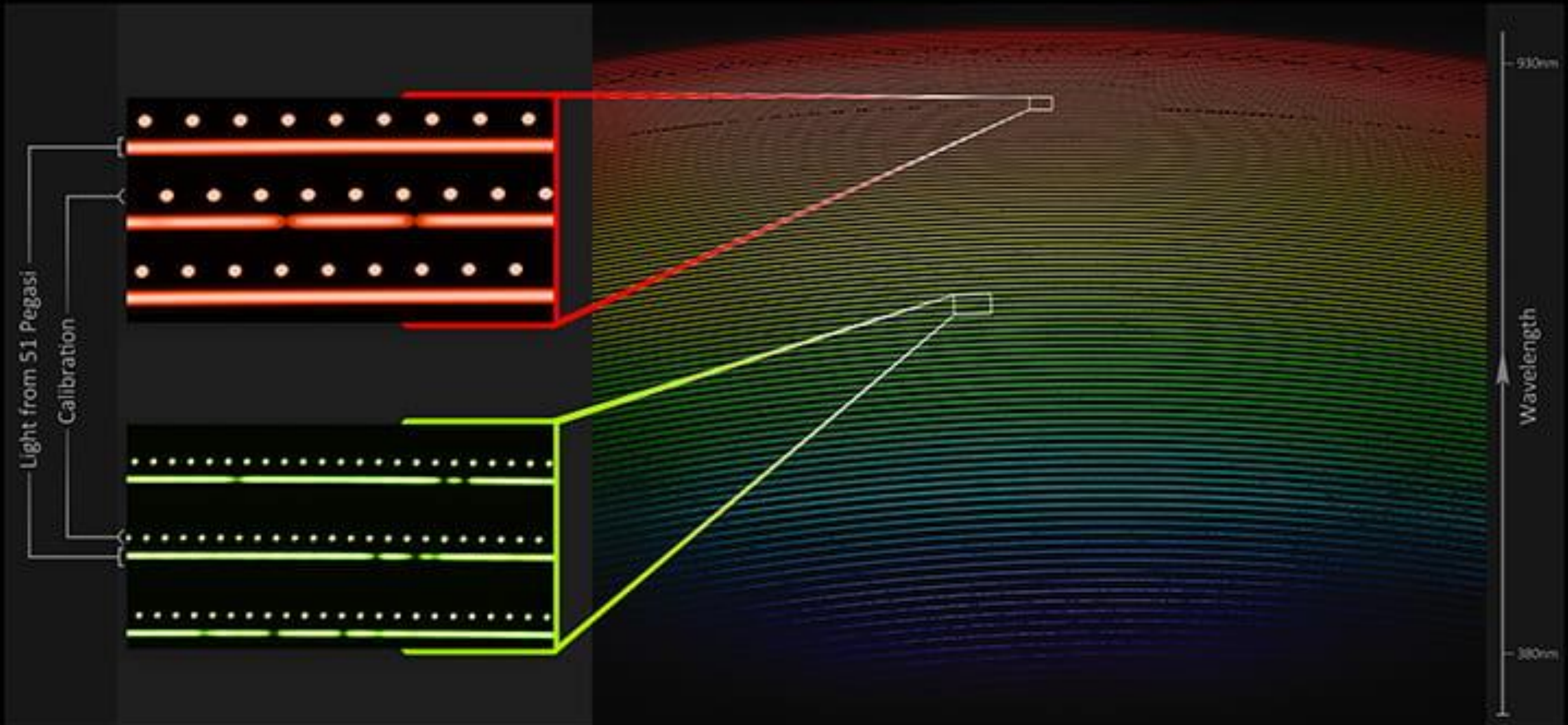


Continuous spectrum
generated inside the
sun

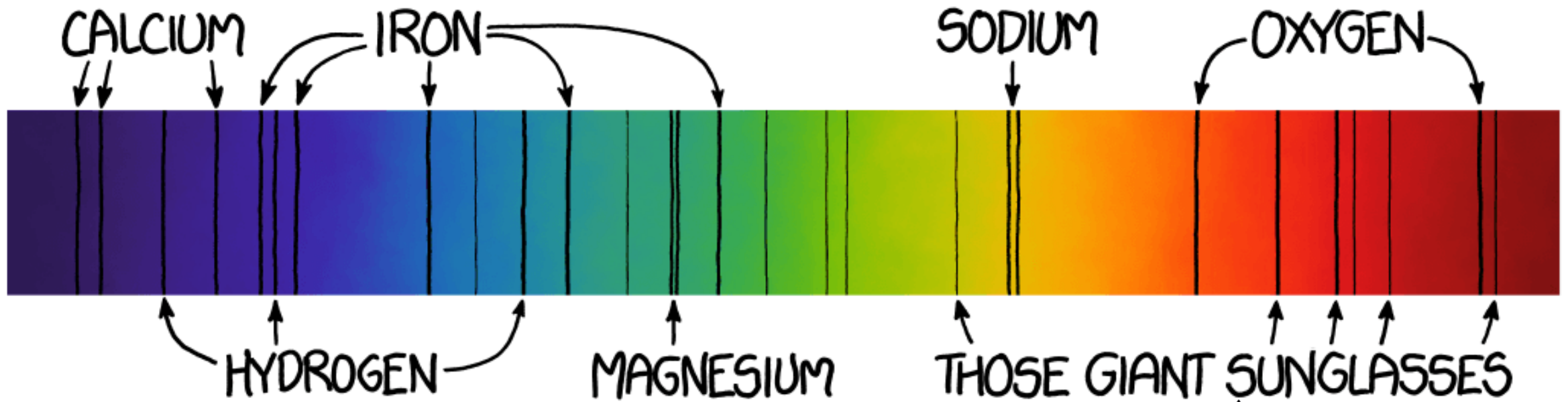
Échelle spectrographs



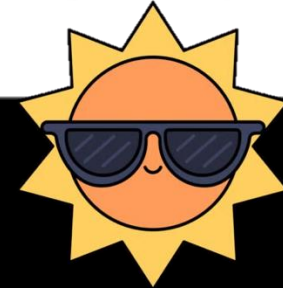
Échelle spectrographs

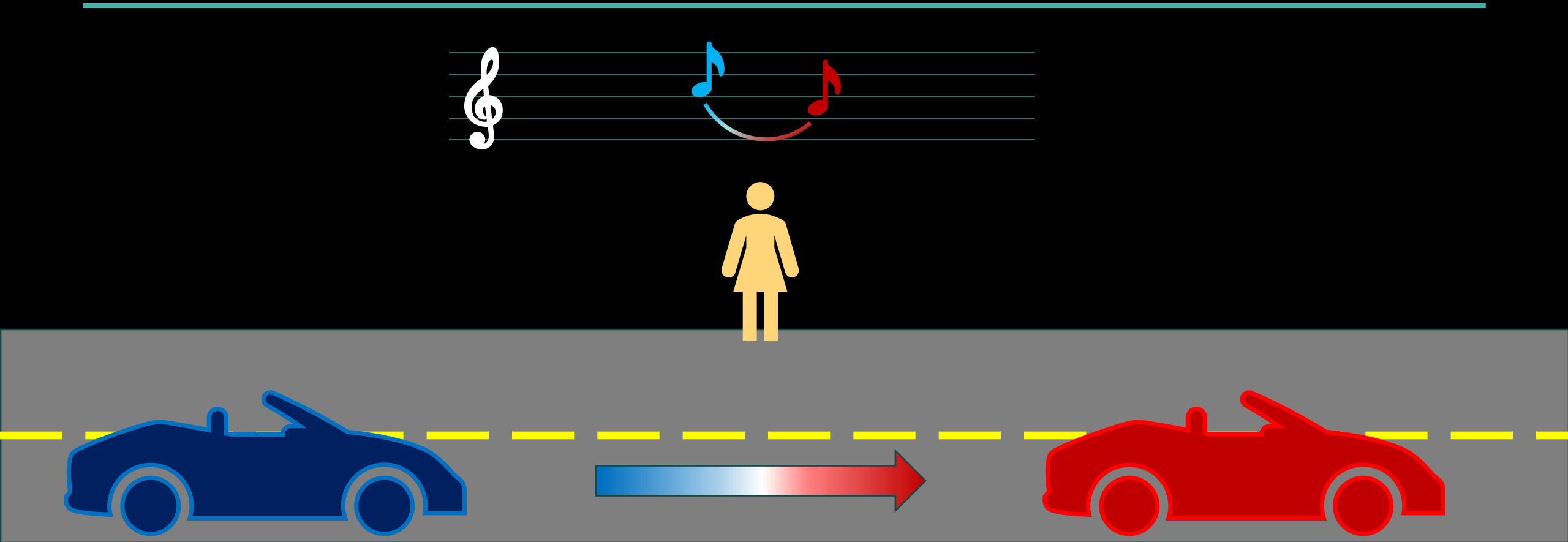


THE SUN'S SPECTRAL LINES

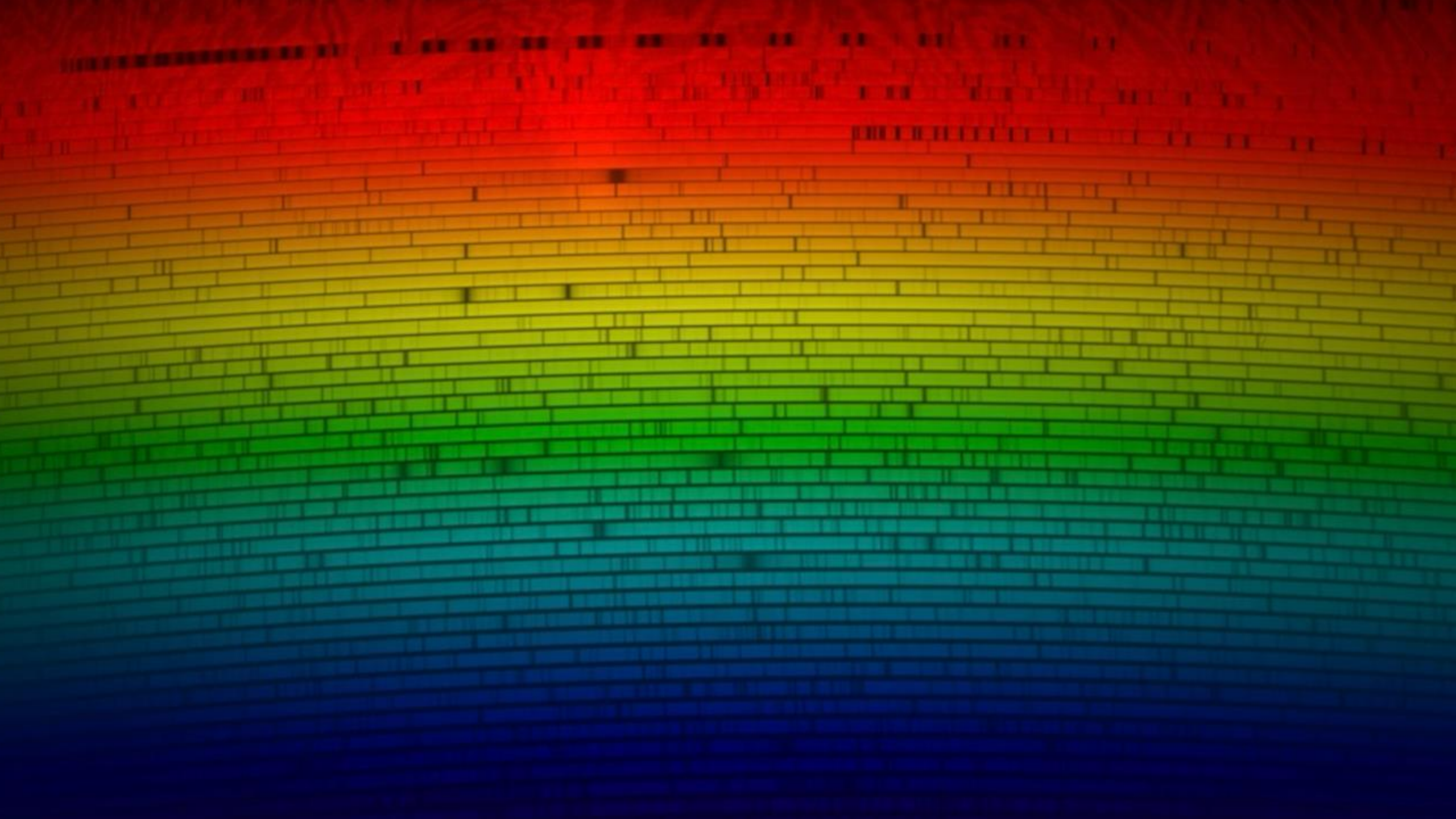


<https://xkcd.com/1733/>





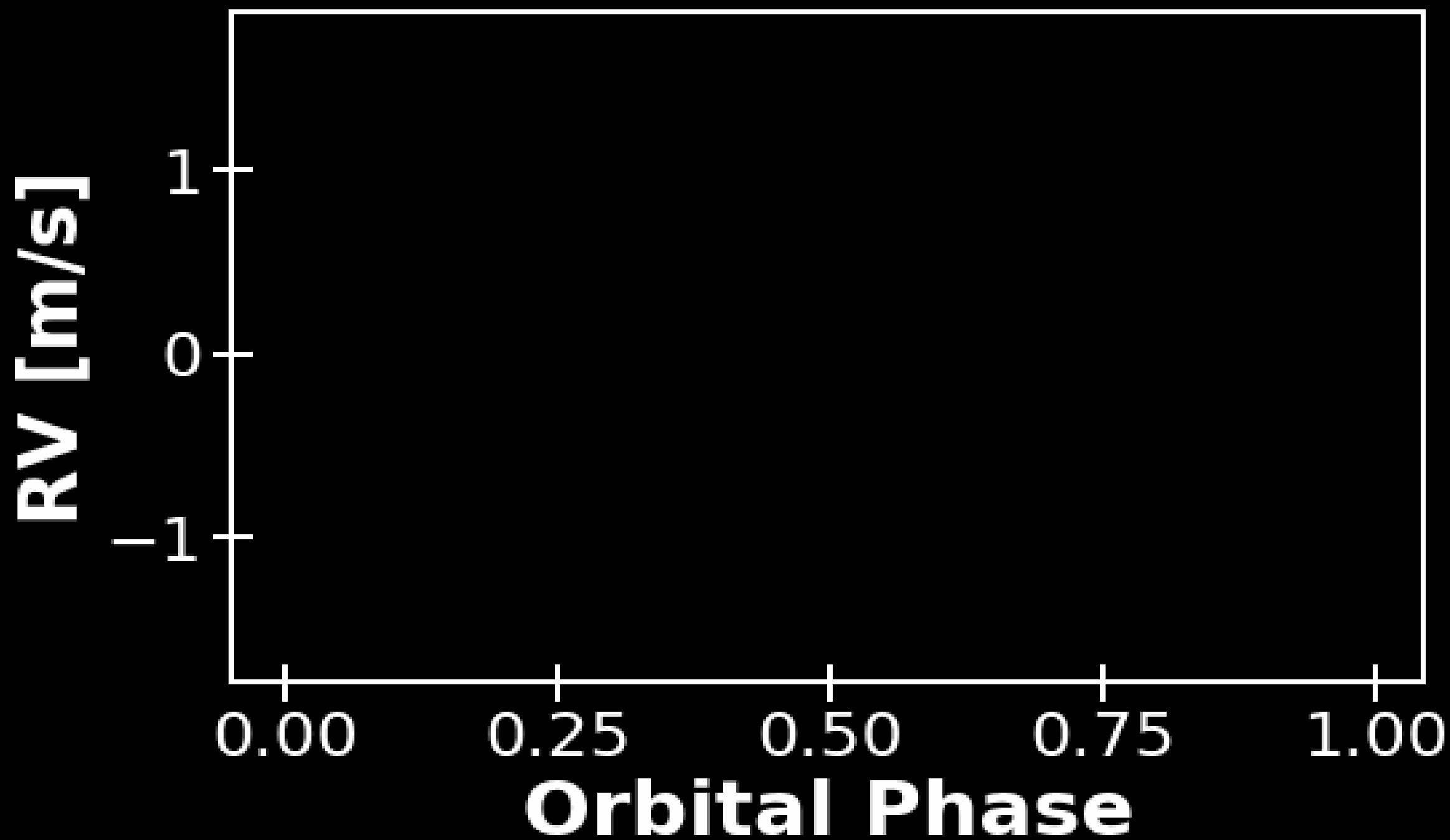
$$f_{obs} = \frac{(v + v_o)}{(v - v_s)} f$$



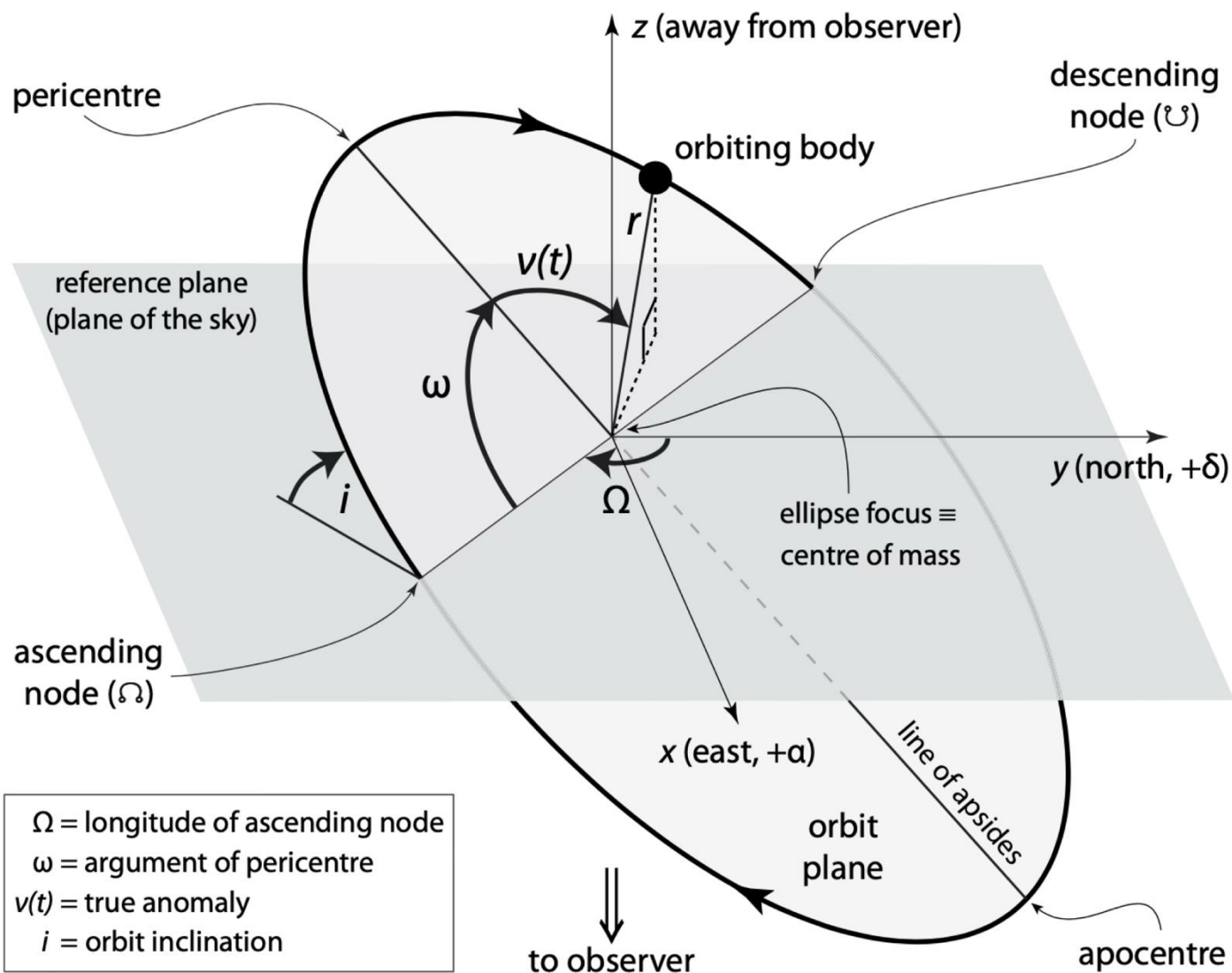
$$f_{obs} = \frac{(v + v_o)}{(v - v_s)} f$$

$$\frac{\Delta\lambda}{\lambda_o} = \frac{v}{c}$$





Planetary Orbits



Need 7 elements to define a Keplerian orbit in 3D

a : semi-major axis of the orbit

e : eccentricity of the orbit

P : orbital period

t_p : position of the planet at pericenter

i : orbital inclination w.r.t. the reference plane. Zero inclination is face on orbit (can't do RV), 90° inclination is edge on orbit (best for RV)

Ω : longitude of the ascending node, where the object moves away from the observer through the plane of reference

ω : angular coordinate of the object's pericenter relative to its ascending node, measured in the orbital plane and in the direction of motion.

Planetary Orbits

The parameters we generally derive when fitting RV data are a little different

Period [days] : Time the planet takes to complete one orbit around its host star

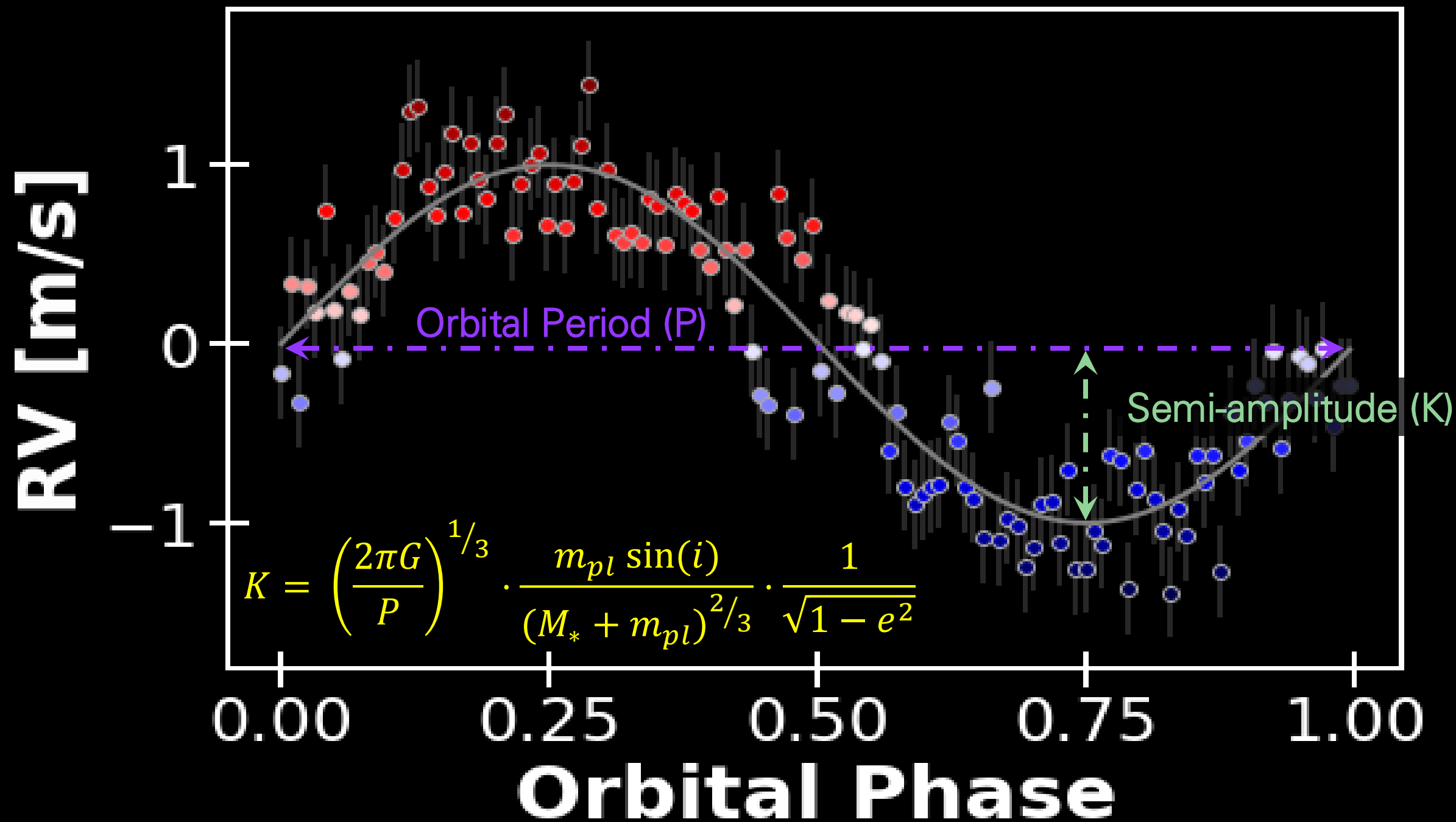
Semi-amplitude [m/s] : Peak velocity of the reflex motion a planet imparts on its host star

