

Looking for Moons



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Outline of this Talk

I. Background

II. Theory

III. Modeling

IV. Challenges

V. Synthetic Example

I. Background

Why bother?

- Intrinsic habitability
- Extrinsic habitability
- Planet formation theory

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- **Intrinsic habitability**
- Extrinsic habitability
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- Intrinsic habitability
- Extrinsic habitability
- Planet formation theory

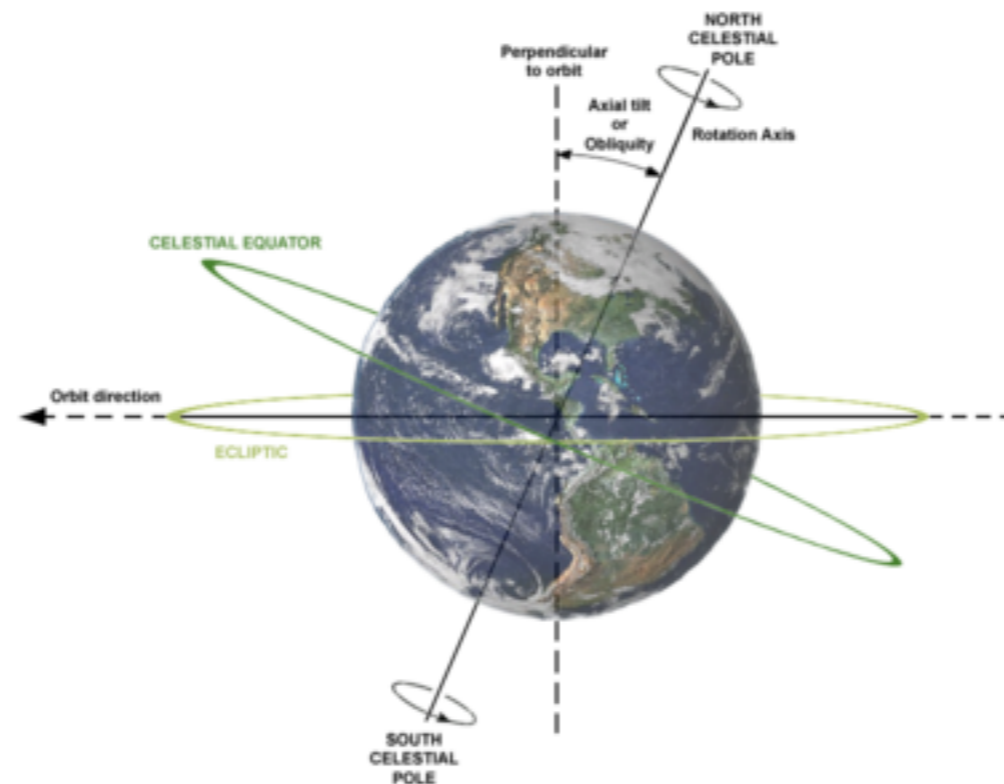