Eccentricity : Ellipticity of the planet's orbit

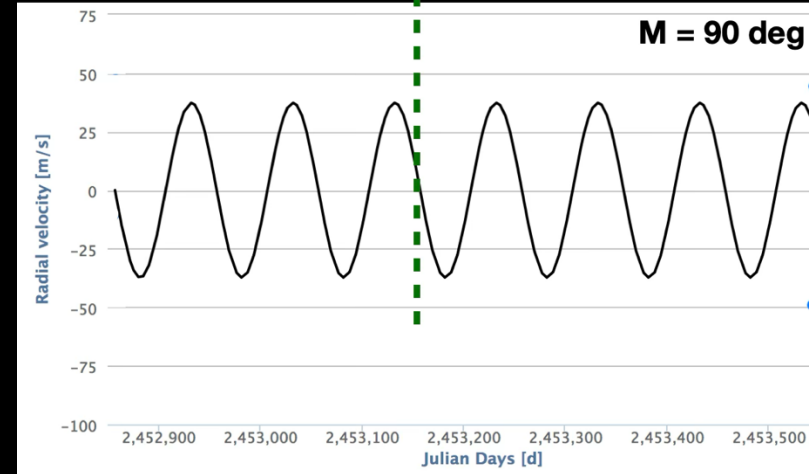
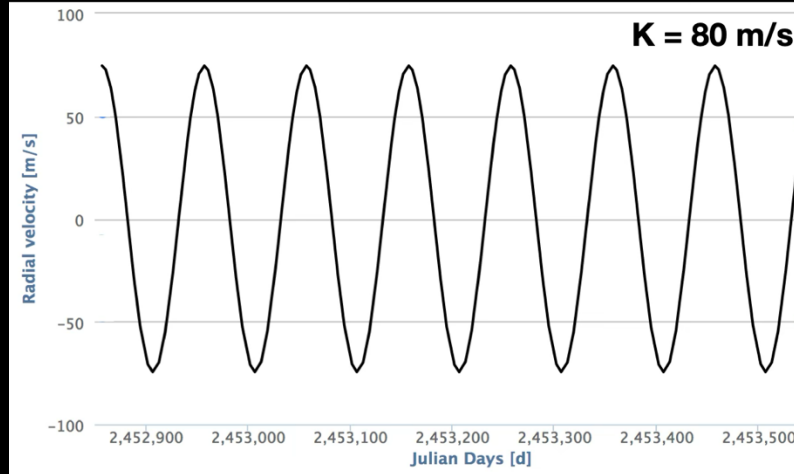
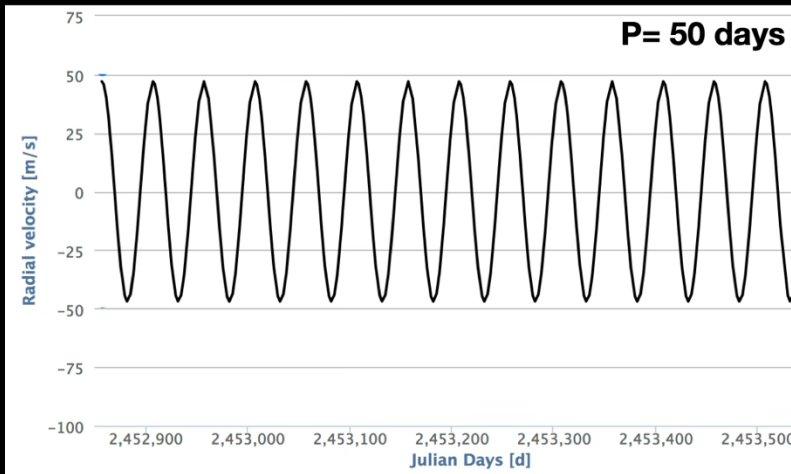
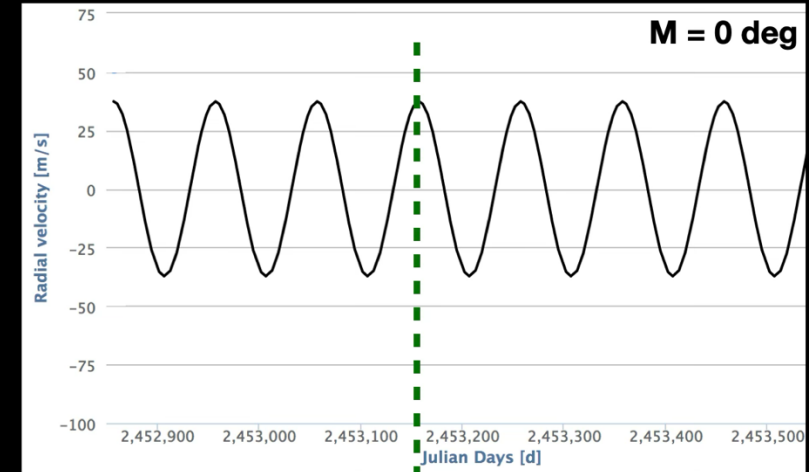
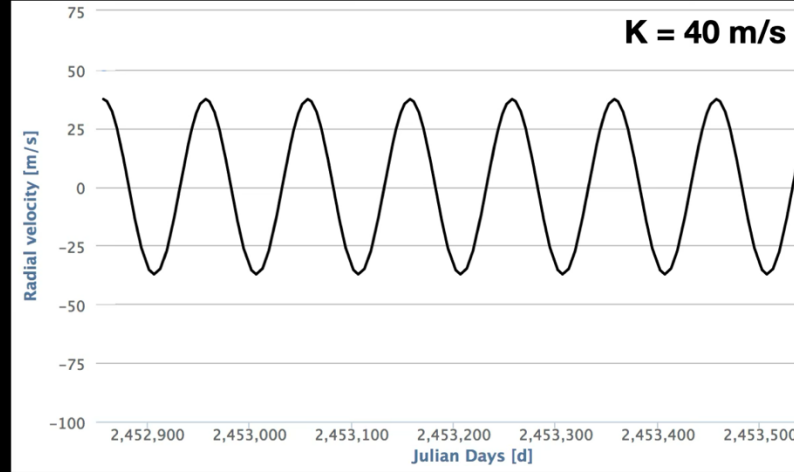
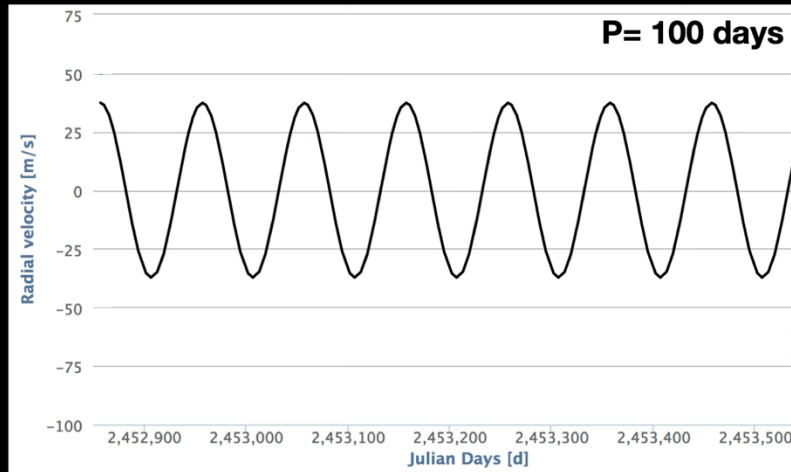
Longitude of periastron [deg] : Orbital angle at which the planet goes through periastron

Time of periastron [JD] : Date when the planet passes through its periastron point

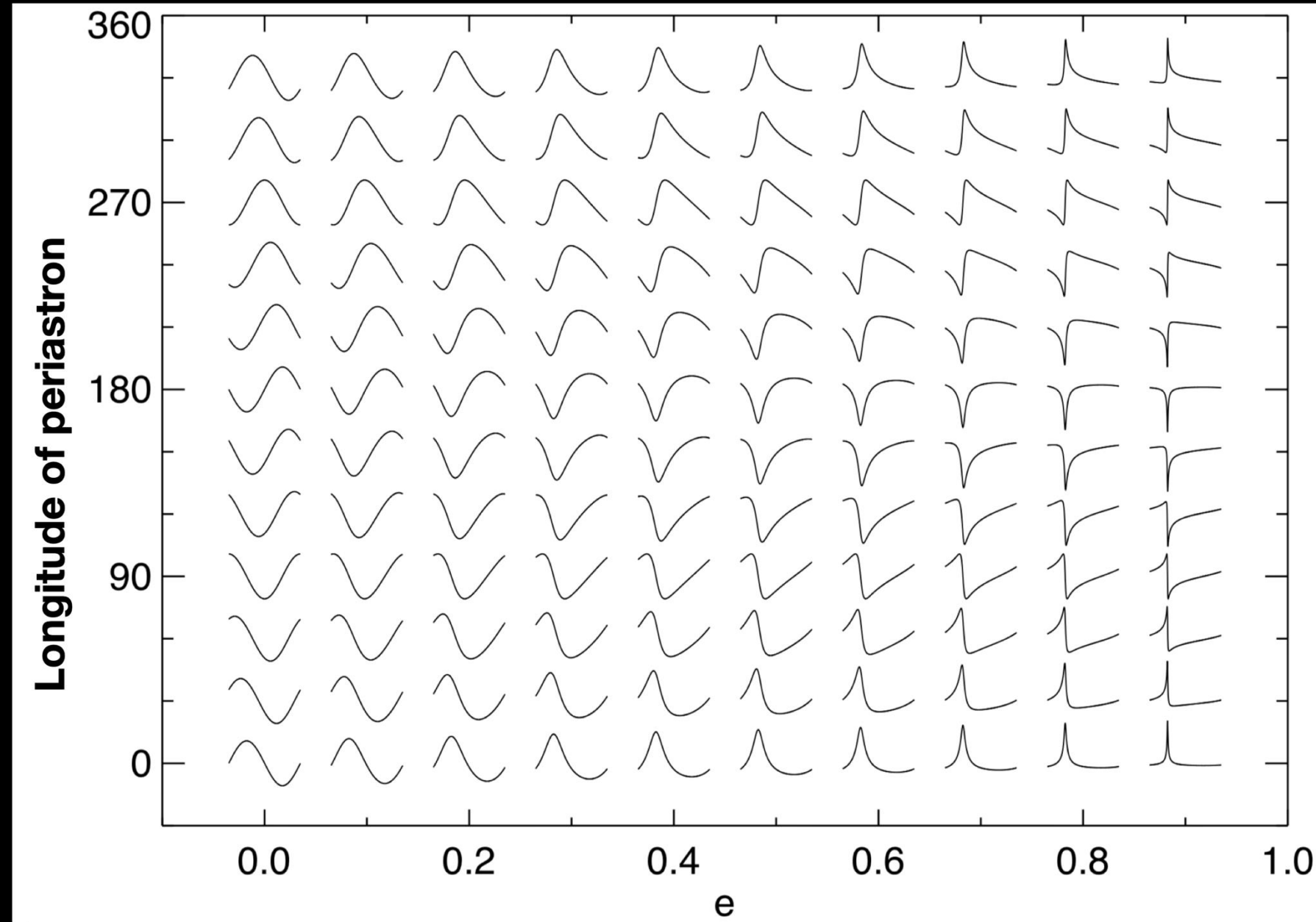
Mean anomaly [deg] : Angular distance from pericenter the planet would have if $e=0$

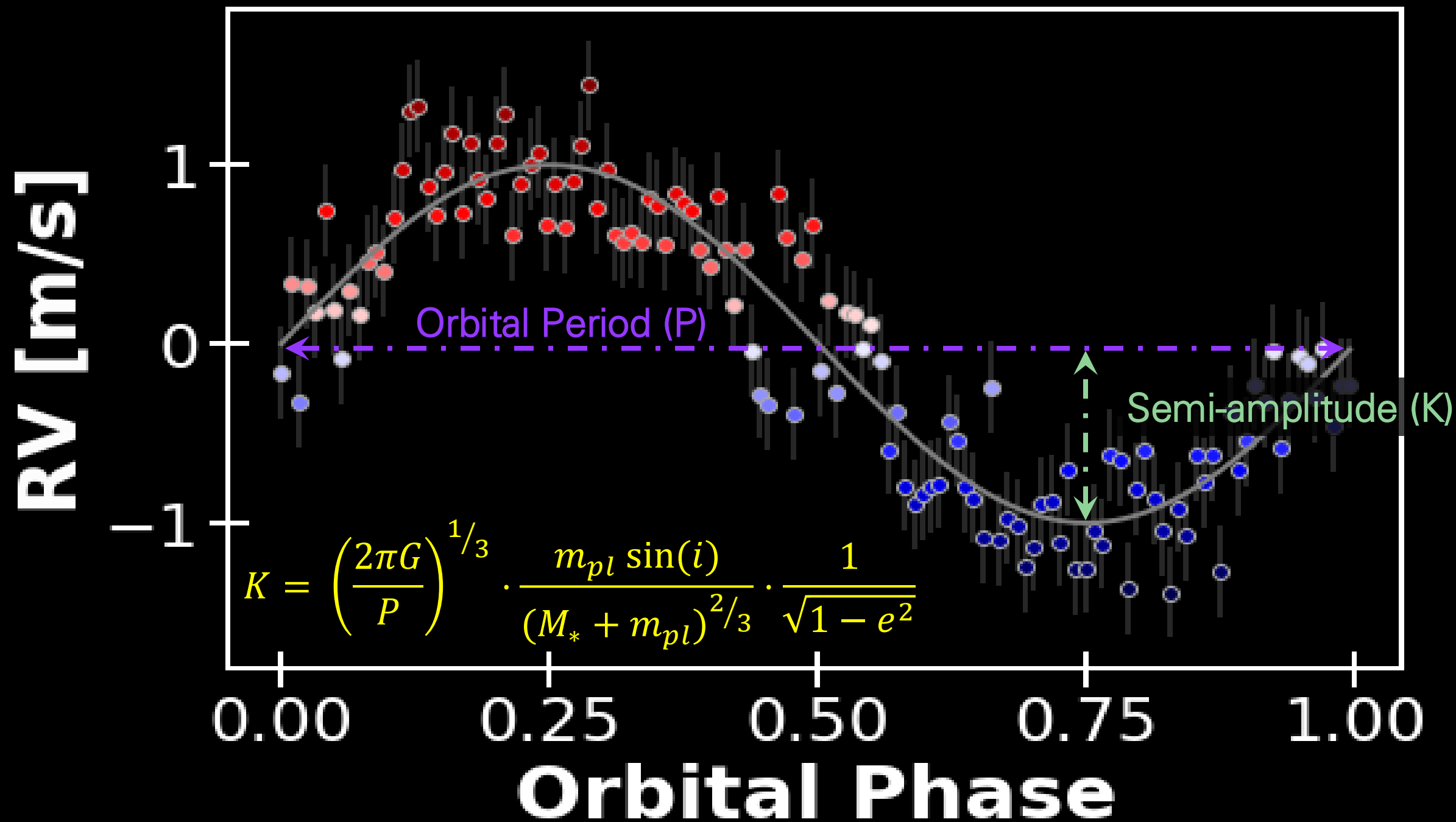


What do these parameters do to the shape of an RV orbit?



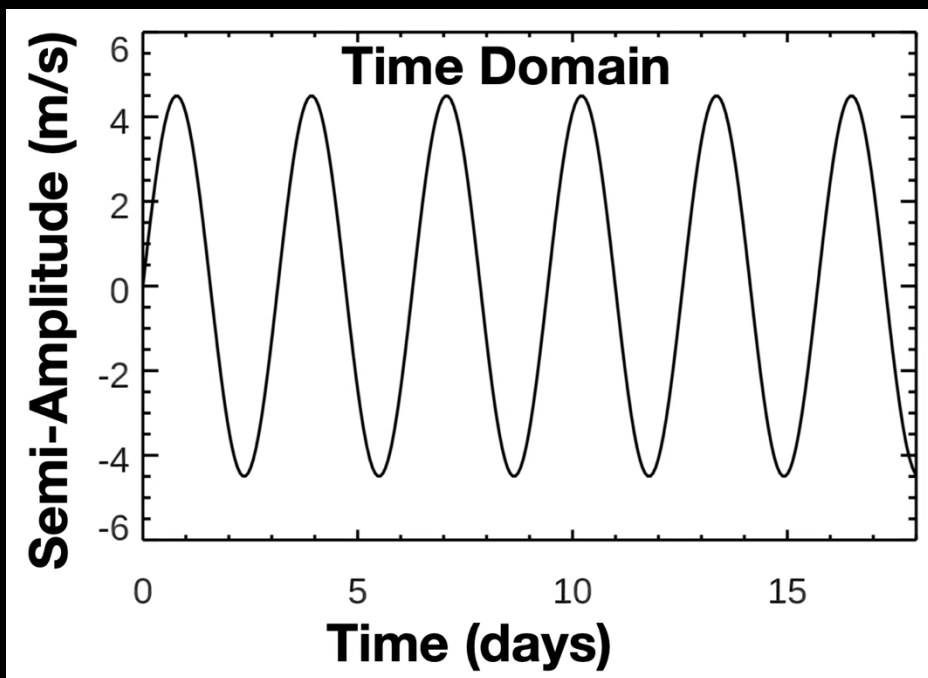
What do these parameters do to the shape of an RV orbit?



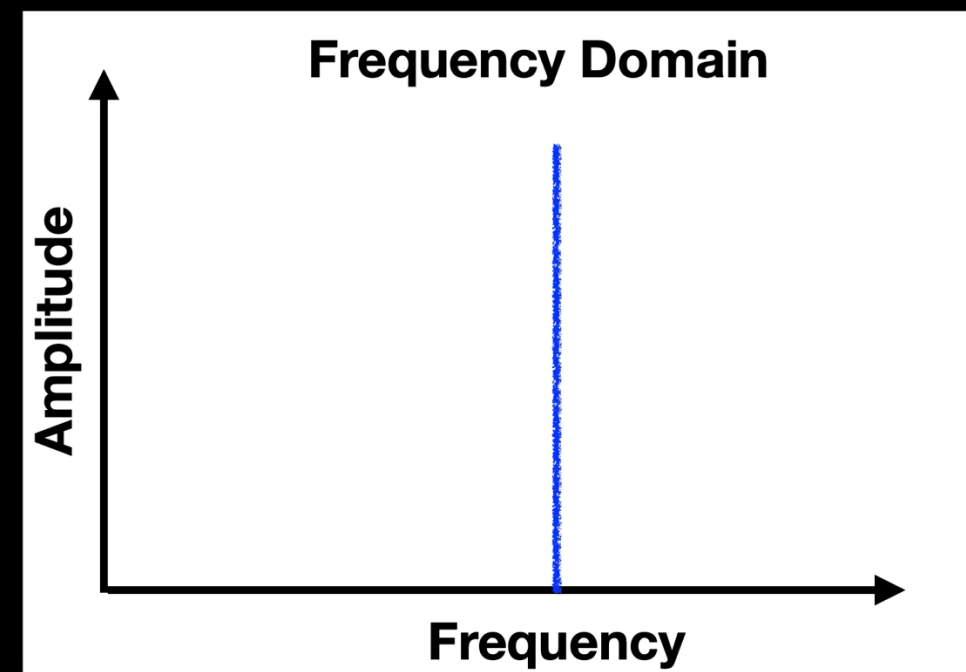


RV points to planets

Idealized case: Use a discrete fourier transform (DFT) to identify perfectly sinusoidal signals in time series data

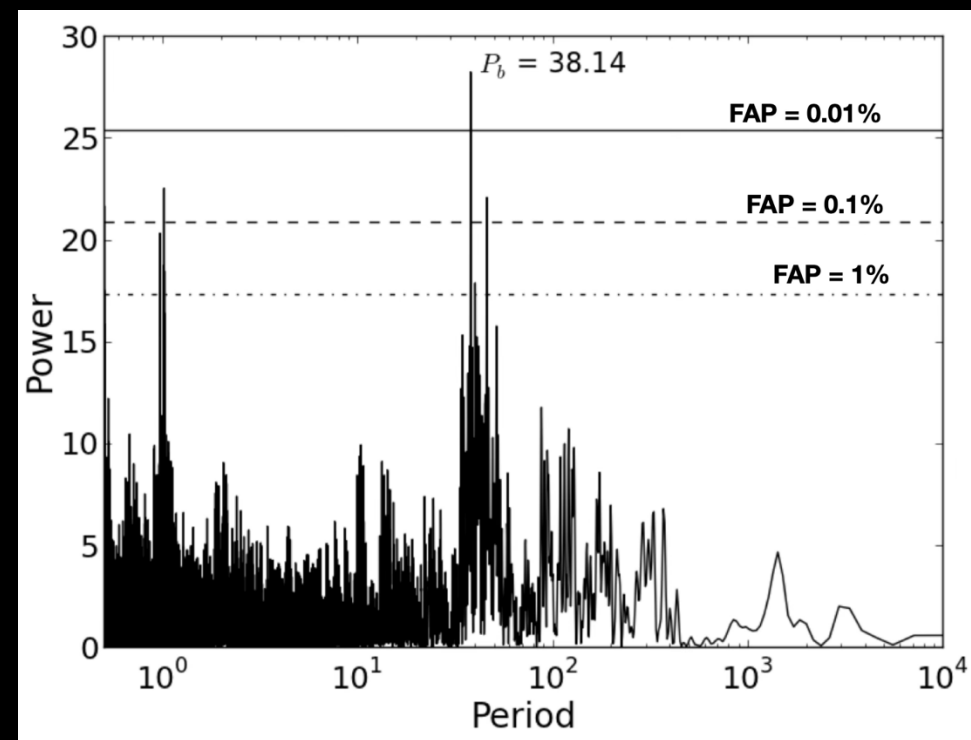
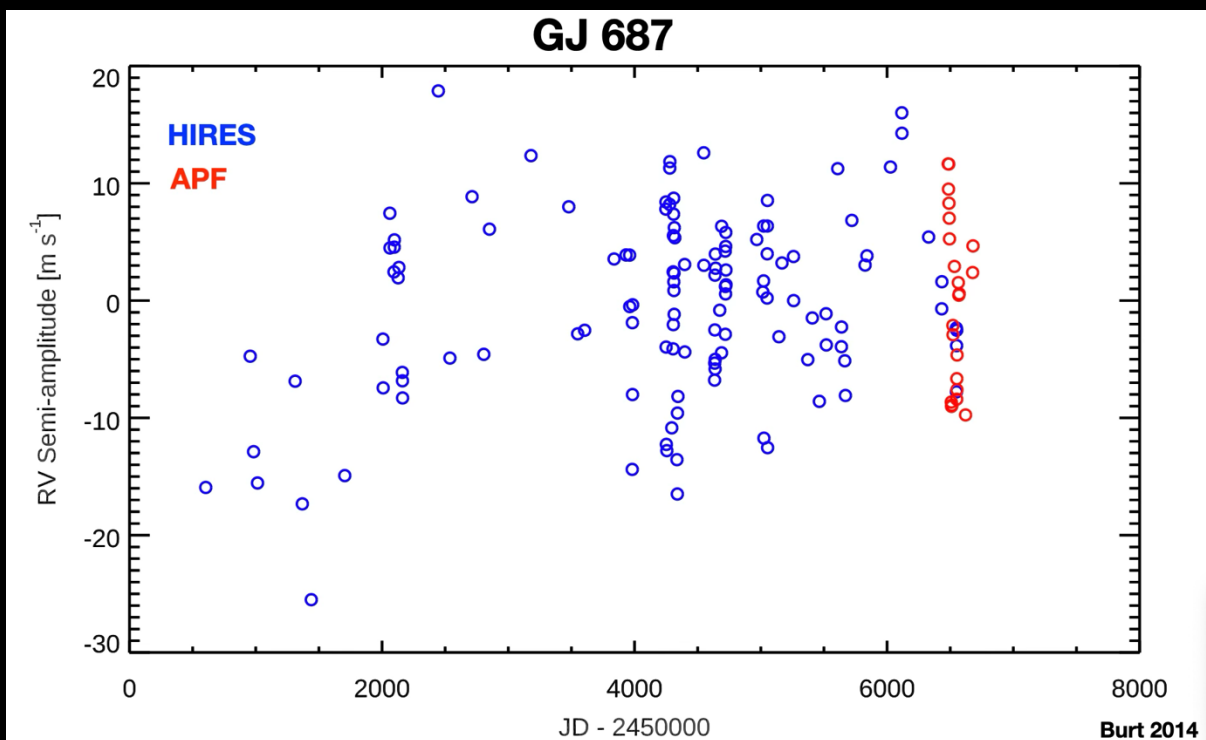


$$\text{DFT}_X(\omega) = \sum_{i=1}^N X(t_j) e^{-i\omega t_j}$$



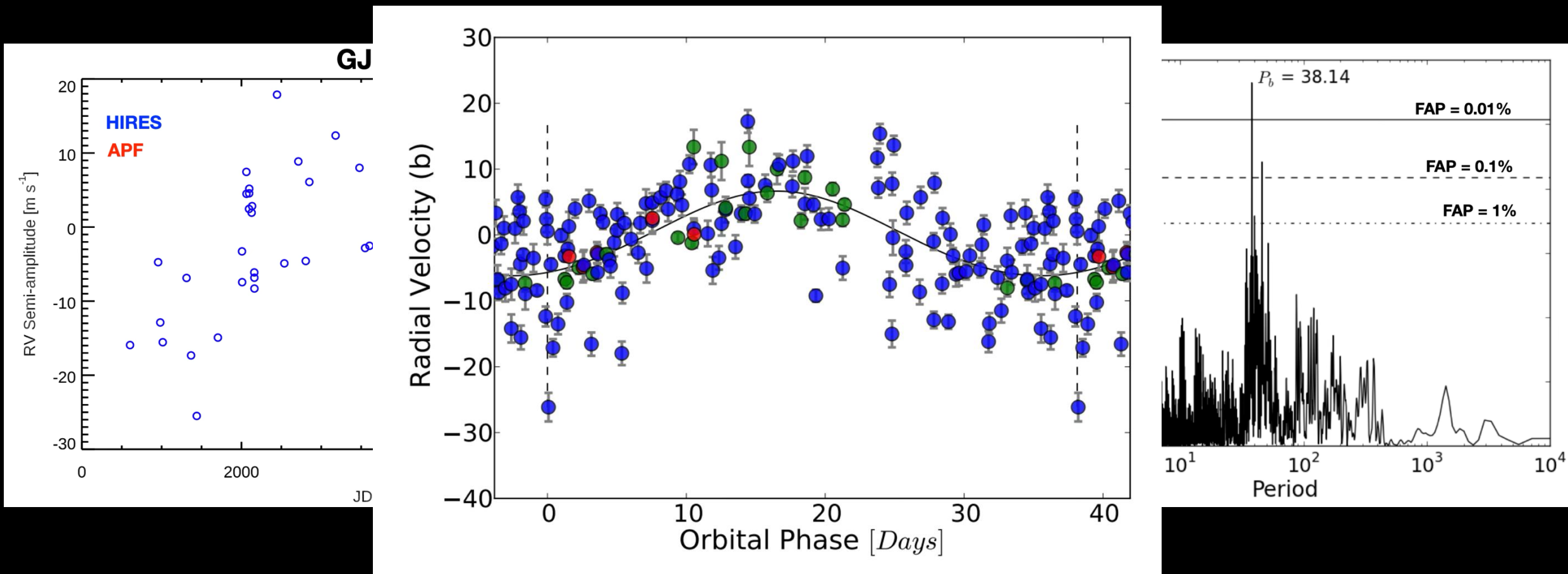
RV points to planets

Realistic case: Use a Lomb-Scargle periodogram to identify sinusoidal signals in unevenly sampled time series data