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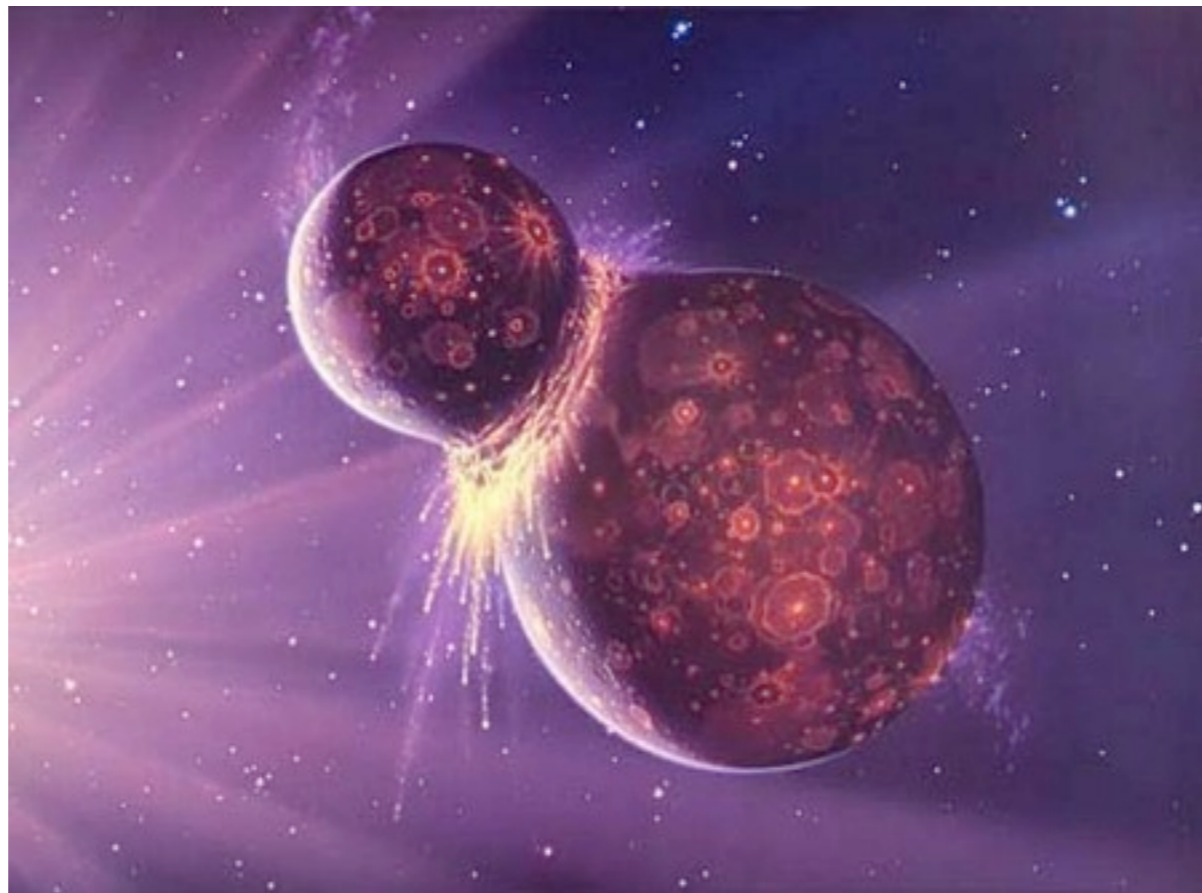


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- Intrinsic habitability
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Order-of-Magnitude Feasibility

- Roughly, Kepler is sensitive to $\sim 1 R_{\oplus}$ planets
- \Rightarrow Kepler is sensitive to $\sim 1 R_{\oplus}$ moons
- We may be able to detect Earth-sized/mass moons

Large Exomoons

- Largest known moon is Ganymede
- $R=0.413 R_{\oplus}$; $M=0.025 M_{\oplus}$
- Not Earth-sized or mass \Rightarrow likely undetectable



Large Regular Moons?