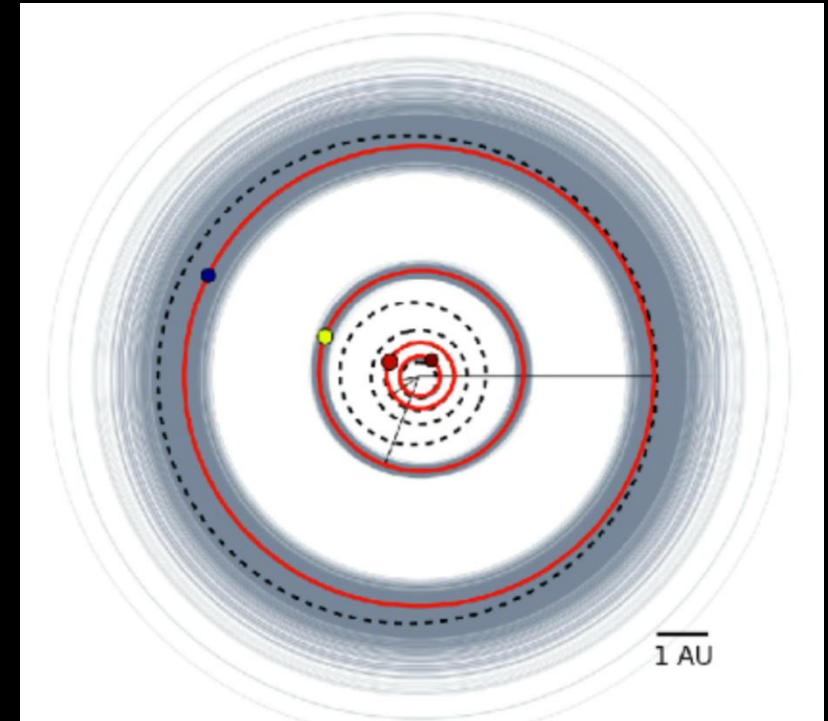
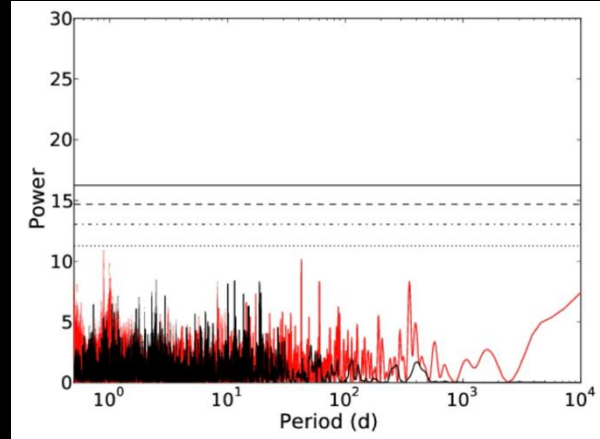
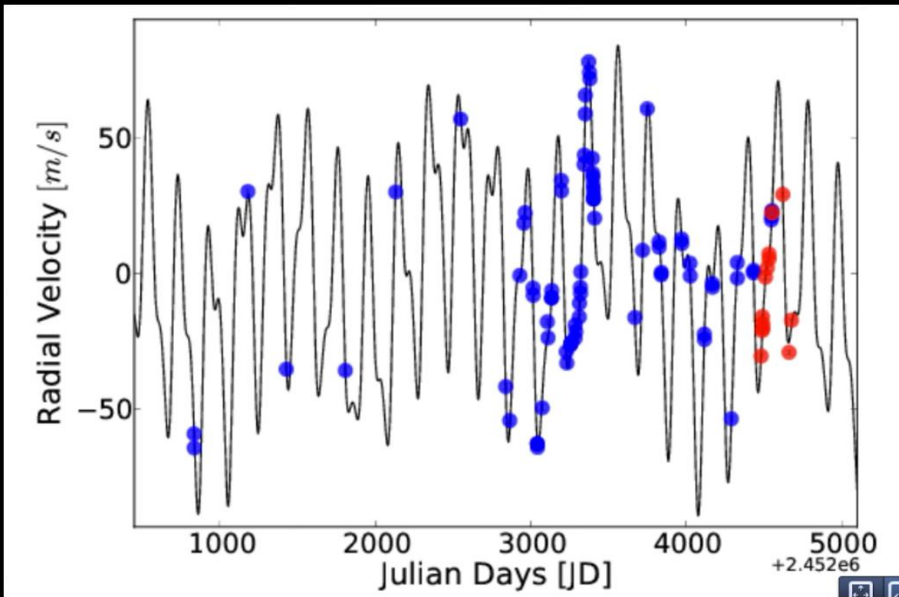


RV points to planets

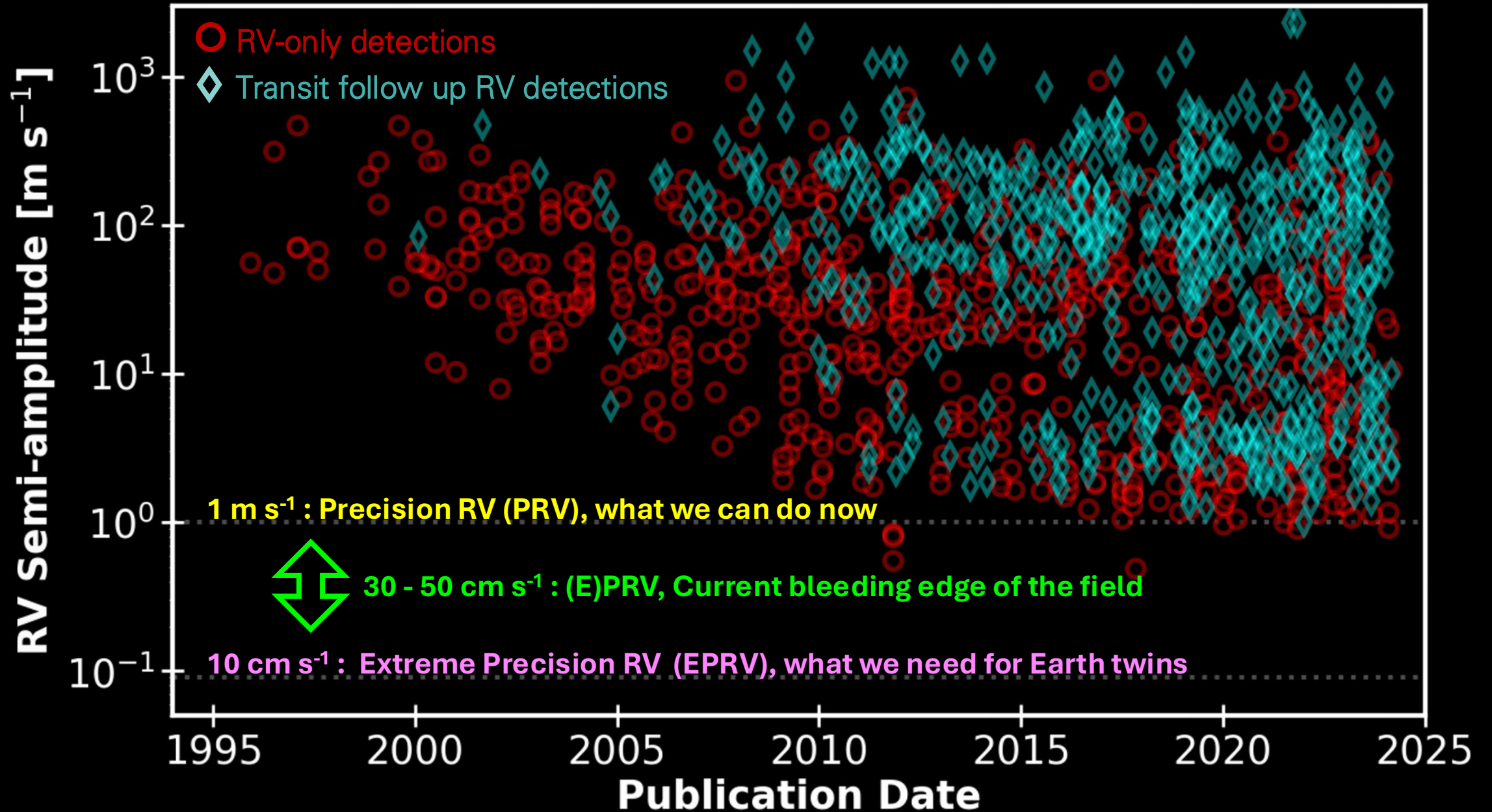
Realistic case: Use a Lomb-Scargle periodogram to identify sinusoidal signals in unevenly sampled time series data



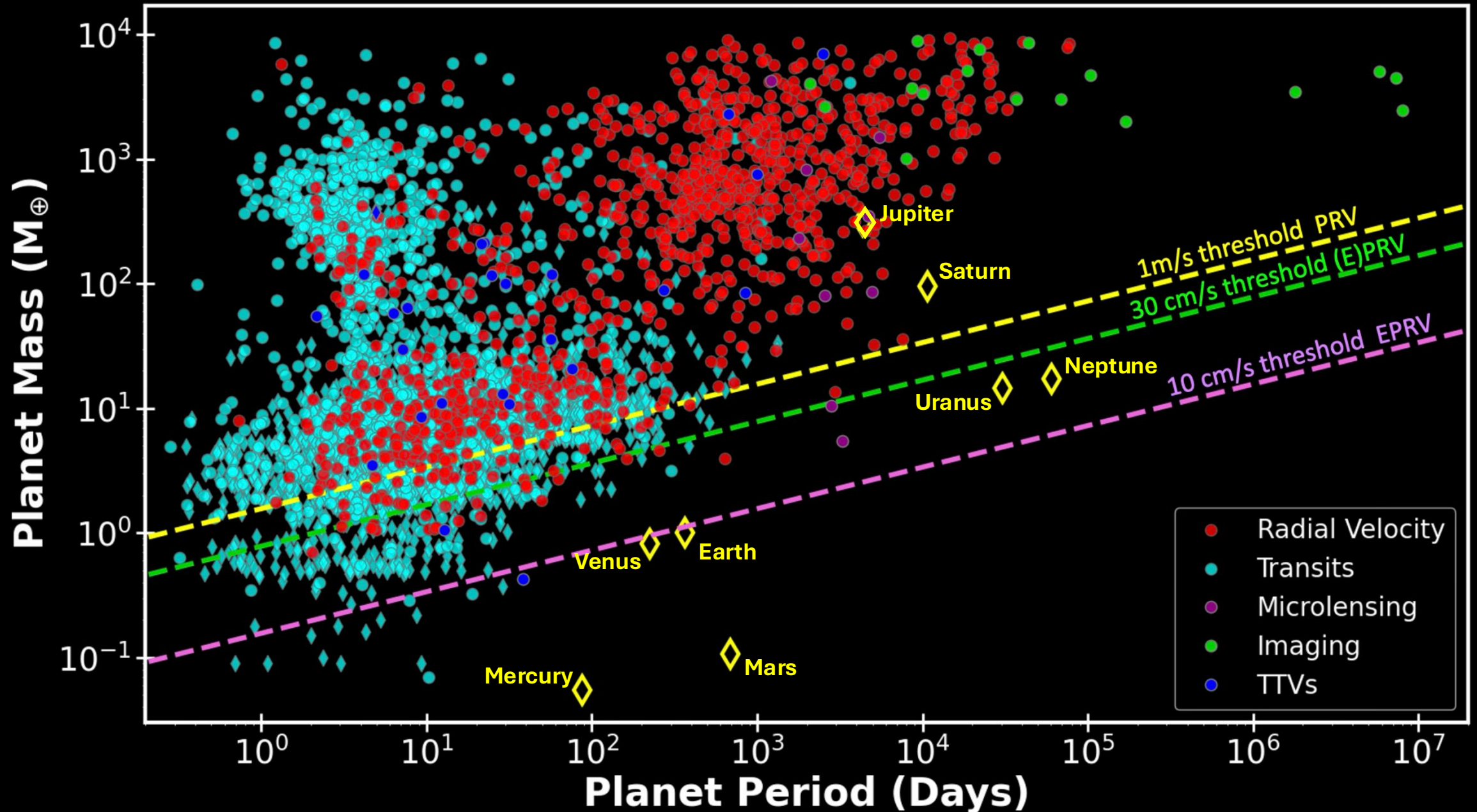
RV points to planets



What can we currently detect?

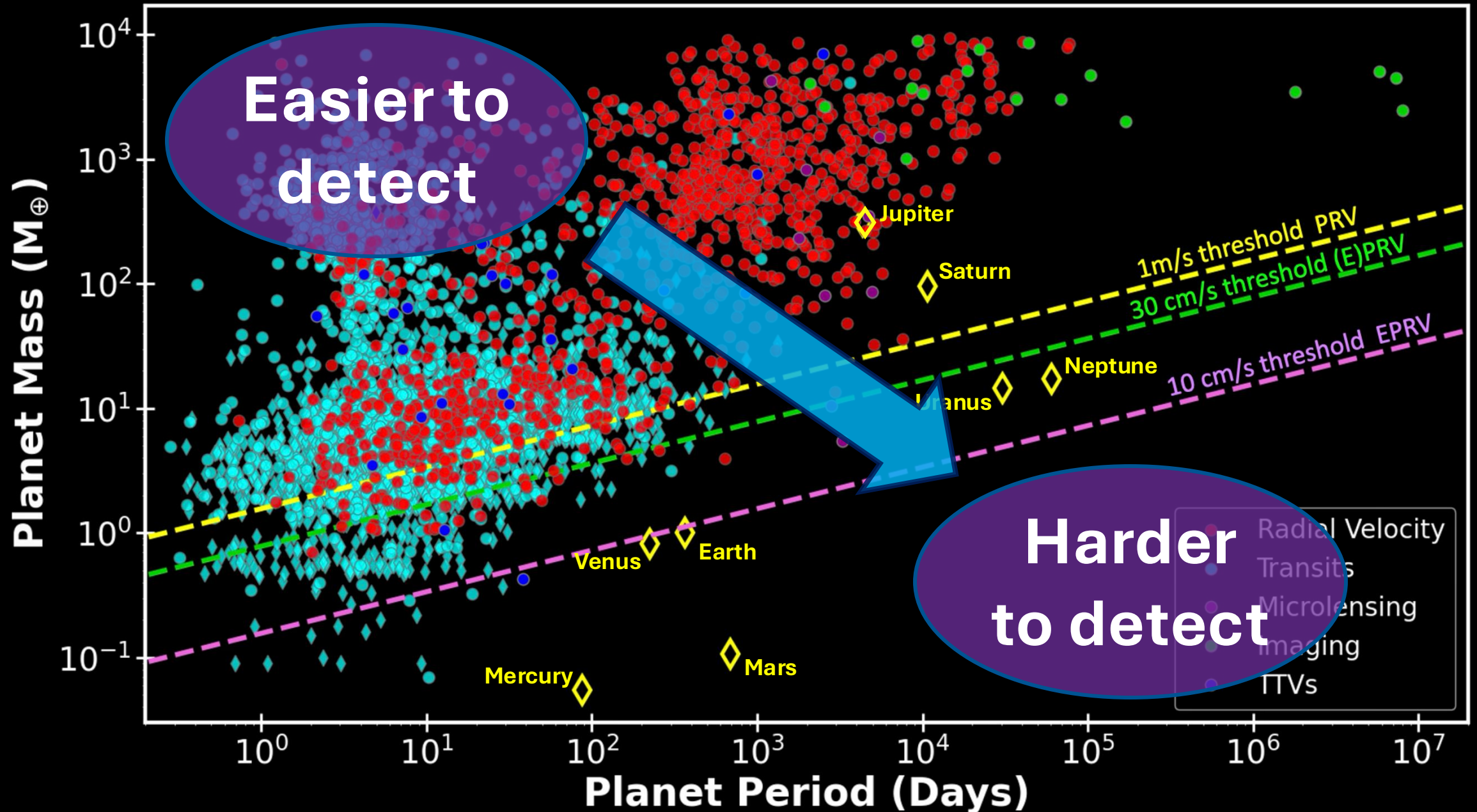


What can we currently detect?

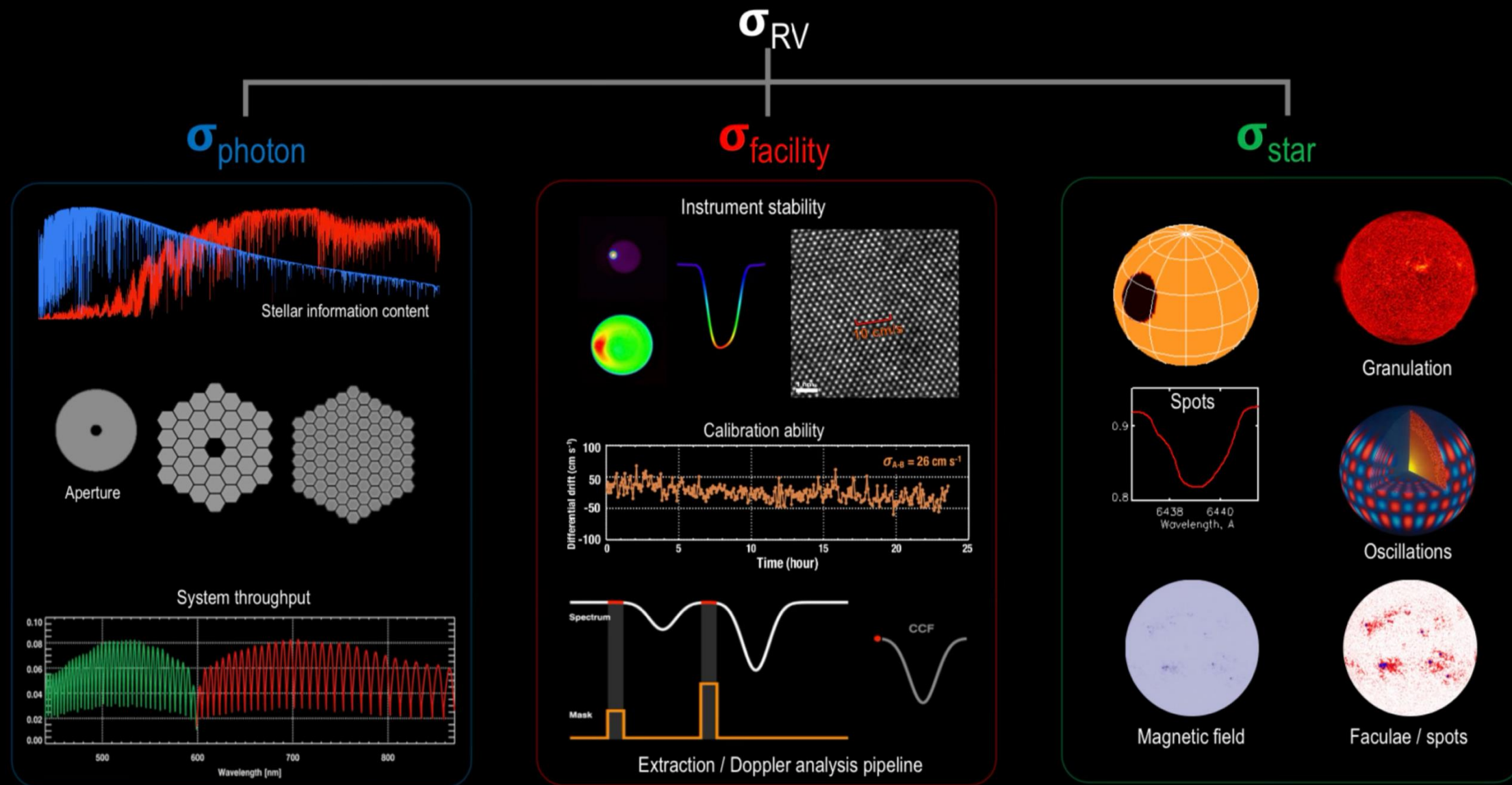


What can we currently detect?

$$K = \left(\frac{2\pi G}{P} \right)^{1/3} \cdot \frac{m_{pl} \sin(i)}{(M_* + m_{pl})^{2/3}} \cdot \frac{1}{\sqrt{1 - e^2}}$$



RV Uncertainty Contributions

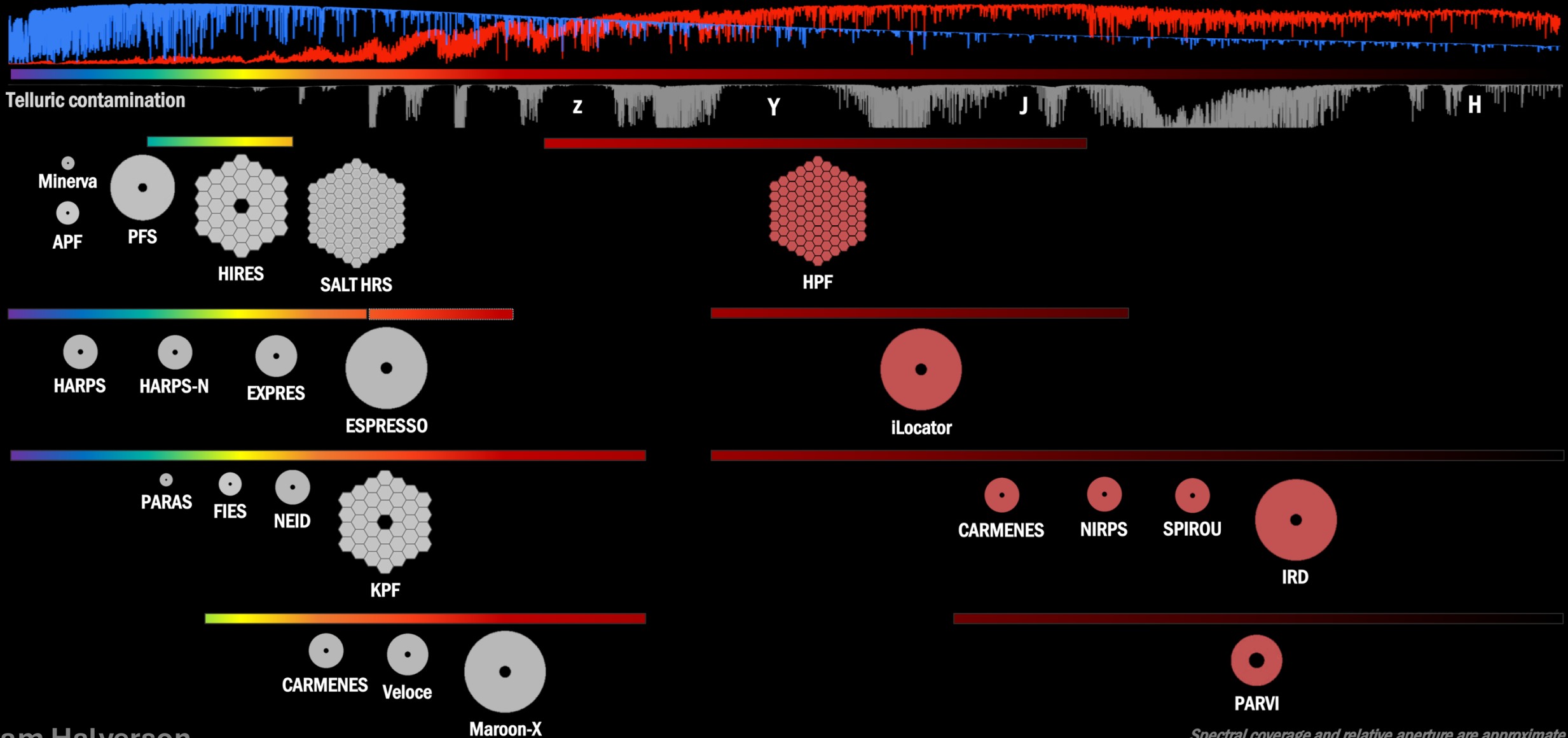


RV Uncertainty Contributions – photon noise

Landscape of high precision Doppler spectrometers

5800 K

2800 K



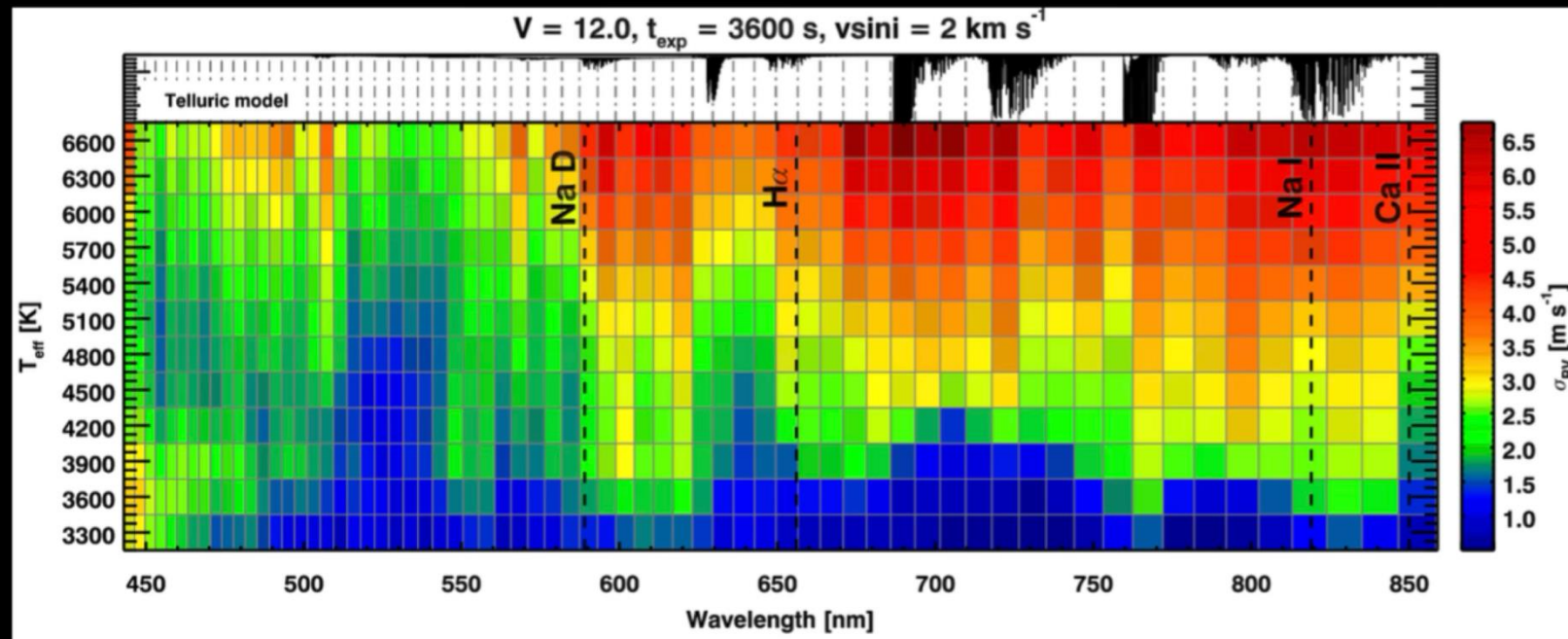
Spectral coverage and relative aperture are approximate

RV Uncertainty Contributions – stellar information content

Beatty & Gaudi 2015

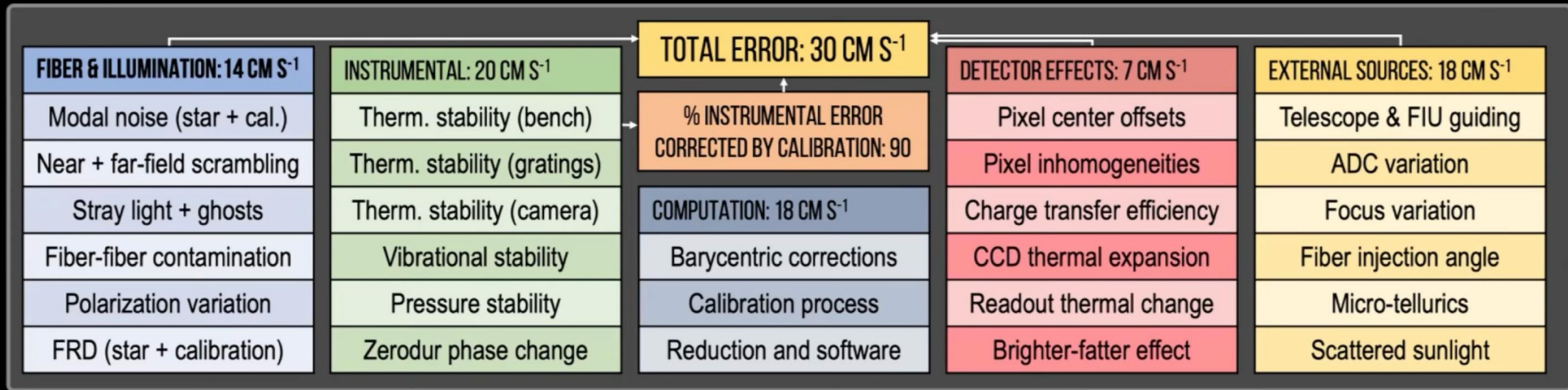
$$\sigma_V = \frac{1}{\sqrt{\sum \frac{I_{0,i}}{\sigma_{V,i}^2}}} \left(\frac{0.5346 \Theta_0(T_{eff})}{\Theta_0(T_{eff})} + \frac{\sqrt{0.2166 \Theta_0^2 + \Theta_R^2 + 0.518 \Theta_{rot}^2 + \Theta_{mac}^2}}{\Theta_0(T_{eff})} \right)^{3/2} \times f(T_{eff}) f(\log g) f([Fe/H]).$$

- Effective Temperature
- Rotational Velocity
- Surface Gravity
- Metallicity
- Macroturbulent Velocity

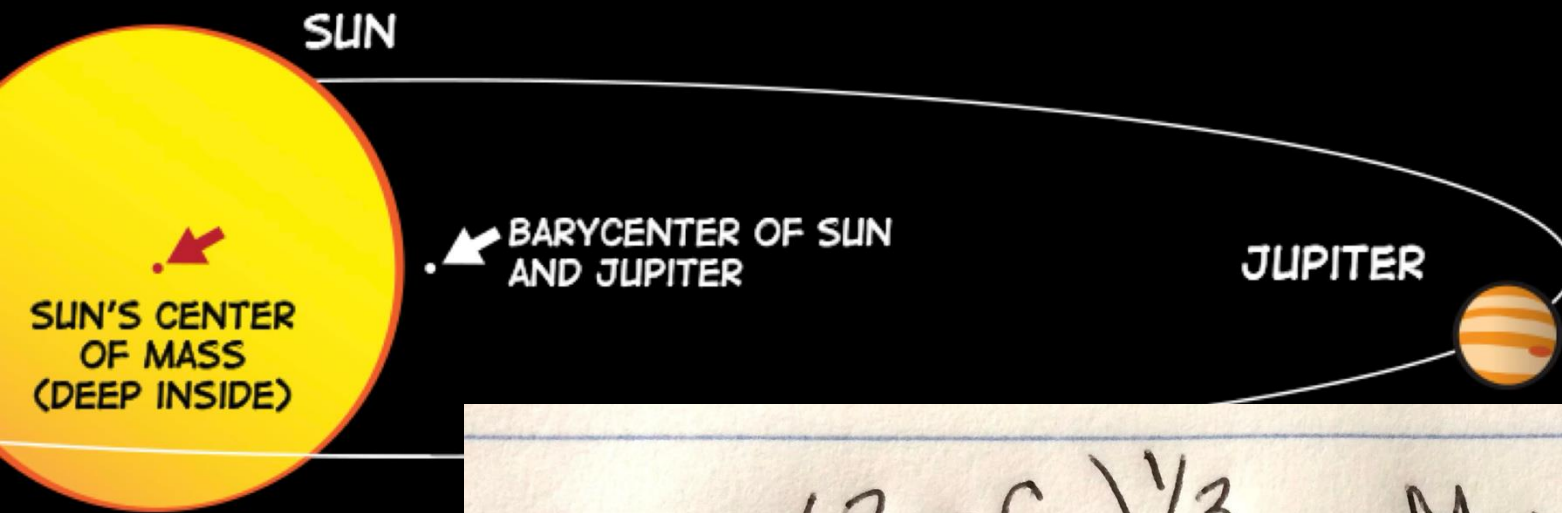


Sam Halverson

RV Uncertainty Contributions -- facility



Setting the Scale



$$K = \left(\frac{2\pi G}{P} \right)^{1/3} \cdot \frac{M_{pl} \cdot \sin(i)}{(M_{star} + M_{pl})^{2/3}}$$

$$M_{\text{Sun}} = 1.98 \times 10^{30} \text{ kg}$$

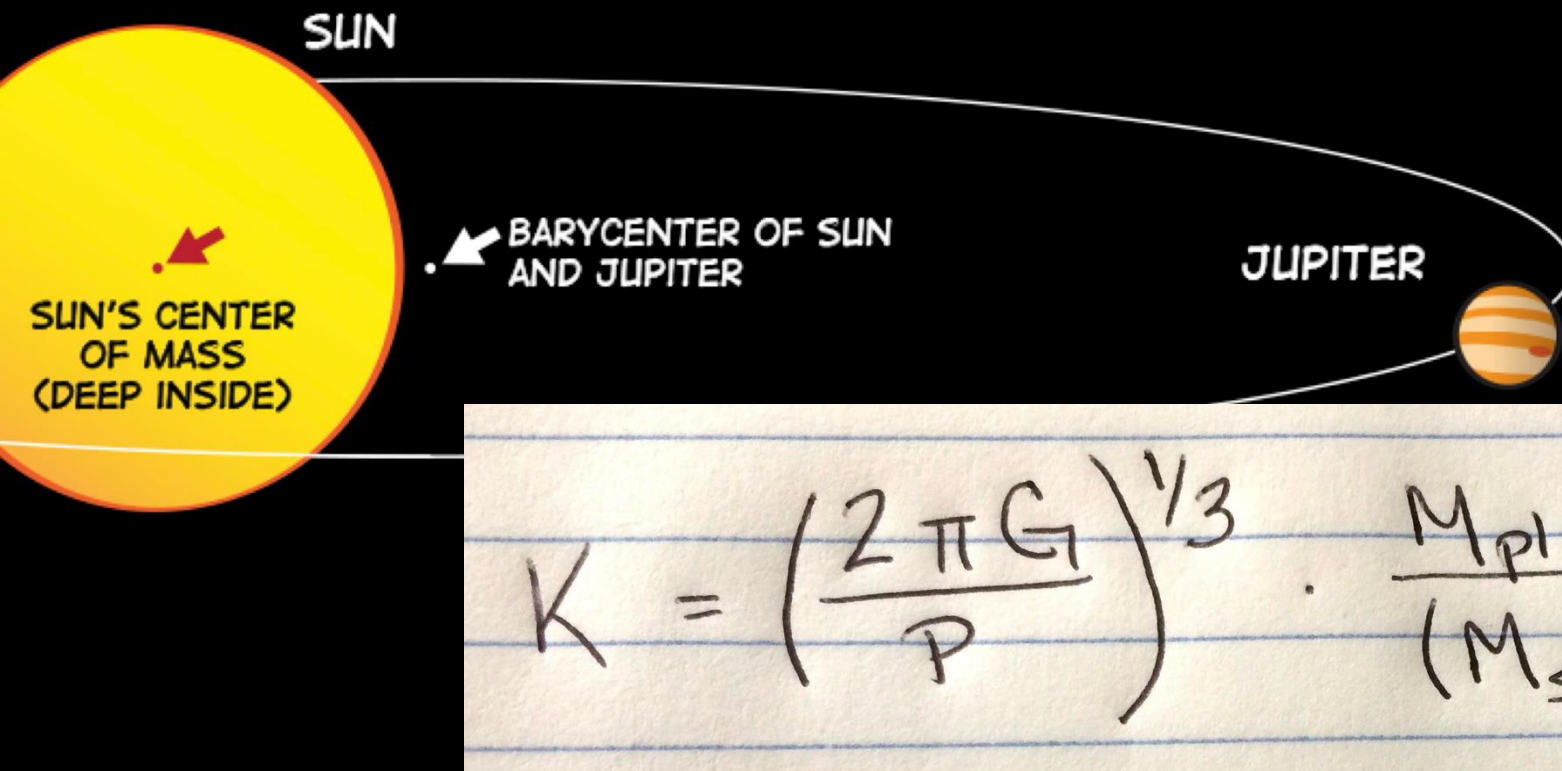
$$M_{\text{Jupiter}} = 1.89 \times 10^{27} \text{ kg}$$

$$P_{\text{Jup}} = 11.86 \text{ years}$$

$$G = 6.67 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2}$$

$$K = 12.46 \text{ m s}^{-1}$$

Setting the Scale



Usain Bolt

12.07 m/s
(aka 27 mph)

$$M_{\text{Sun}} = 1.98 \times 10^{30} \text{ kg}$$

$$M_{\text{Jupiter}} = 1.89 \times 10^{27} \text{ kg}$$

$$P_{\text{Jup}} = 11.86 \text{ years}$$

$$G = 6.67 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2}$$

$$K = 12.46 \text{ m s}^{-1}$$

Setting the Scale

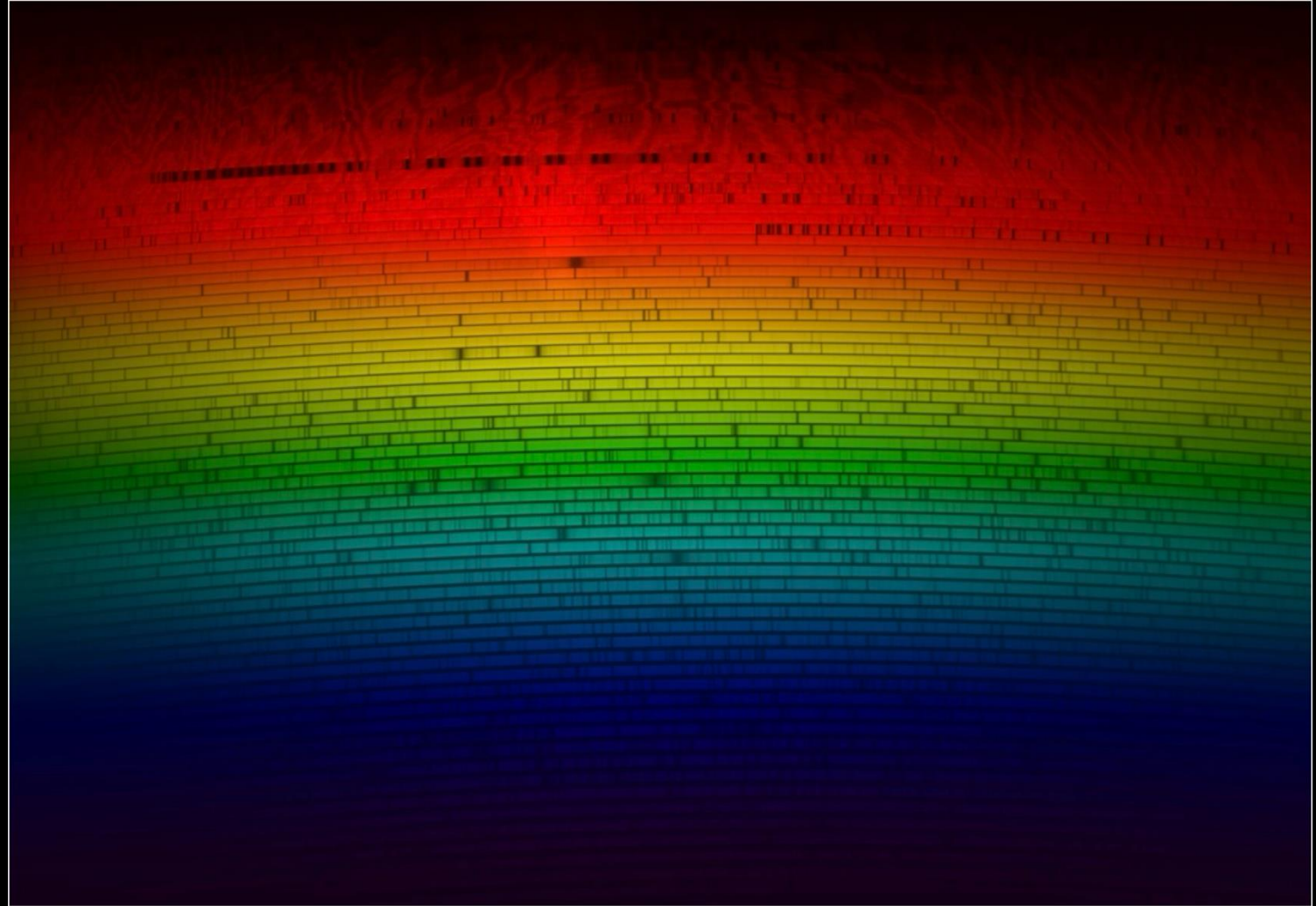
Doppler Shift Equation

$$\frac{\Delta\lambda}{\lambda_0} = \frac{v}{c}$$

$$K_{\text{Jup}} = 12.46 \text{ m s}^{-1}$$

$$\lambda_0 = 510 \text{ nm}$$

$$\Delta\lambda = 2.11 \times 10^{-5} \text{ nm}$$

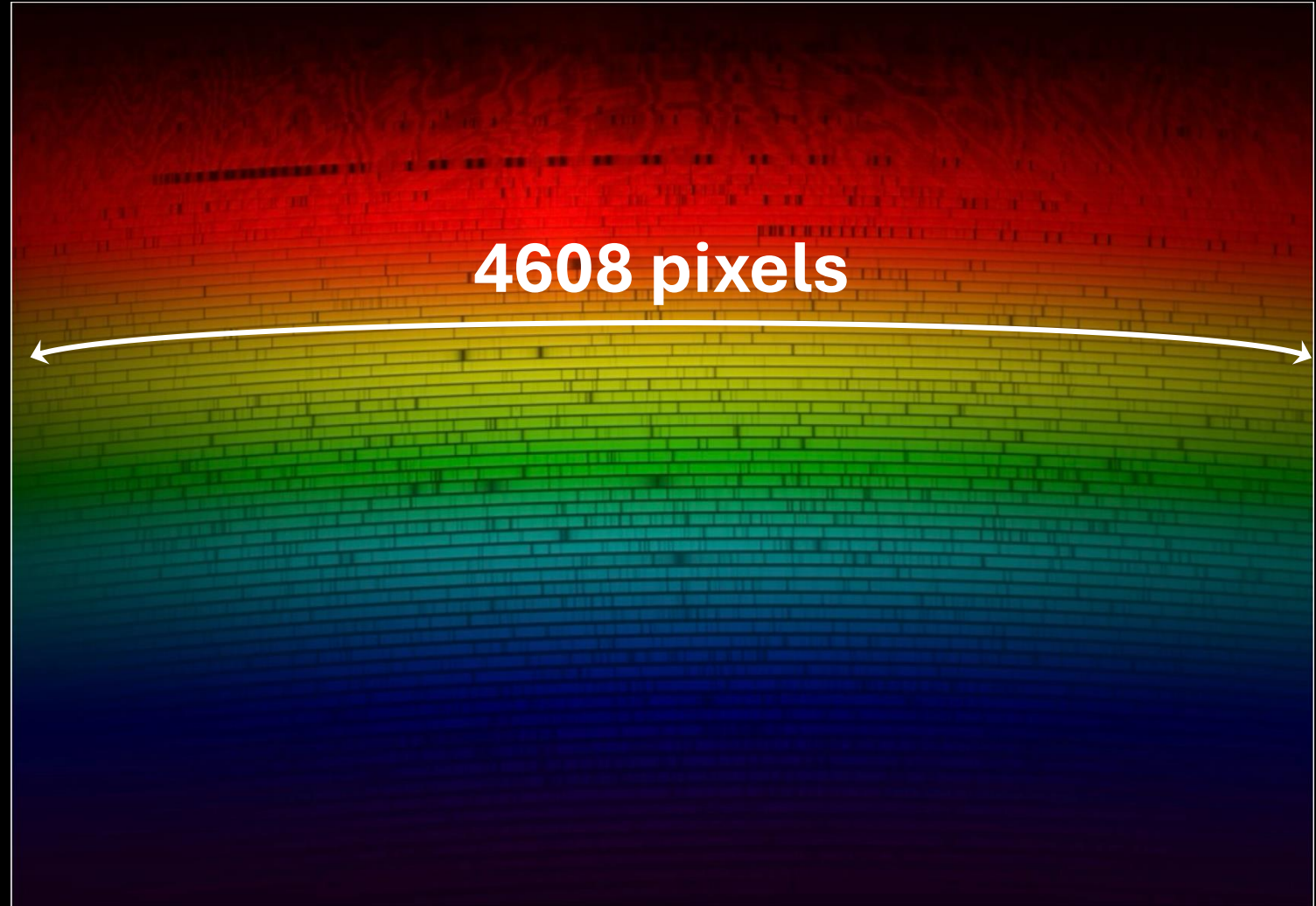


Setting the Scale

One order $\sim 6\text{nm}$

So what is our $\Delta\lambda$ in pixels?

$$\frac{\Delta\lambda}{\lambda_{\text{range}}} = \frac{\Delta \text{pixels}}{N \text{ pixels}}$$