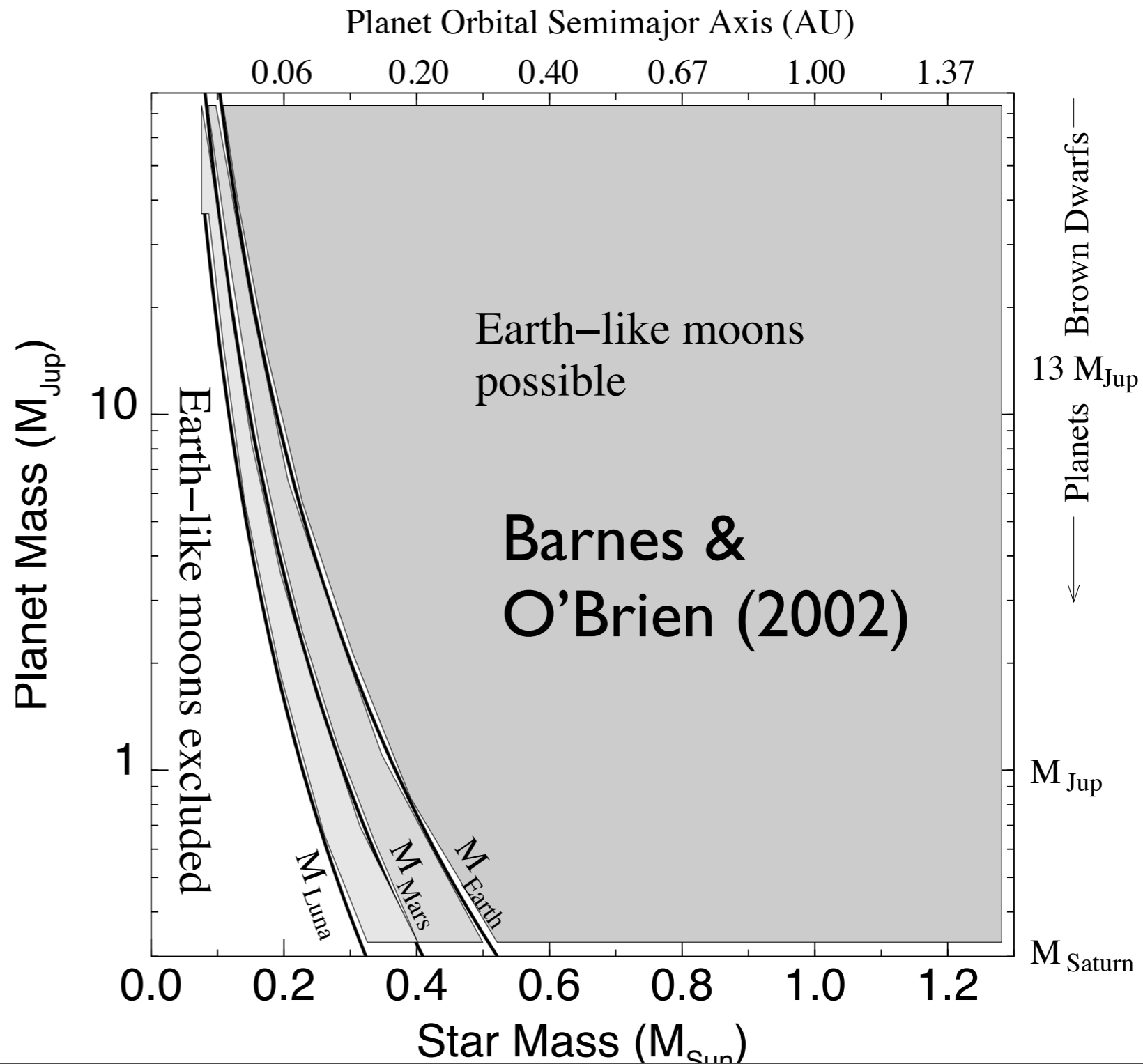
- *Two classes of satellites: Regular & Irregular*
- Regular satellites form in orbit of host planet
- Examples: Galilean satellites, Titan
- Canup & Ward (2004) argue this process limits $\sum m_i \approx (2 * 10^{-4}) M_P$
- Bad news for large moons

Large Irregular Moons?

- *Two classes of satellites: Regular & Irregular*
- Irregular satellites come from elsewhere
- Examples: Triton, the Moon
- No obvious limit. We only require dynamical stability.
- Good news for large moons?