Setting the Scale

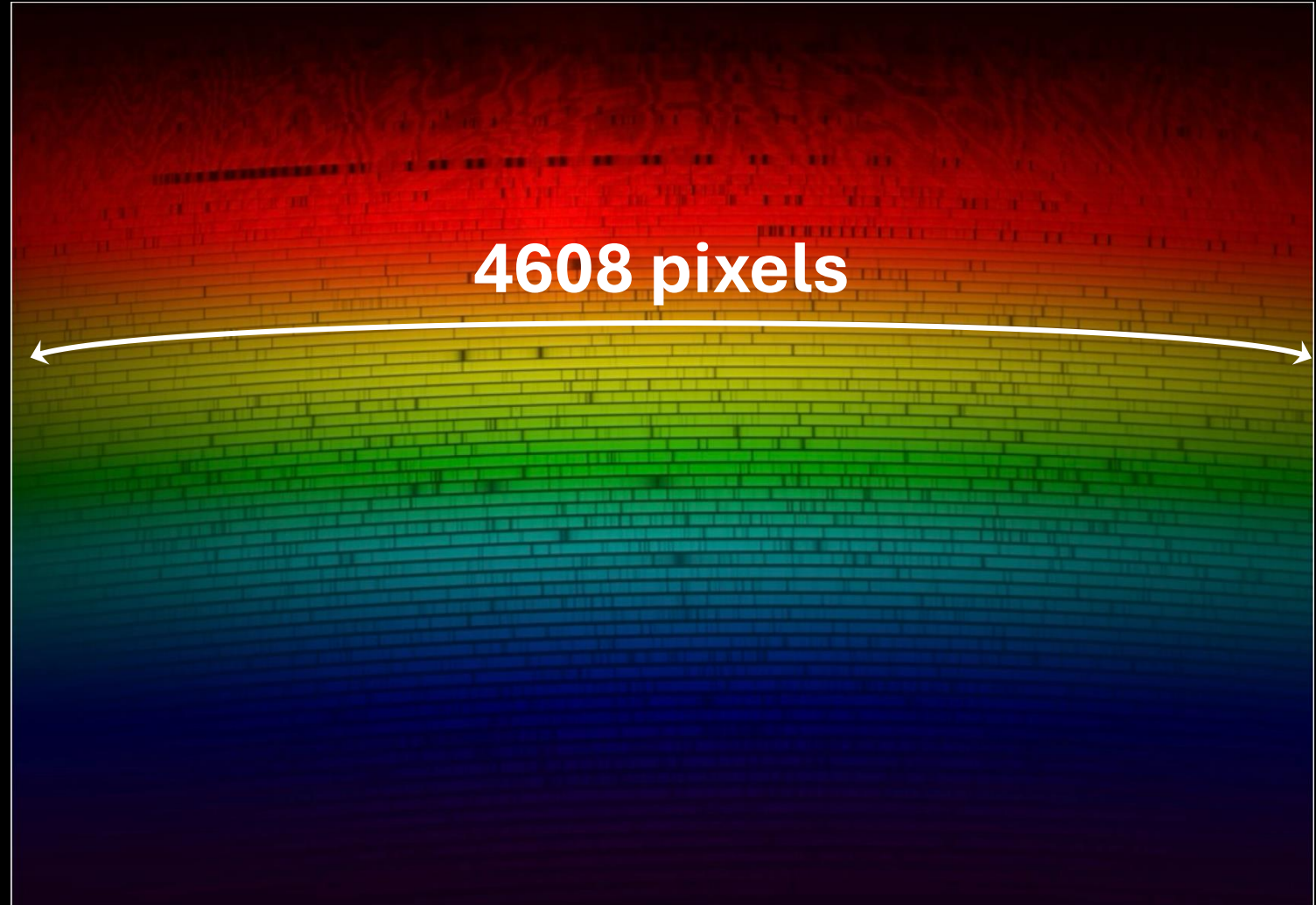
$$\frac{\Delta\lambda}{\lambda_{\text{range}}} = \frac{\Delta\text{pixels}}{N_{\text{pixels}}}$$

$$\Delta\lambda = 2.11 \times 10^{-5} \text{ nm}$$

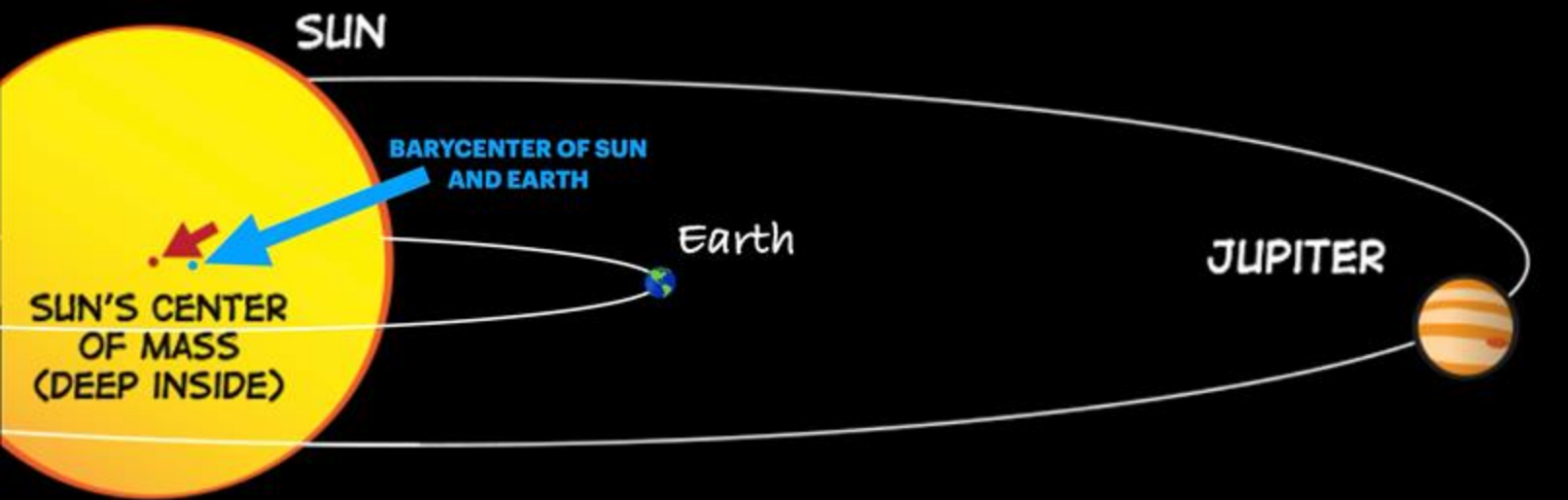
$$\lambda_{\text{range}} = 6 \text{ nm}$$

$$N_{\text{pixels}} = 4608$$

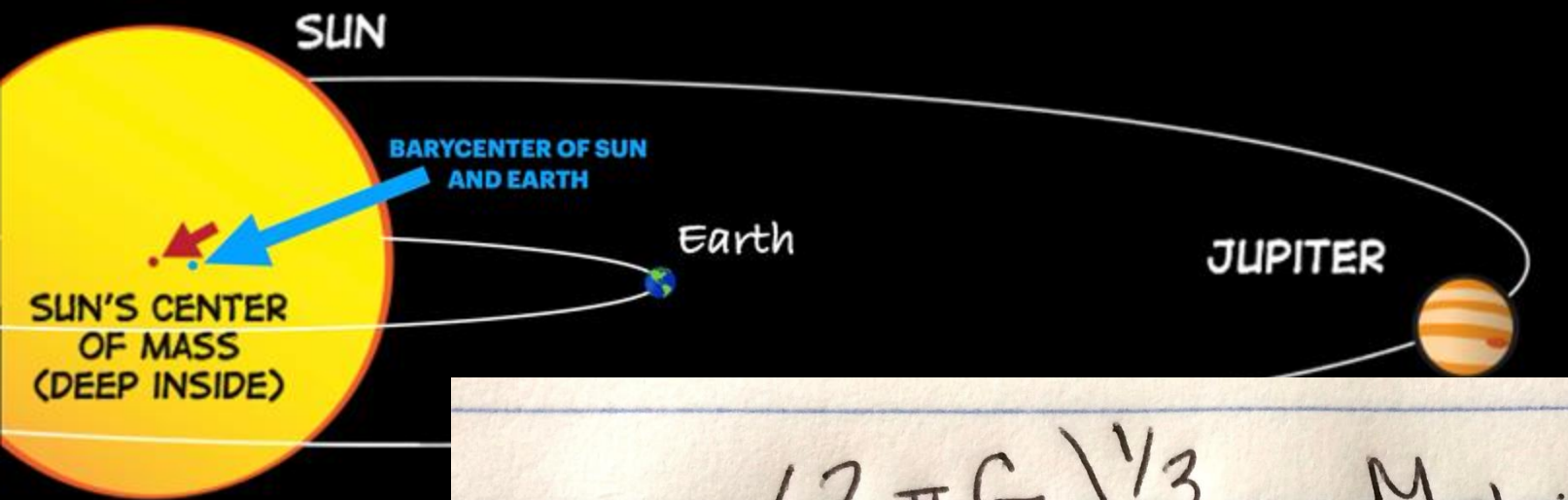
$$\Delta\text{pixels} = 0.016 \text{ pix}$$



Setting the Scale



Setting the Scale



$$K = \left(\frac{2\pi G}{P} \right)^{1/3} \cdot \frac{M_{pl} \cdot \sin(i)}{(M_{star} + M_{pl})^{2/3}}$$

$$M_{\text{Sun}} = 1.98 \times 10^{30} \text{ kg}$$

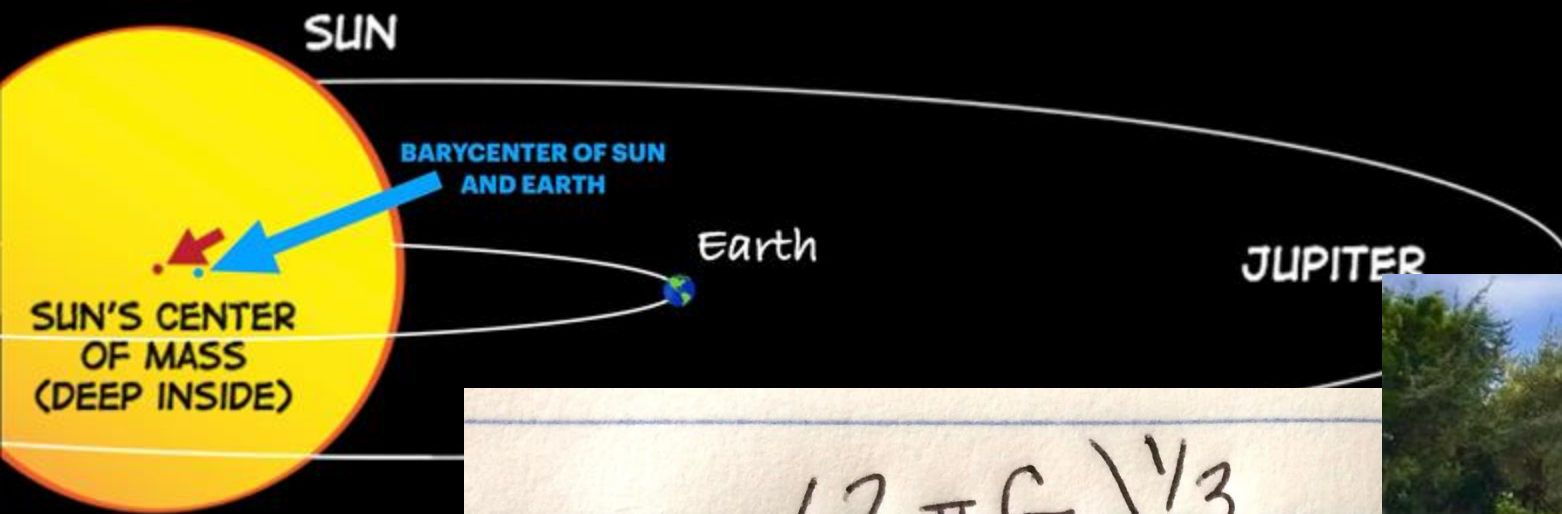
$$M_{\text{Earth}} = 5.97 \times 10^{24} \text{ kg}$$

$$P_{\text{Earth}} = 1.0 \text{ years}$$

$$G = 6.67 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2}$$

$$K = 0.09 \text{ m s}^{-1}$$

Setting the Scale



$$K = \left(\frac{2\pi G}{P} \right)^{1/3}$$



$$M_{\text{Sun}} = 1.98 \times 10^{30} \text{ kg}$$

$$M_{\text{Earth}} = 5.97 \times 10^{24} \text{ kg}$$

$$G = 6.67 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2}$$

$$K = 0.09 \text{ m s}^{-1}$$

Setting the Scale

$$\frac{\Delta\lambda}{\lambda_{\text{range}}} = \frac{\Delta\text{pixels}}{N_{\text{pixels}}}$$

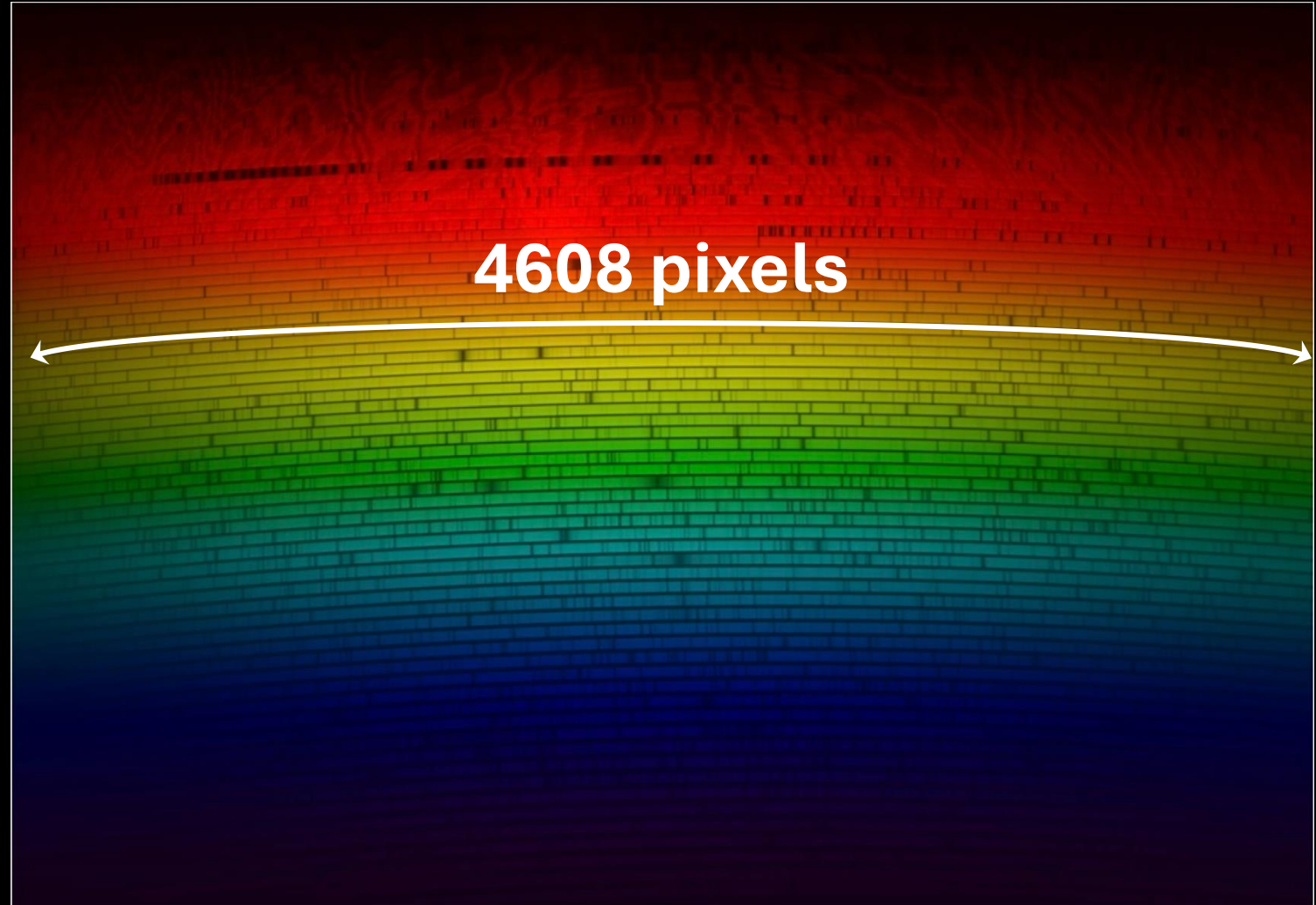
$$K = 9 \text{ cm s}^{-1}$$

$$\Delta\lambda = 0.0000153 \text{ nm}$$

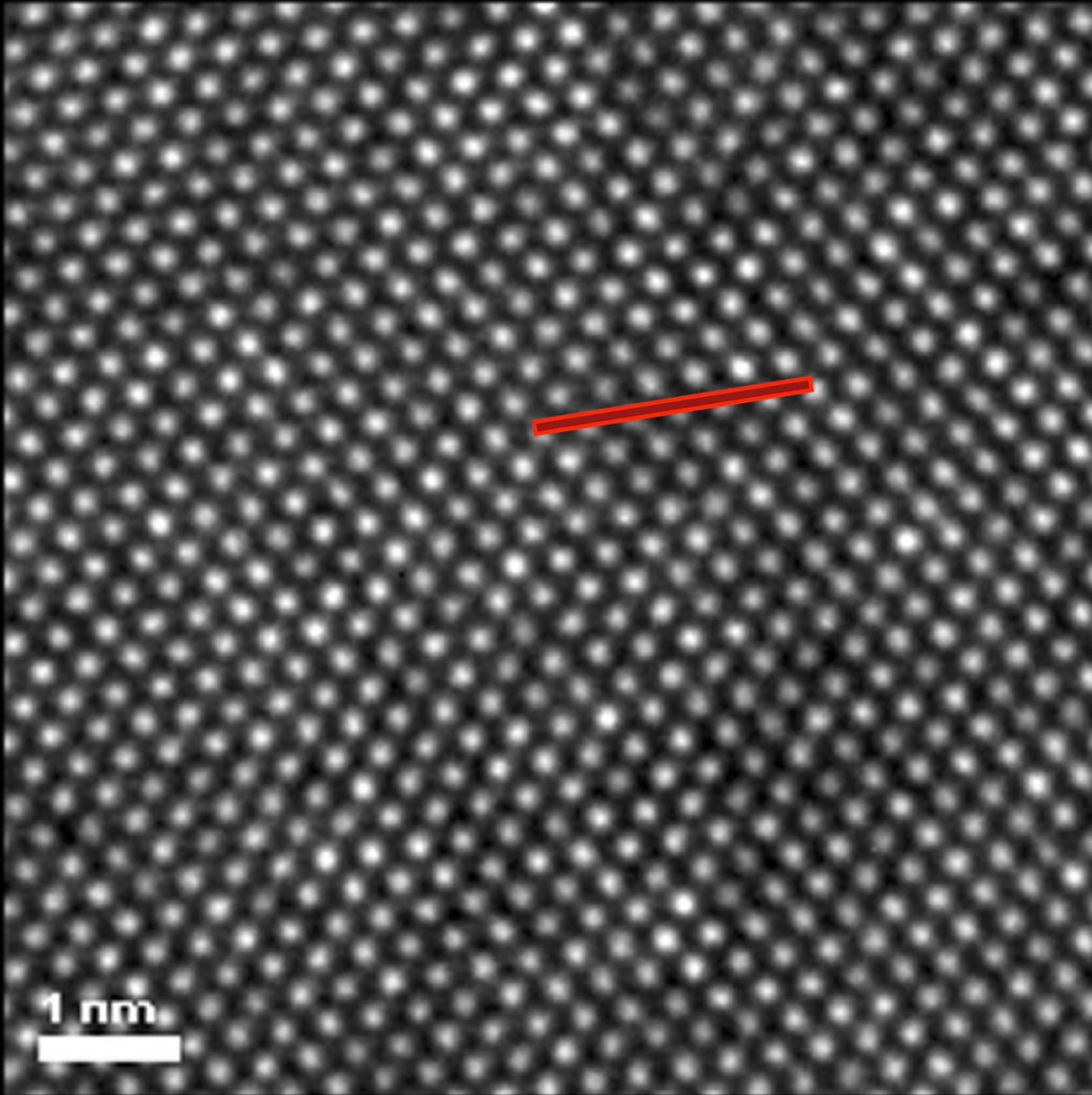
$$\lambda_{\text{range}} = 6 \text{ nm}$$

$$N_{\text{pixels}} = 4608$$

$$\Delta\text{pixels} = 0.00012 \text{ pixels}$$

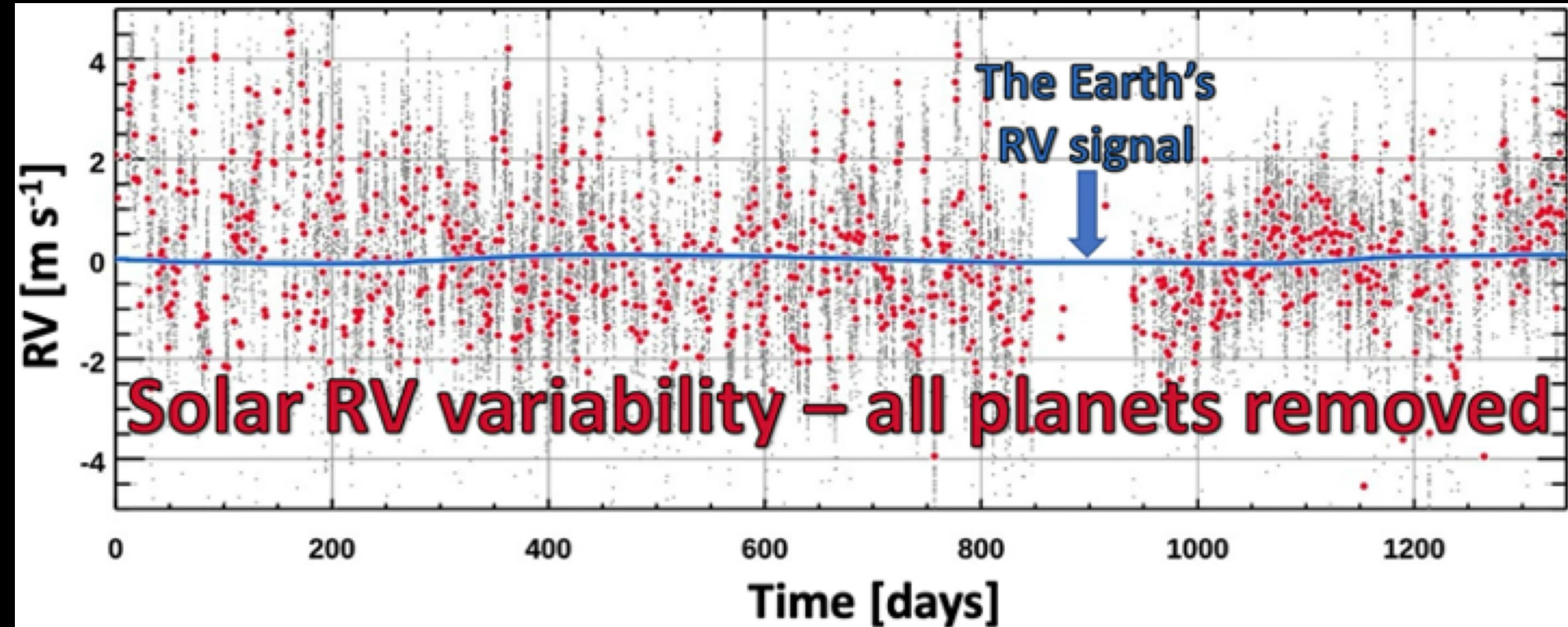


Setting the Scale

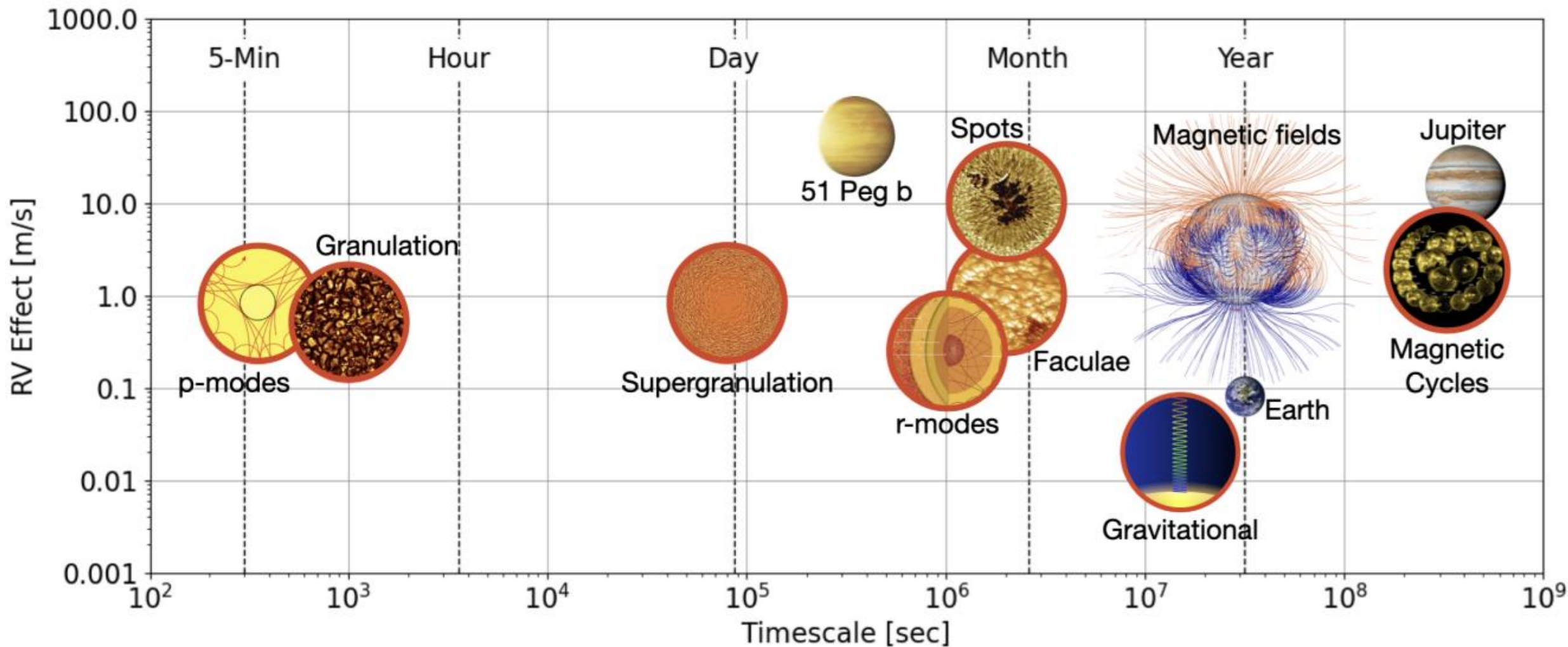


The RV signal of Earth around the sun is equivalent to an absorption line moving by SIX silicon atoms