Large Stable Moons

- Moon must be within the Hill sphere
- Moon tends to spin-in/out due to tides



Checklist

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- ✓ Motivation to look for exomoons

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- ✓ Feasible existence of large (detectable) moons

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- ✓ Motivation to look for exomoons
- ✓ Feasible existence of large (detectable) moons
- ? Viable method to detect such moons

II. Theory

Transits

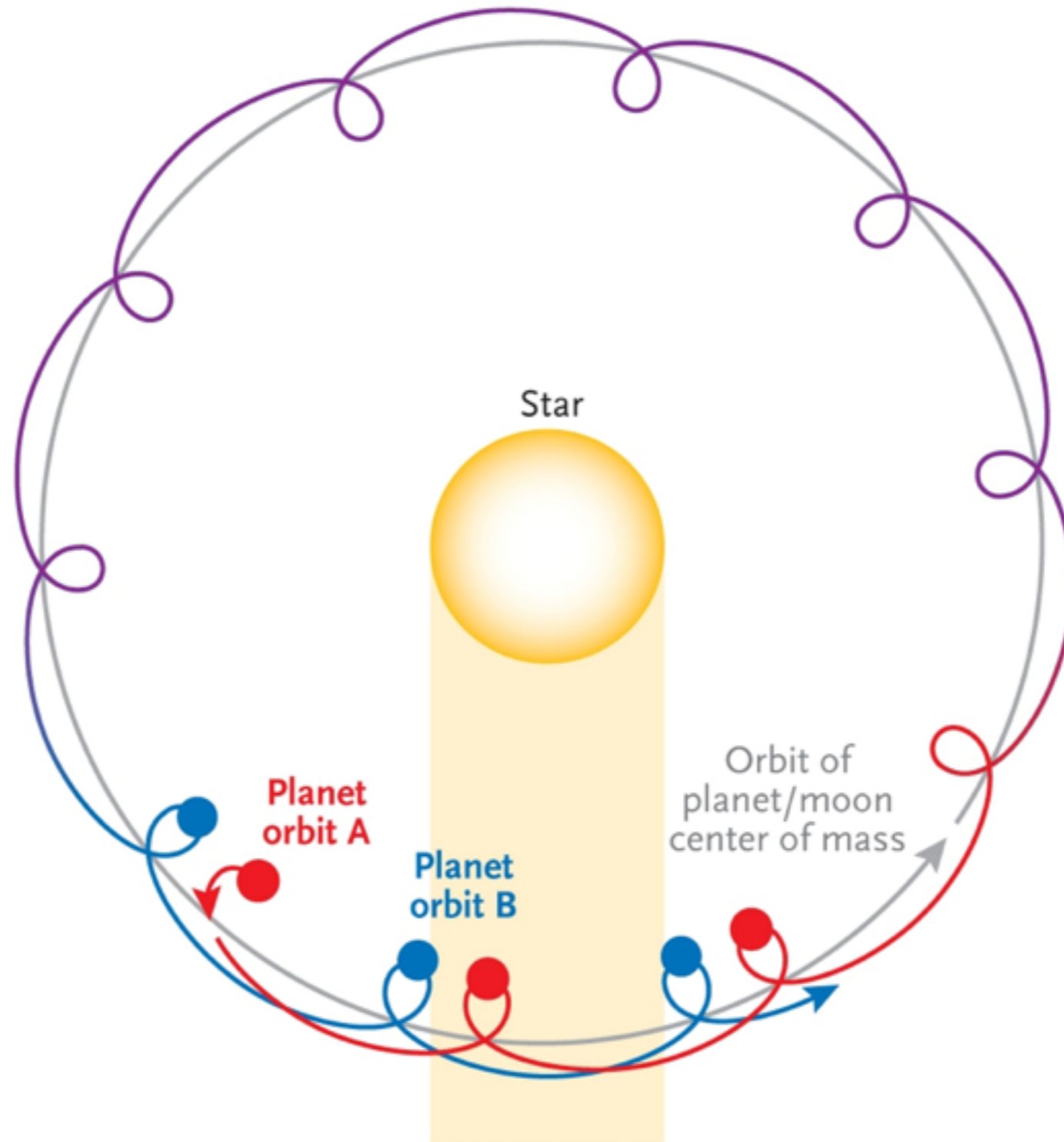
- The remainder of this talk will focus on the transit method.
- ***This is not the only method to detect exomoons.***
- Notably, microlensing is a highly viable method.
- Astrometry, radial velocity, direct imaging, eclipse timing, pulsar timing are less viable.