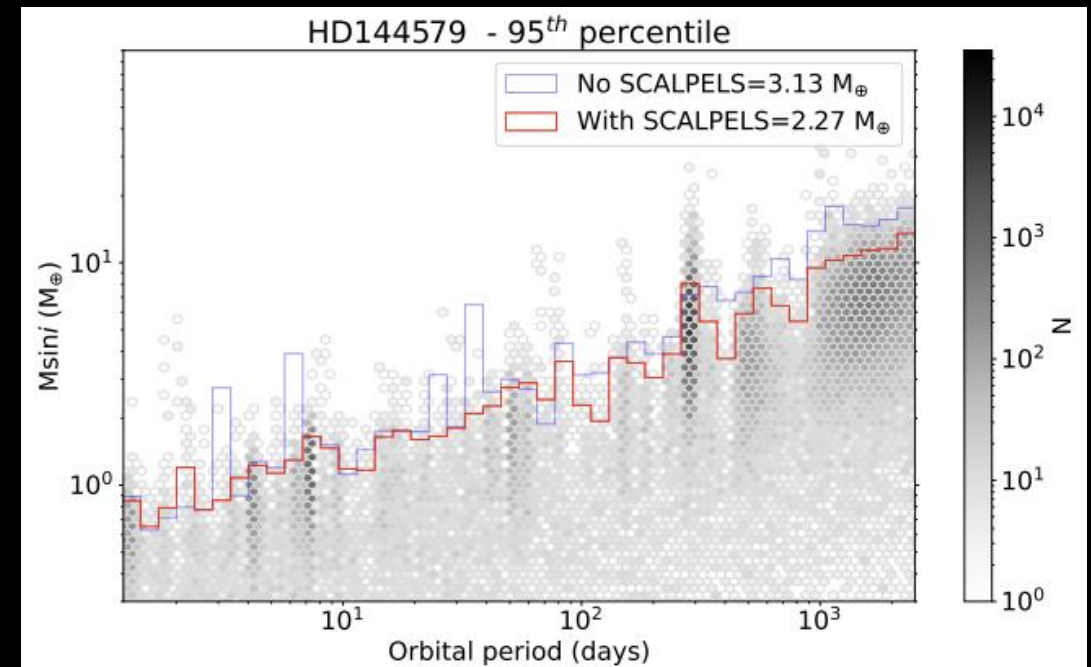
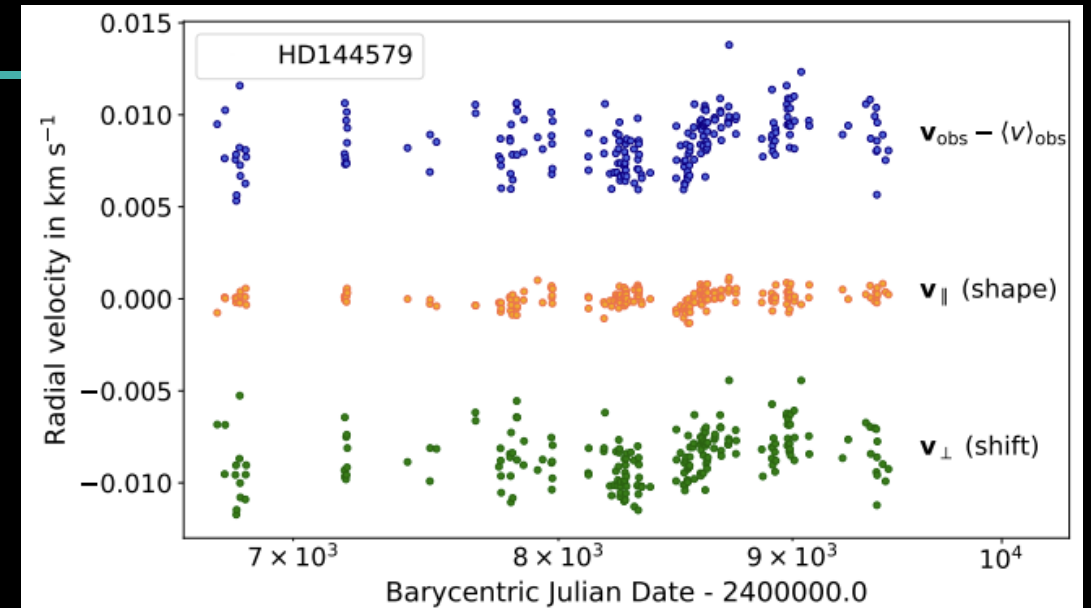
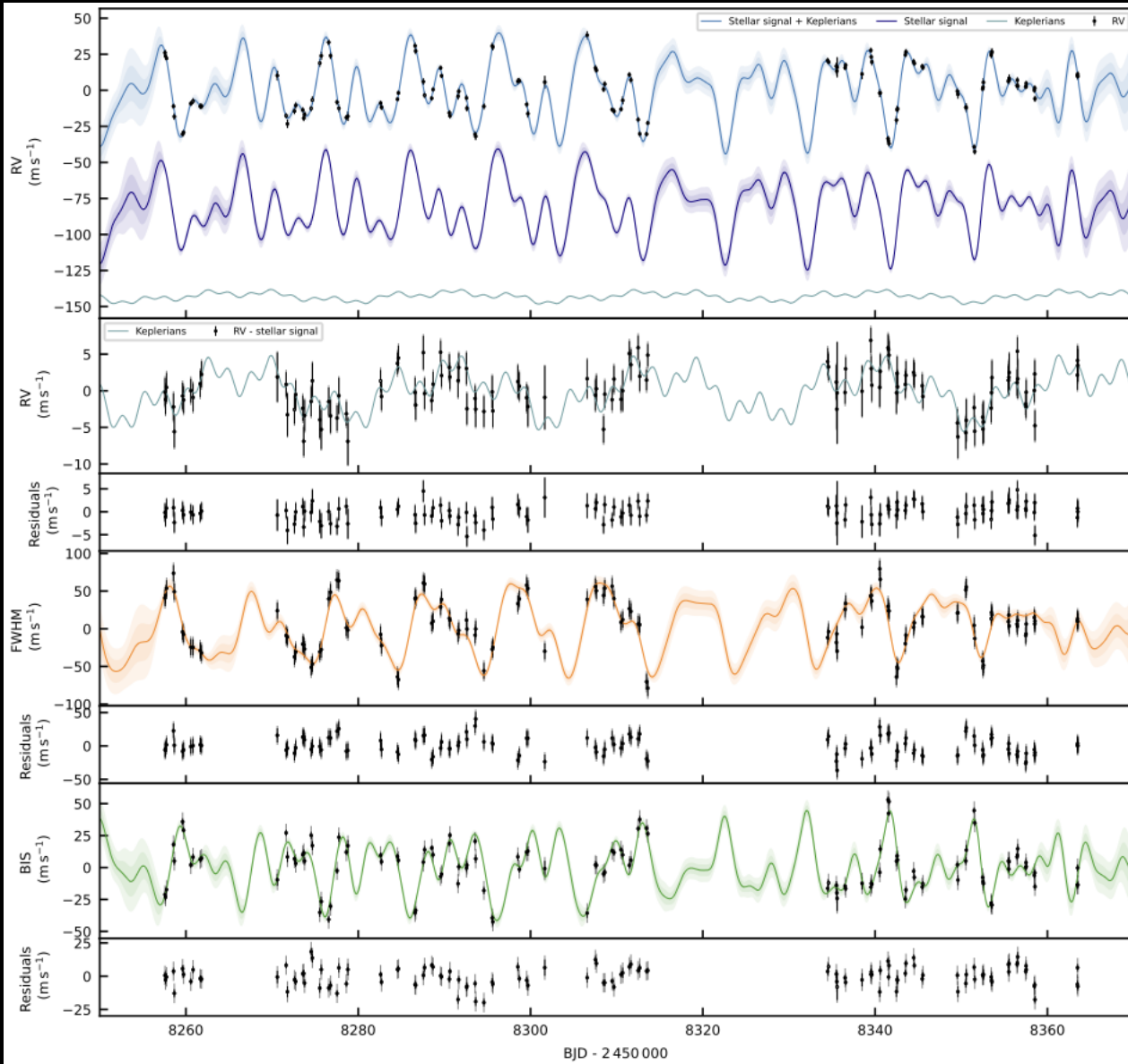
Setting the Scale



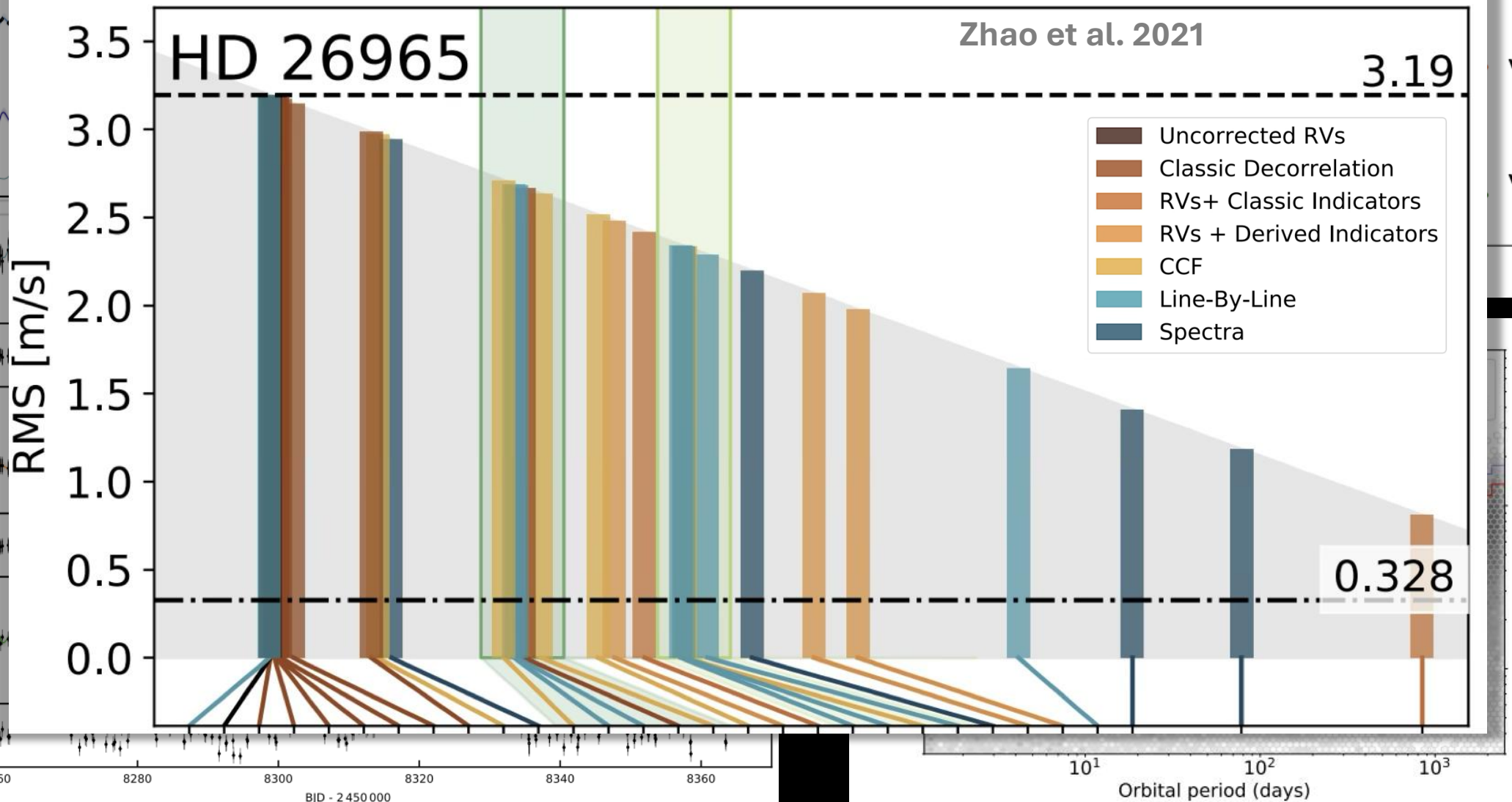
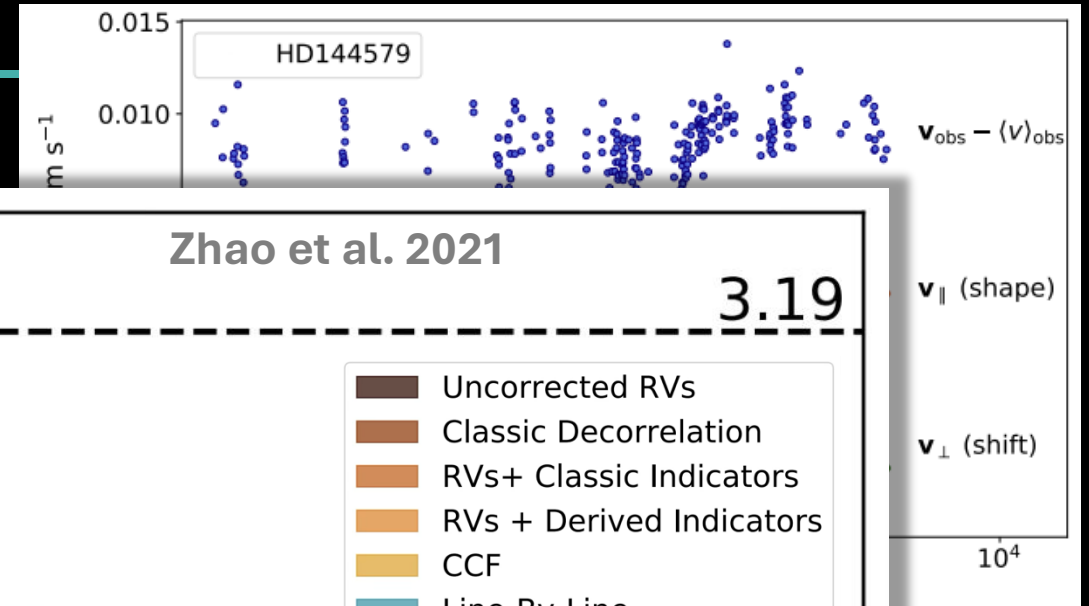
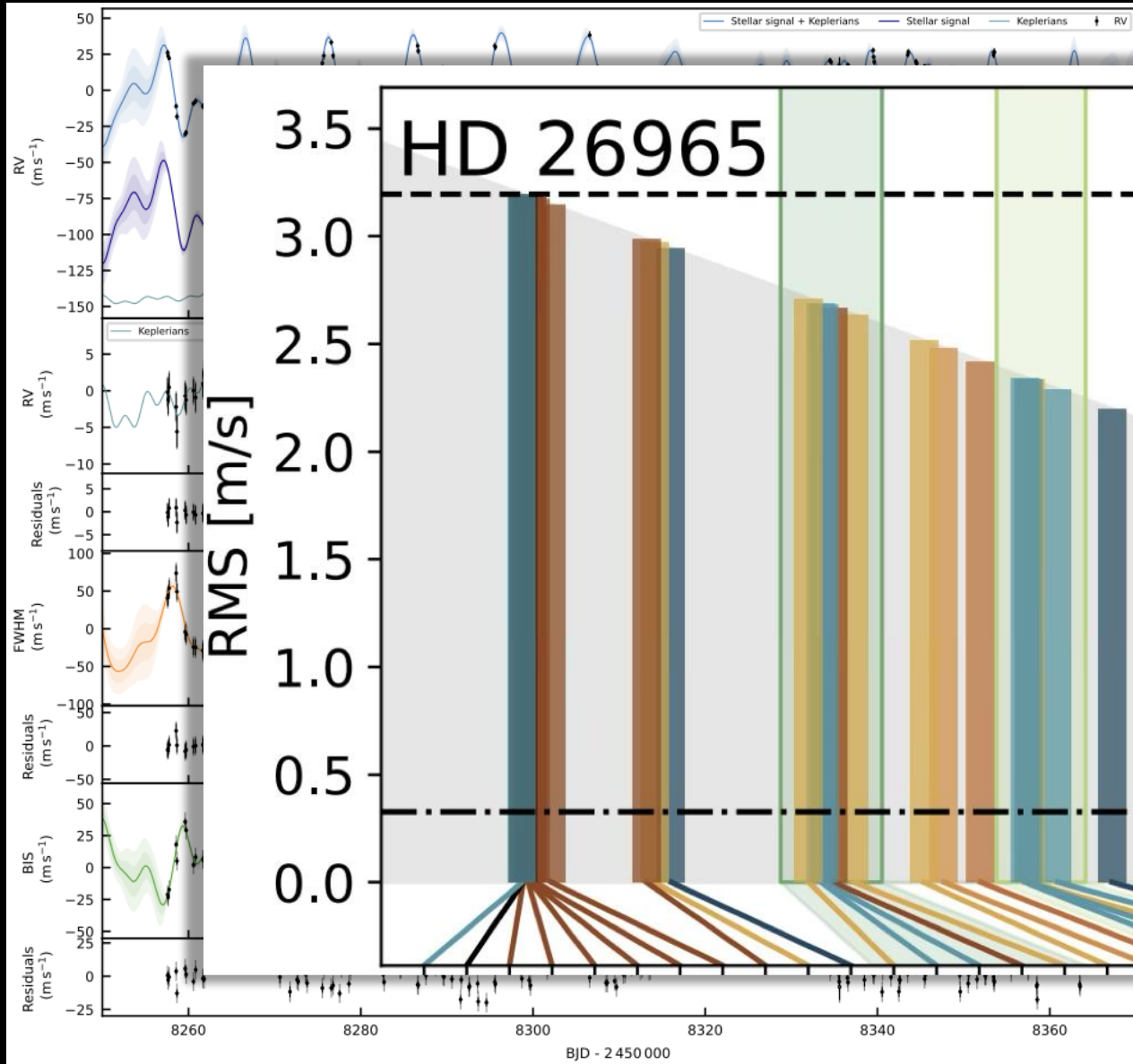
RV Uncertainty Contributions – stellar variability



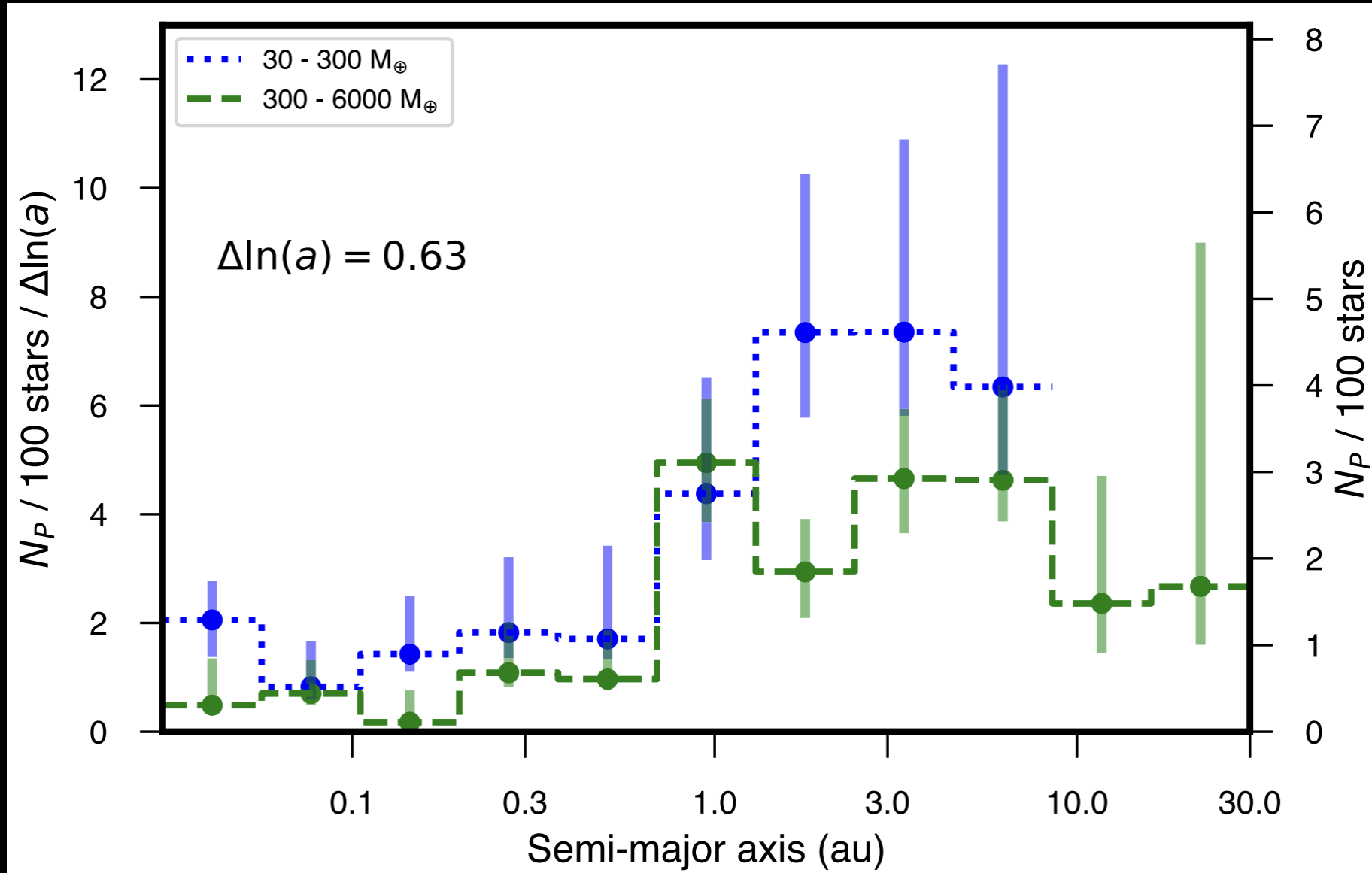
Stellar Variability



Stellar Variability



State of the Field



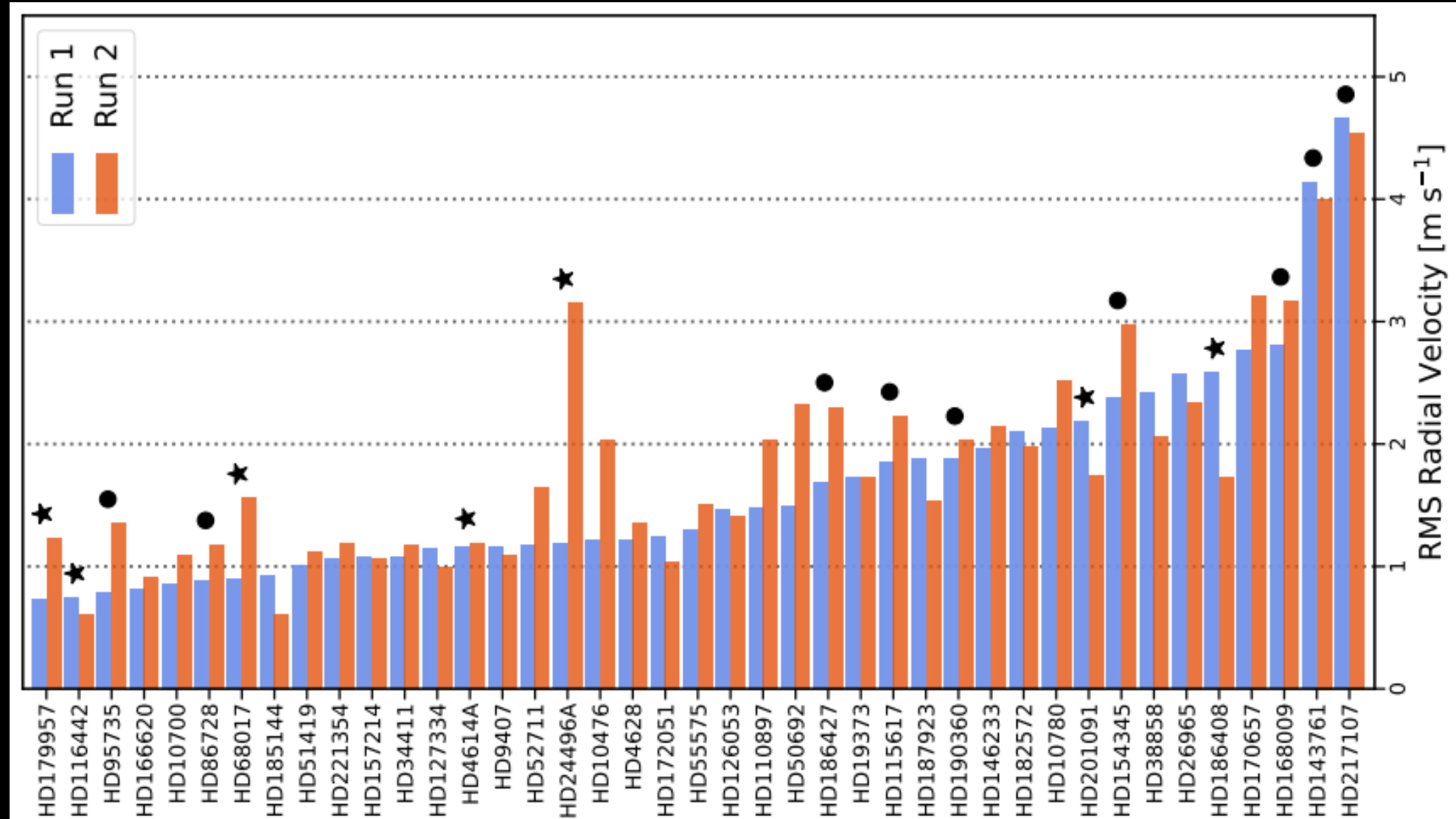
State of the Field

- **EXPRES 100 Earths Survey**
- **NEID Earth Twins Survey**
- **HARPS-N Rocky Planet Search**
- **ESPRESSO GTO**
- **Terra Hunting Experiment (HARPS3)**
- **HUnting for M Dwarf Rocky planets Using MAROON-X (HUMDRUM)**
- **... many additional, PI-level efforts**

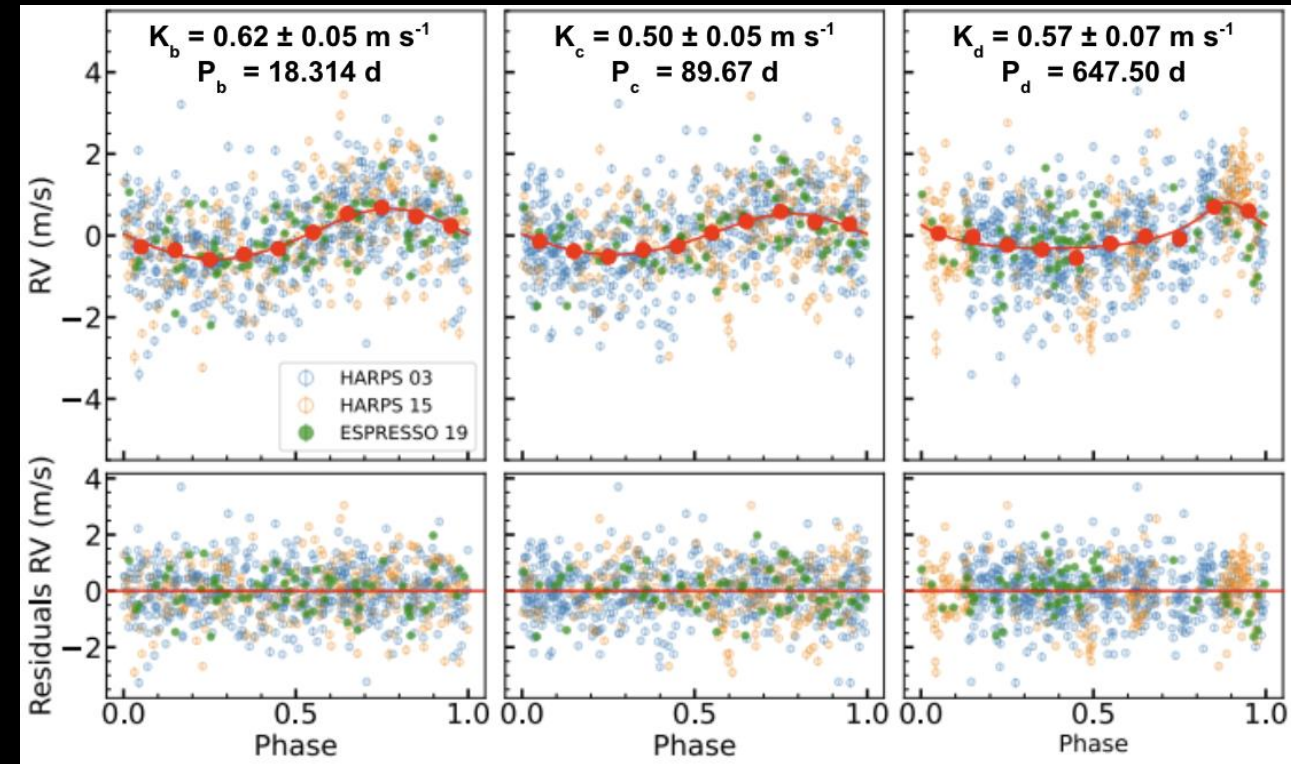
State of the Field – Time series RMS

Run 1:
October 2020
– June 2022

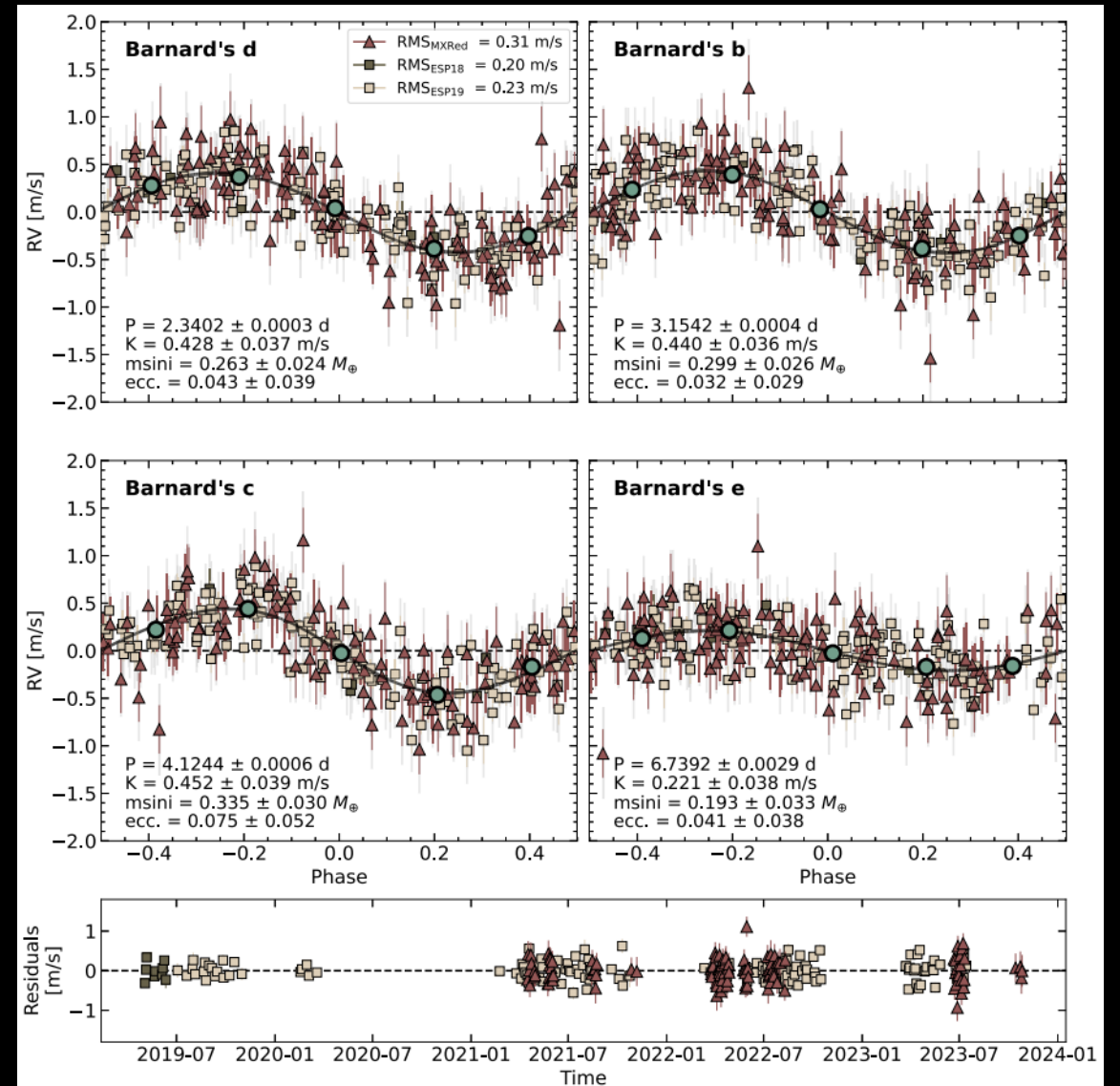
Run 2:
October 2022
– August 2024



State of the Field – Pure RV Detections

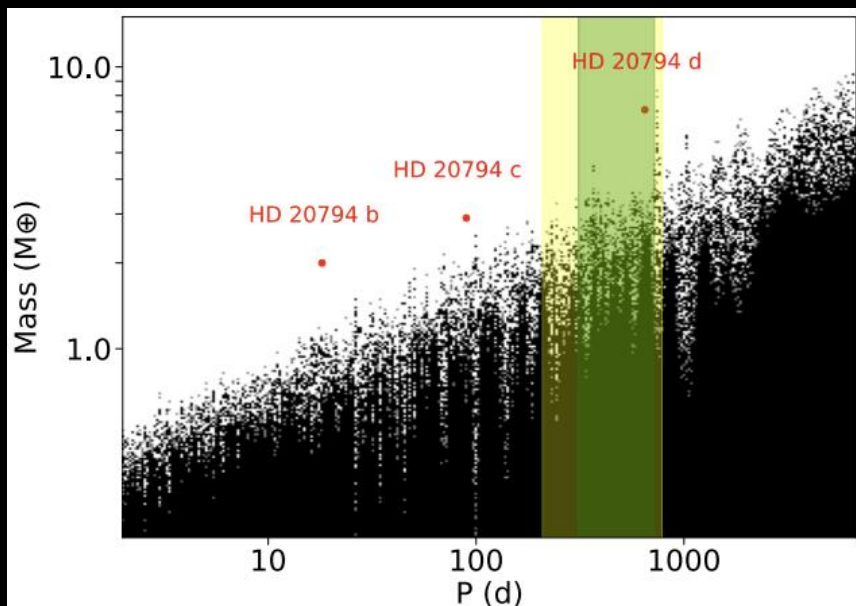


Nari et al. 2025

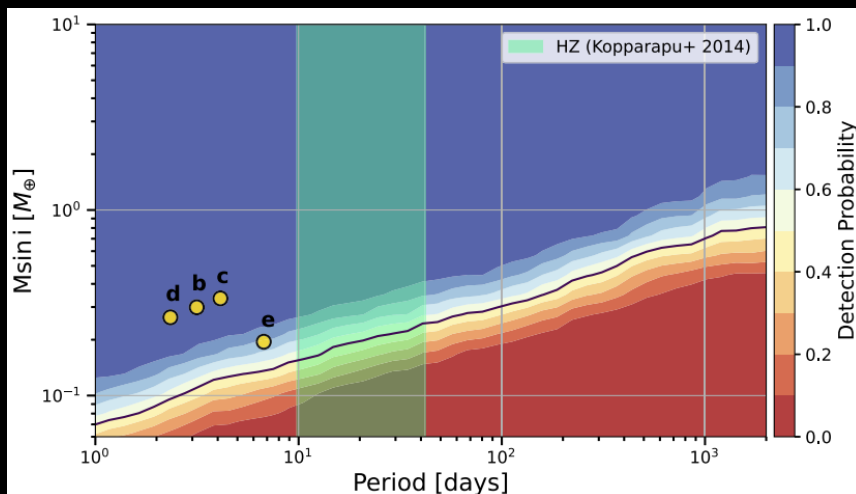


Basant et al. 2025

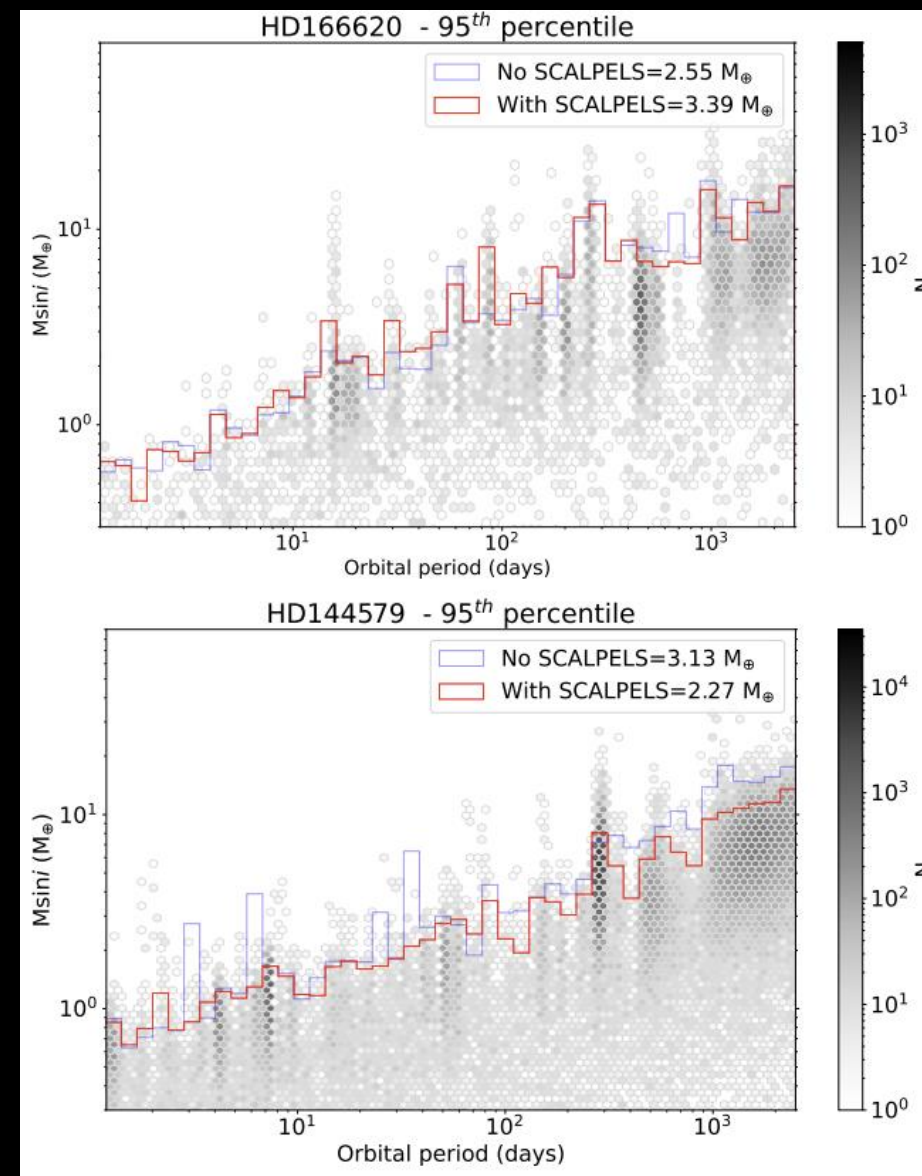
State of the Field – RV Sensitivity



Nari et al. 2025

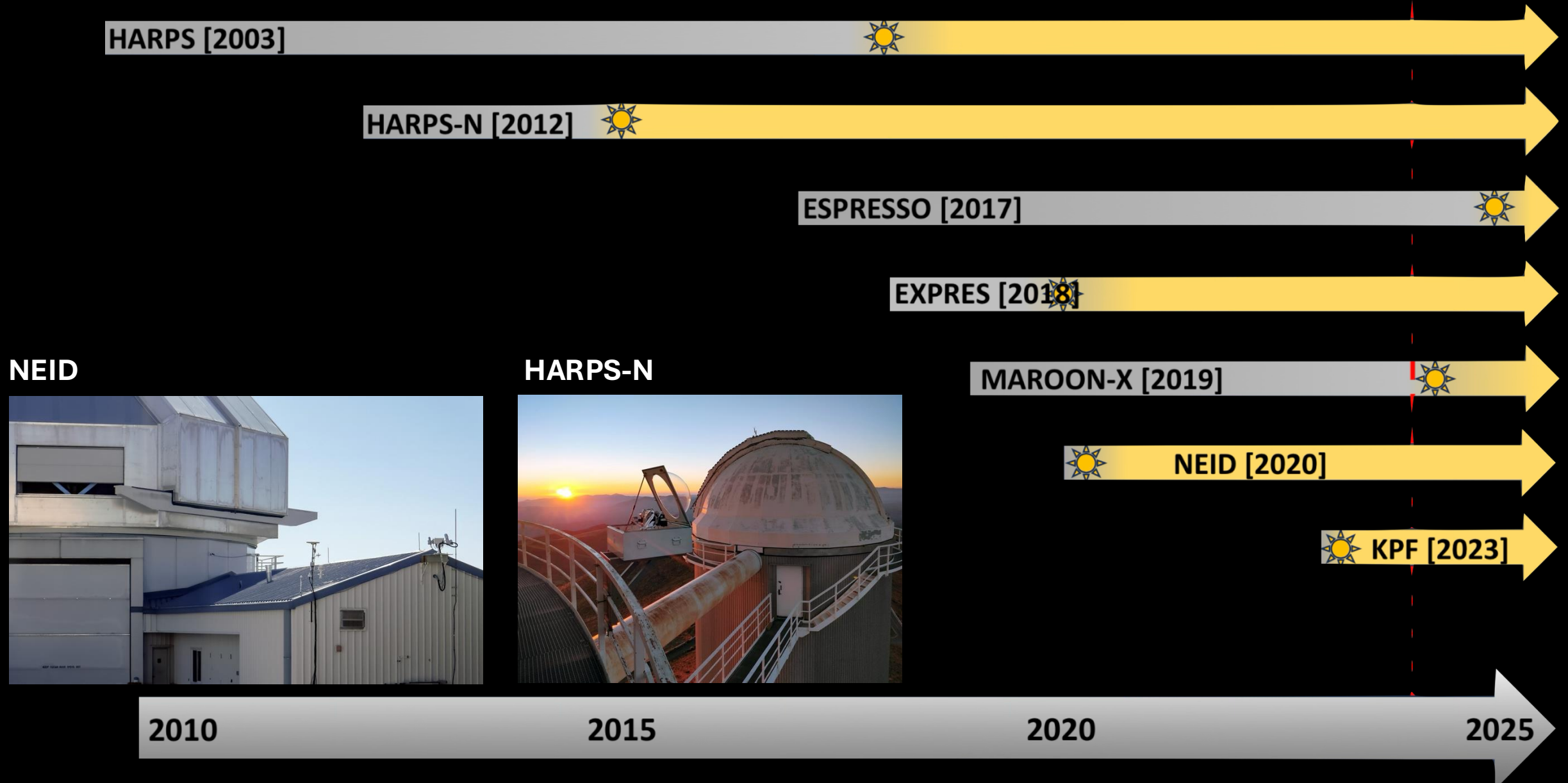


Basant et al. 2025



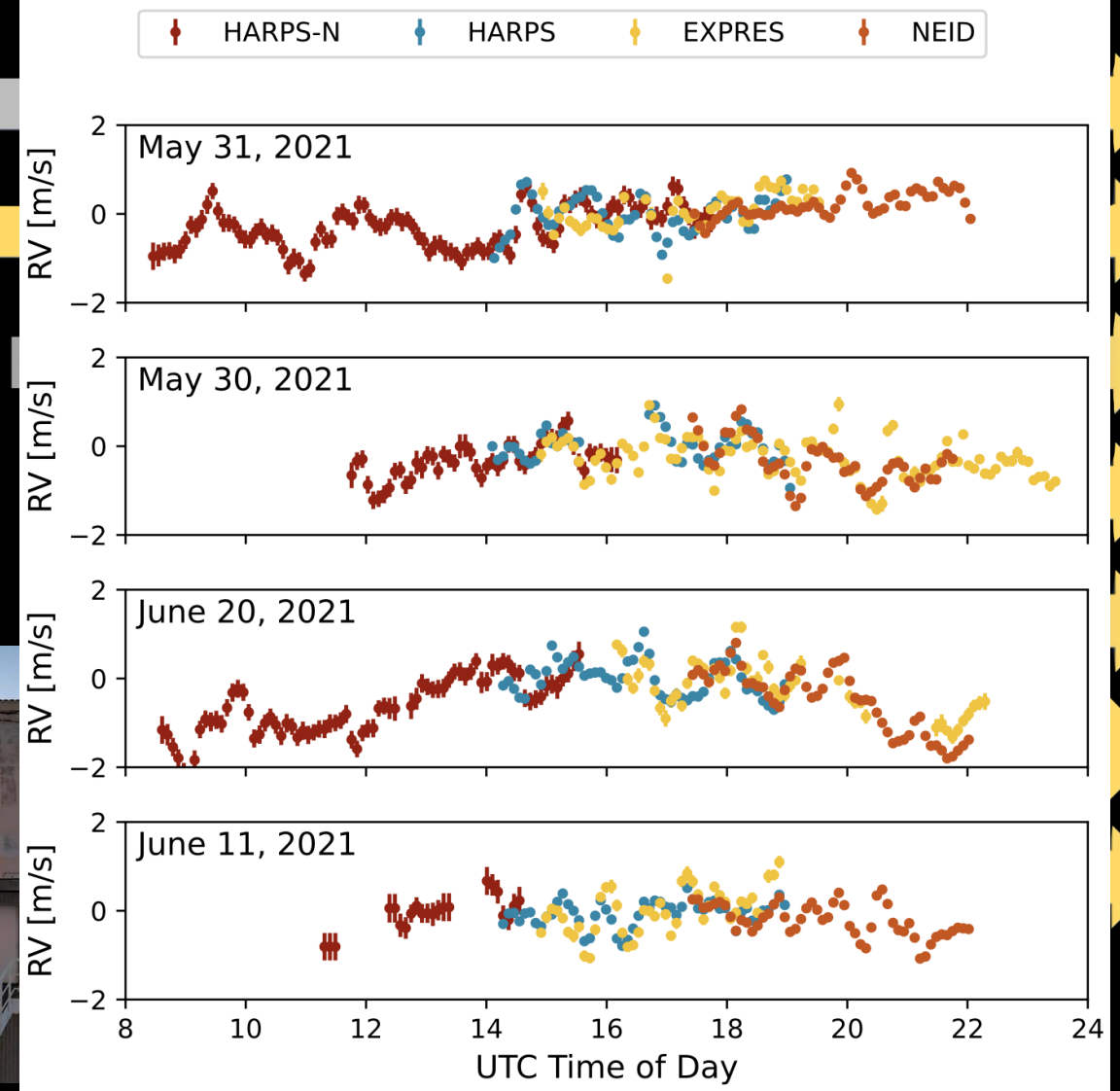
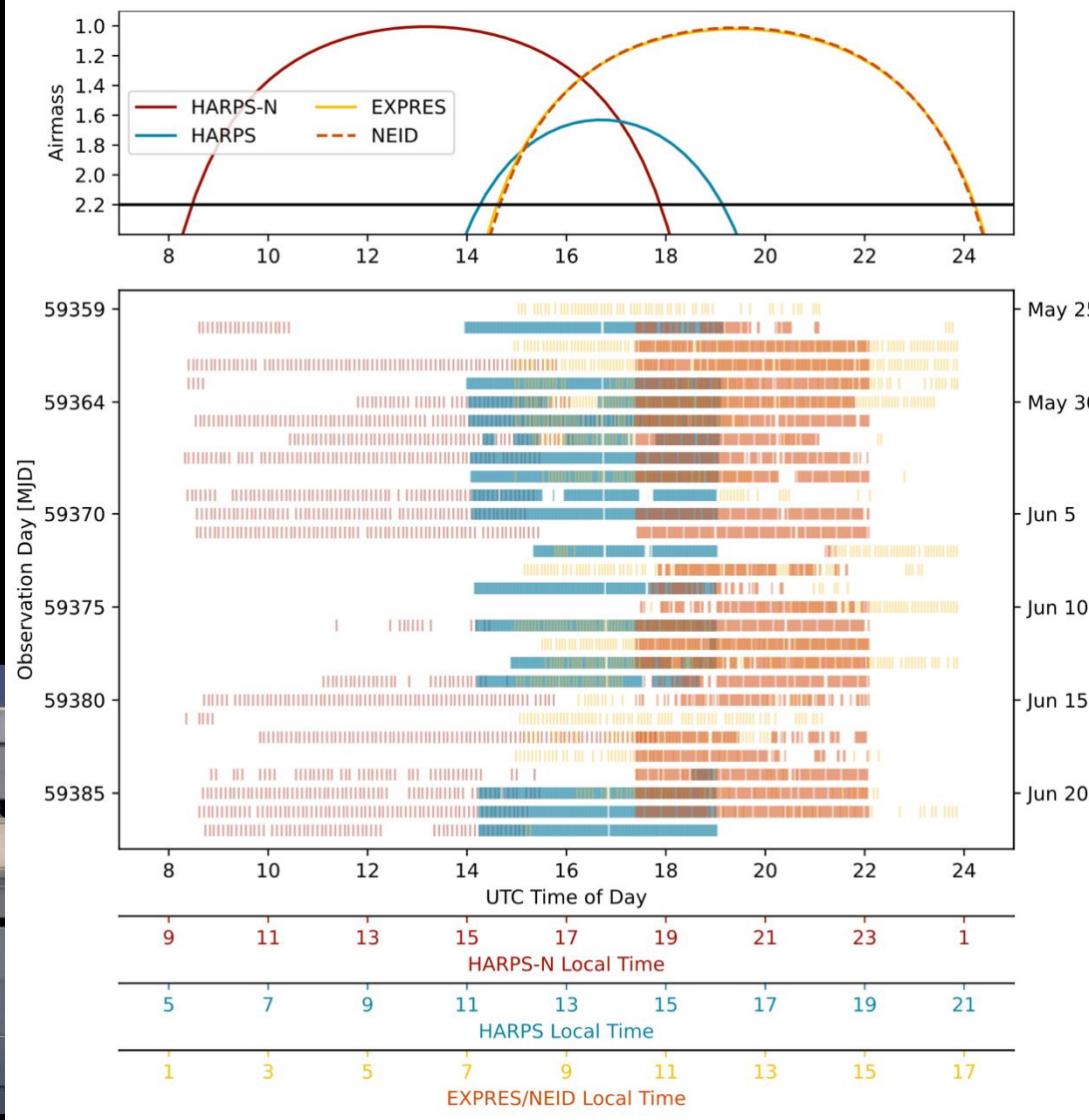
John et al. 2024