Observational Consequences

1. Dynamical effects (gives M_s)
2. Eclipse effects (gives R_s)

Transit timing variations (TTV)

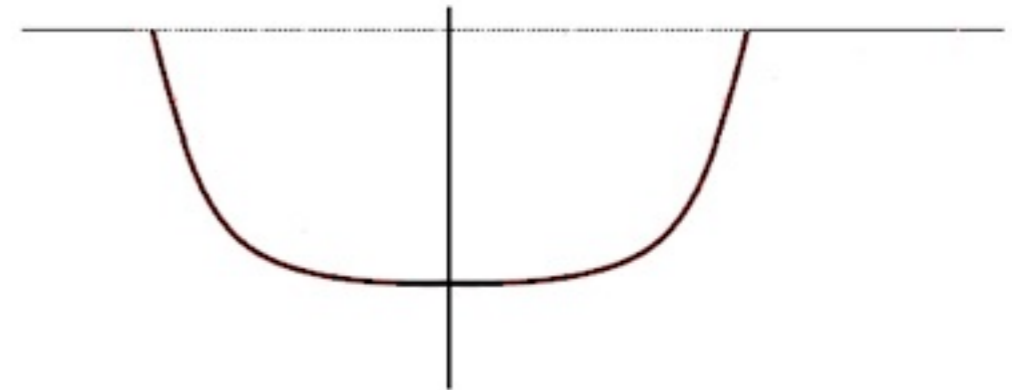
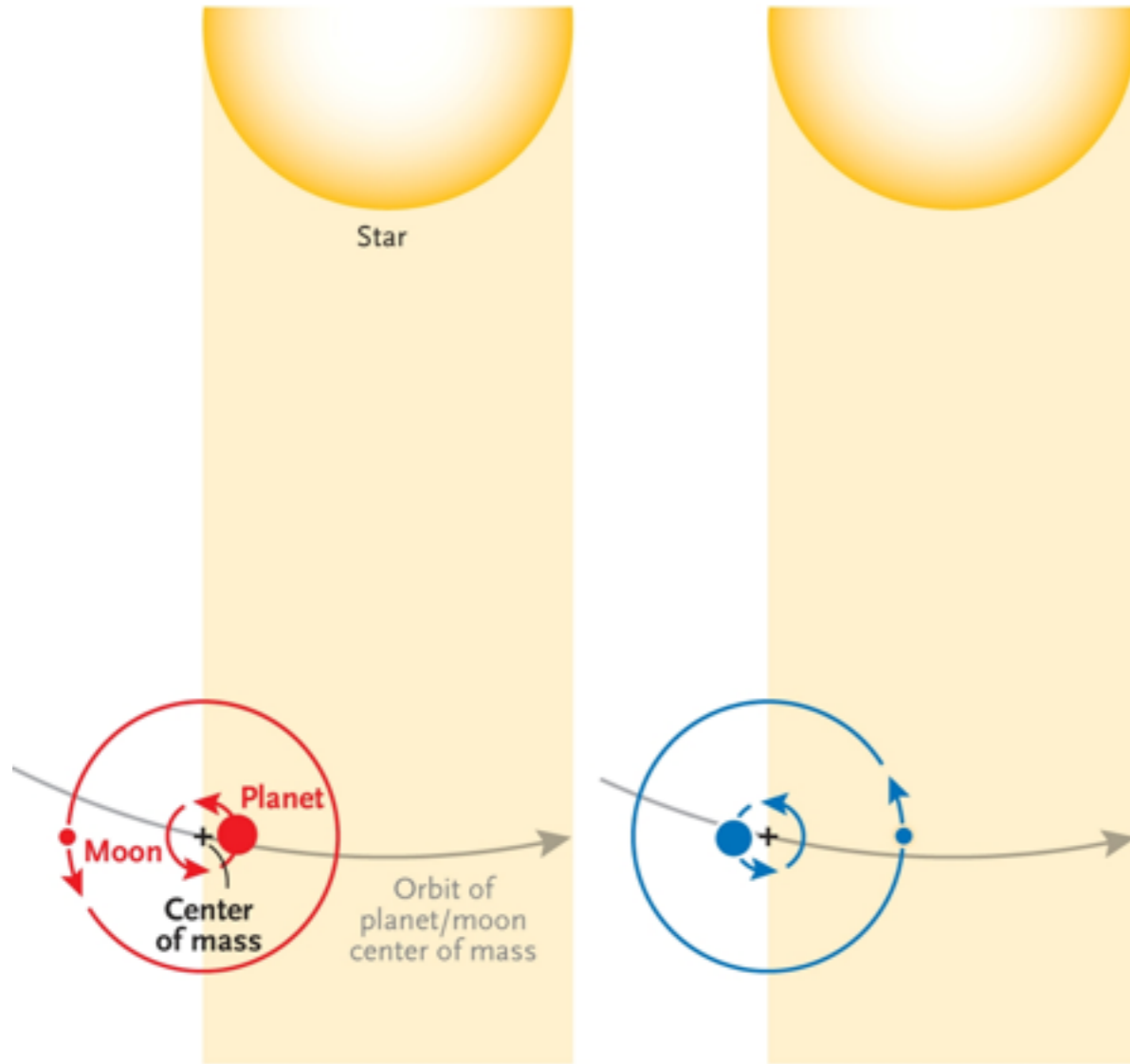
Transit timing variations (TTV)