State of the Field – Solar RV



State of the Field – Solar RV

Zhao et al. 2023



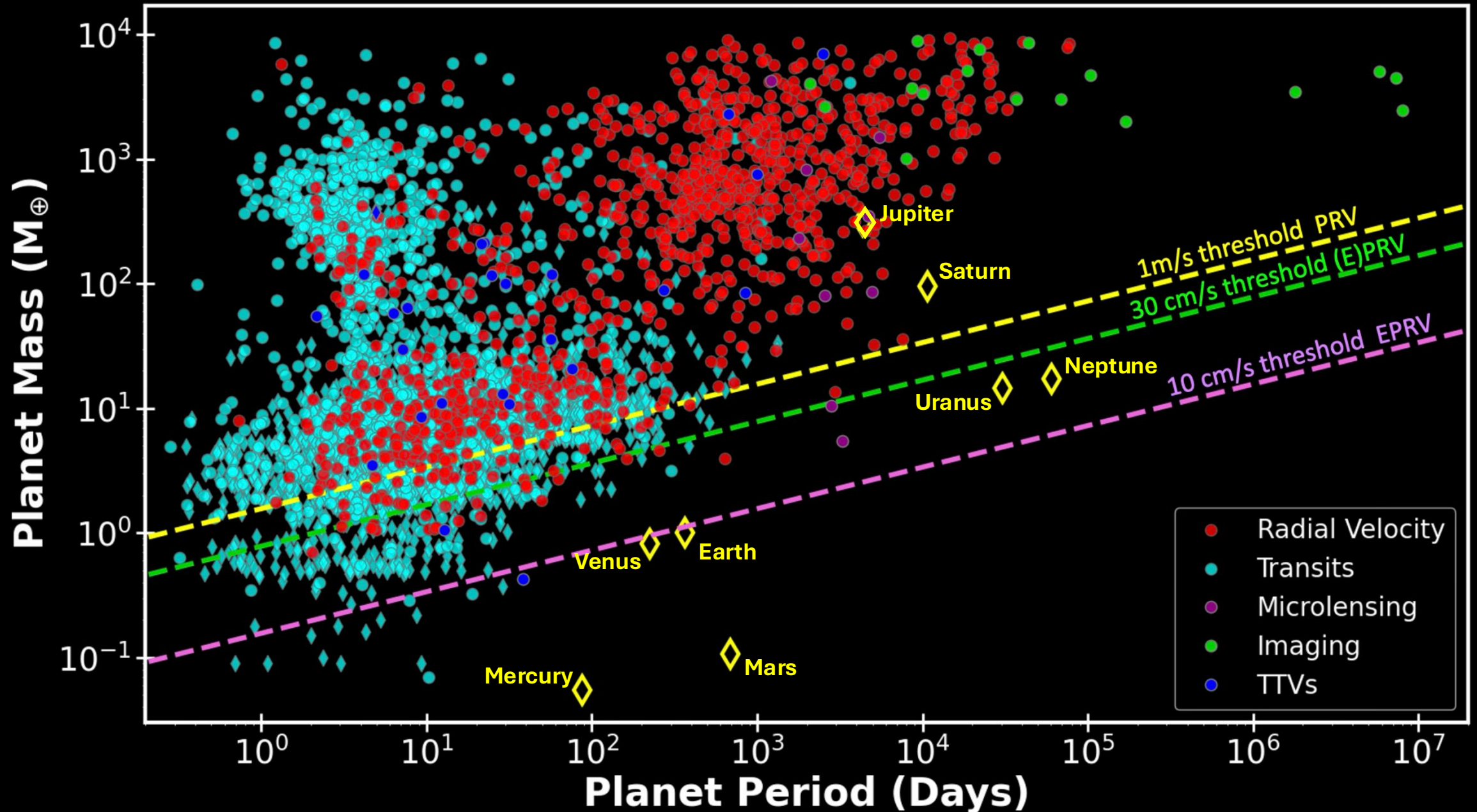
2010

2015

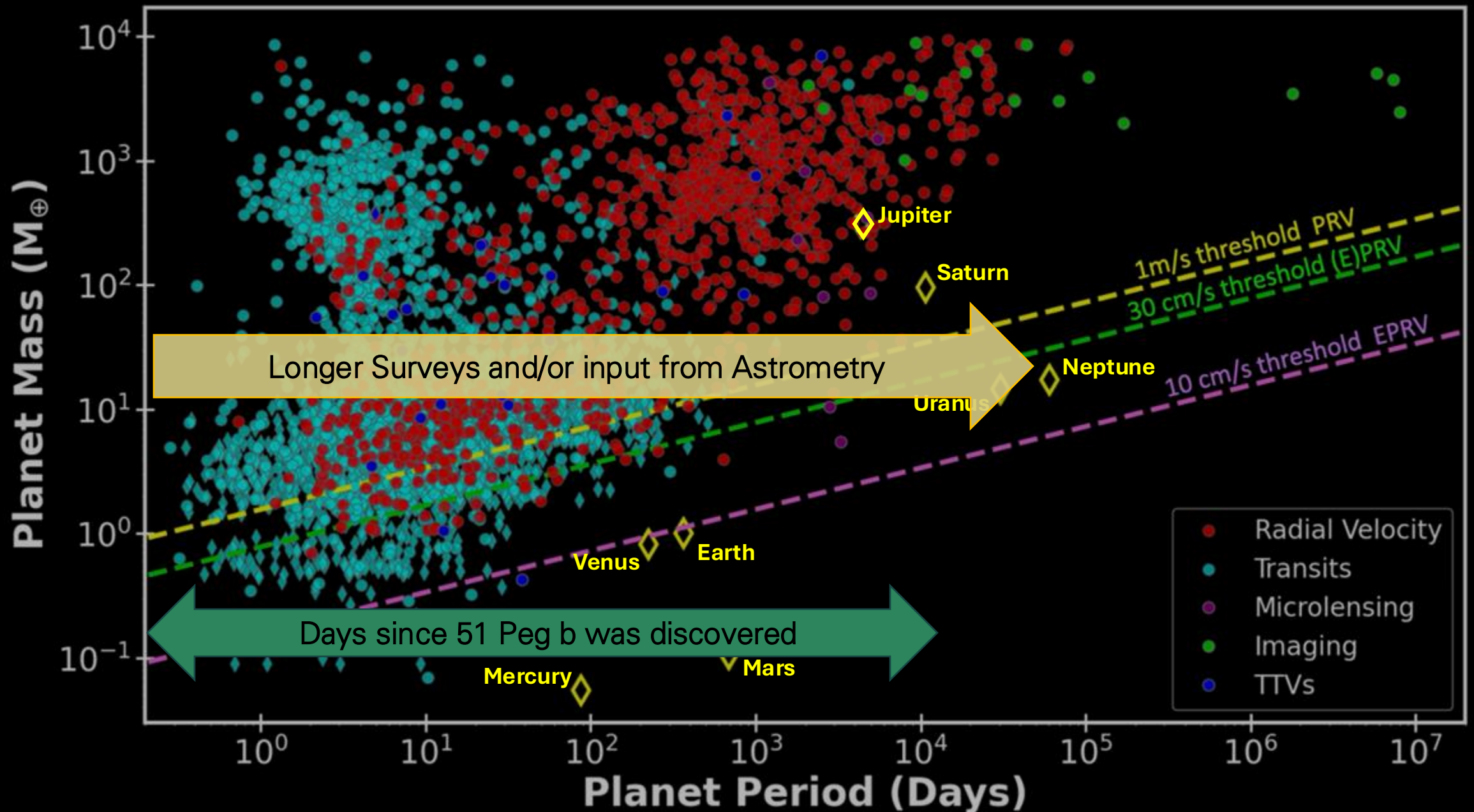
2020

2025

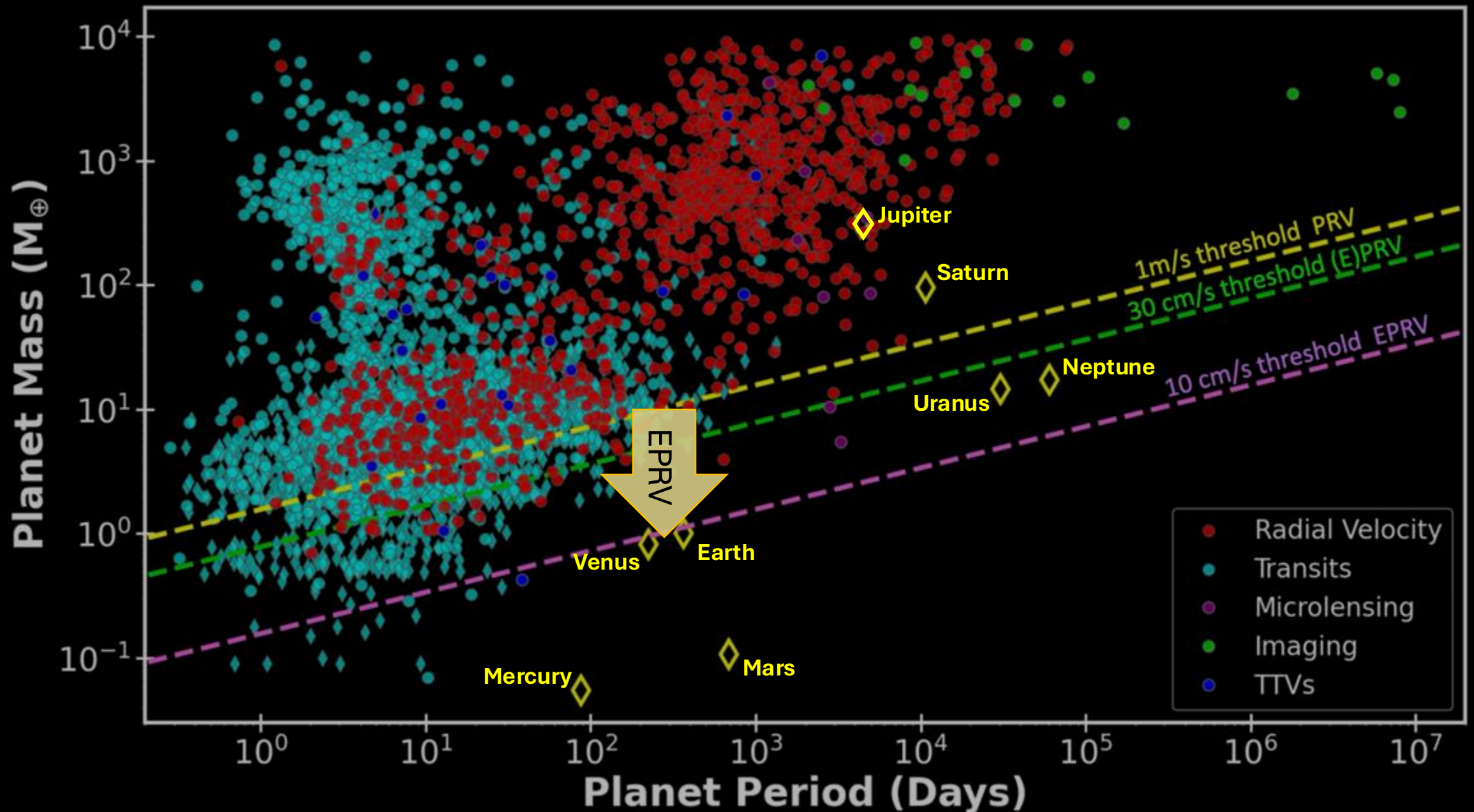
Major Challenges



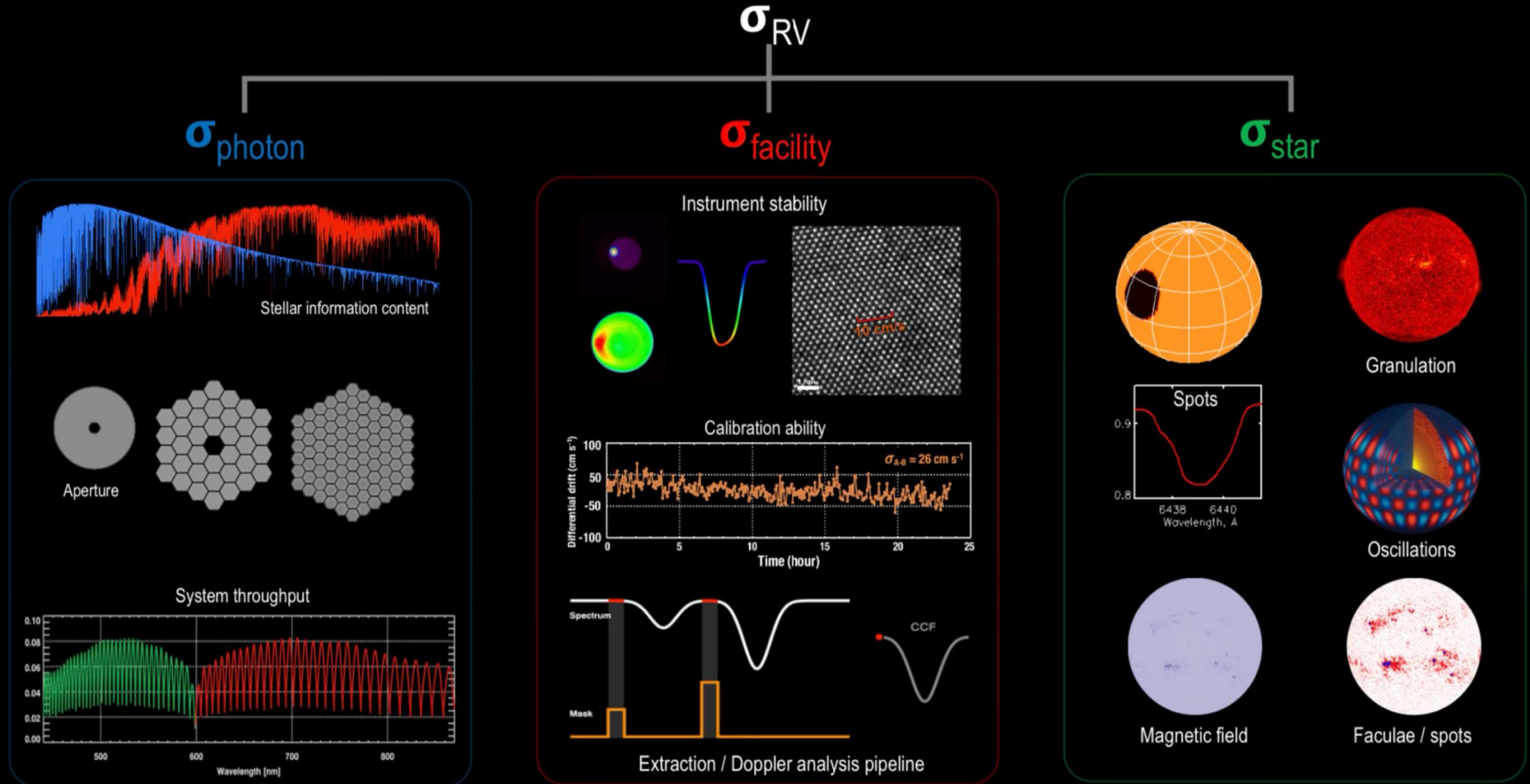
Major Challenges



Major Challenges



Major Challenges



Major Challenges

Useful overview on what's needed to move the field forward to Earth-detecting capabilities presented in the EPRV Working Group's Final Report

(Crass et al. 2021)

TABLE 6-1. Near-term Roadmap (1–5 years) to determine the feasibility and likelihood of a successful EPRV survey.

Stellar Variability:
Support the adoption of solar feeds for spectrographs that demonstrate >100k spectral resolution, SNR > 300 and <50 cm/s stability over a day.
Determine how well variability mitigation strategies built from Sun-as-a-star knowledge translate to other spectral types present in the proposed list of target stars.
Determine the level of RV precision and accuracy enabled by stellar variability mitigation strategies and modeling and the corresponding implications for the planet mass determinations.
Instrumentation:
Maximize knowledge gained from current instruments still under development, construction, commissioning, and that have recently begun operations.
Establish or use existing testbeds for full instrument system development and component testing and characterization, and verification of software-based instrument simulators and select pipeline modules.
Determine whether it will be possible to secure a sufficient number of CCDs for a full EPRV survey in a timely manner.
Determine whether CMOS (complementary metal-oxide semiconductor) detectors are an acceptable replacement for CCD detectors.
Investigate the continued availability of gratings required for high-resolution spectrographs.
Determine if there are alternative, cheaper, and more robust methods of fabricating gratings.
Investigate the feasibility of securing robust, long-lived, high-stability calibration sources.
Architecture:
Determine whether extreme AO in the visible combined with fiber injection of single-mode fiber-fed diffraction limited spectrographs presents a viable and more desirable option than traditional seeing-limited RV instruments.
Determine whether it would be practical to retrofit existing telescopes for dedicated, robotic operation for EPRV observations, or whether new telescopes are required. Determine which of these options presents the least risk and requires the fewest resources.
Identify suppliers for multiple, large-aperture telescope systems and conduct site selection surveys, should the building of new telescopes be required for the full EPRV survey.
Telluric Line Contamination:
Determine whether telluric contamination lines in spectra can be adequately mitigated, over a sufficiently broad wavelength range.
Extensive and Detailed Theoretical Analysis:
Determine what combination of spectral bandwidth, resolution, SNR and cadence is sufficient for the detection of Earth-analog systems.
Explore the advantages of spectropolarimetry in EPRV observations (e.g., as implemented in SPIRou).
Specify, based on lessons learned from observational data, the required quality of the spectra (including resolution and SNR) to detect Earth analogs, which then constrains the required effective apertures, observing time, and cadence.
Software:
Support the development of a well-designed, well-engineered, and actively maintained open-source pipeline with demonstrated ability to retrieve state of the art results on EPRV data from multiple instruments.
Programmatics:
Ensure the needed staffing of personnel with expertise in PRV, heliophysics, and stellar variability to conduct the necessary analysis as well as conduct an EPRV survey. This necessarily involves establishing formal collaborations with non-U.S. entities, and creating attractive employment paths for early career (graduate students, postdoctoral fellows, and non-tenure track researchers) experts in PRV science and technology.
Establish a Research Coordination Network and Standing Advisory Committee.

Major Challenges

Make sure to also check out recordings from the 2020 Sagan Summer Workshop which was entirely focused on EPRV!

Themes included:

- **Fundamentals of PRV, Error Budgets, Instrumentation**
- **Fundamentals of Data Analysis and Statistical Significance**
- **Stellar Signals and Tellurics**
- **Beyond EPRVs: Characterizing Planets**

https://nexsci.caltech.edu/workshop/2020/agenda_virtual.shtml

EPRV Research Coordination Network

Updating the EPRV Working Group's Final Recommendations & Near-Term Road Map

A Community Forum To Capture Recent Advancements In:

- Stellar Variability
- Instrumentation
- Telescope Architectures
- Telluric Line Contamination
- Theoretical Analyses
- Software & Pipelines
- Programmatics
- Leveraging Modern Datasets

Thursday, December 19, 2024 | 8a – 10a Pacific

Event posted to the RCN Google Calendar
Zoom Link: bit.ly/EPRV_Recommendation_Updates

Presented by the
EPRV Research Coordination Network



WAVELENGTHS

EPRV & Machine Learning Workshop

Tuesday June 11th, 8:00 – 11:30a Pacific Time

Overview Talks

- 8⁰⁰ Extreme Precision RV for Machine Learning Experts -- Eric Ford [Penn State]
- 8³⁰ Machine Learning for Extreme Precision RV Experts -- Chris Shallue [Harvard University]

Science Presentations

- 9⁰⁰ "Improving Earth-like Planet Detection in Radial Velocity Using Deep Learning" -- Yinan Zhao [University of Geneva]
- 9²⁰ "Transfer Learning for Mitigating Stellar Variability Using Sun-as-a-Star Observations" -- Jinglin Zhao [DTU Space]
- 9⁴⁰ "AESTRA: Deep Learning for Precise RV Estimation in the Presence of Stellar Activity" -- Yan Liang [Princeton University]
- 10⁰⁰ "Removing Systematics from Contaminated Lines in SPIRou RVs using Weighted PCA" -- Merwan Ould-Elhkim [IRAP]
- 10²⁰ "EPRVs of Planet-Hosting Stars in the Presence of Stellar Noise using Deep Learning" -- Virisha Timmaraju [JPL]

Panel Discussion

- 10⁴⁰ – 11³⁰ "Future Directions for Leveraging Machine Learning in EPRV" -- featuring Zoe de Beurs [MIT], Eric Ford [Penn State University], Umaa Rebbapragada [JPL] & David Hogg [NYU/Flatiron]

Presented by the
EPRV Research Coordination Network



EPRV Colloquium Series: May 29th, 2025
8a PT / 11a ET / 4p UK / 5p CEST

Chris Lam [University of Florida]
"gaspery: Optimized Scheduling of Radial Velocity Follow-Up Observations for Active Host Stars"

Hannah Osborne [University College London]
"Homogenous analysis of small planet masses"



Presented by the
EPRV Research Coordination Network

From Wobbles to Worlds:

The role of precision
radial velocities in
exoplanet discovery
and characterization

Dr. Jennifer Burt
Exoplanet Exploration Program Office