Transit Timing Variation (TTV)

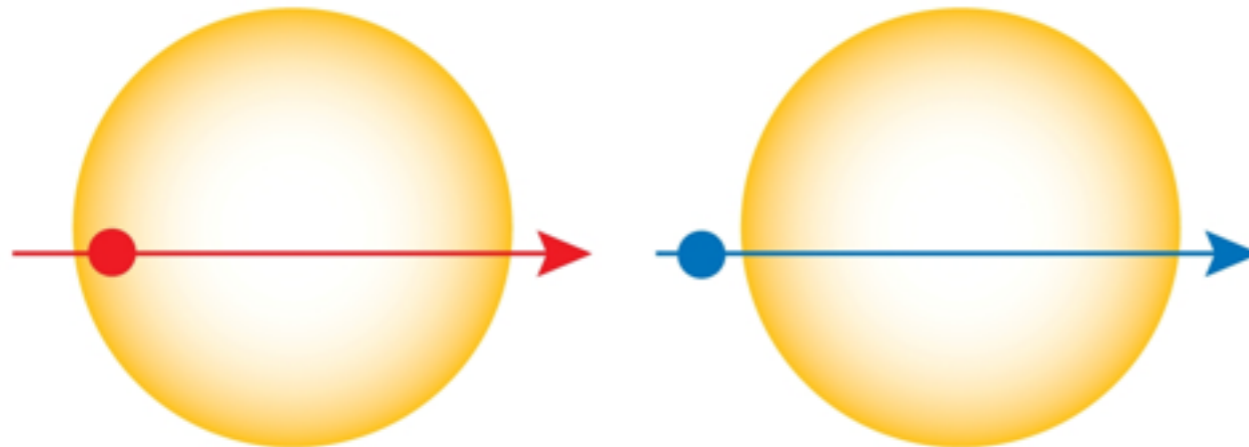
Orbit A Transit

Orbit B Transit



Orbit A Transit

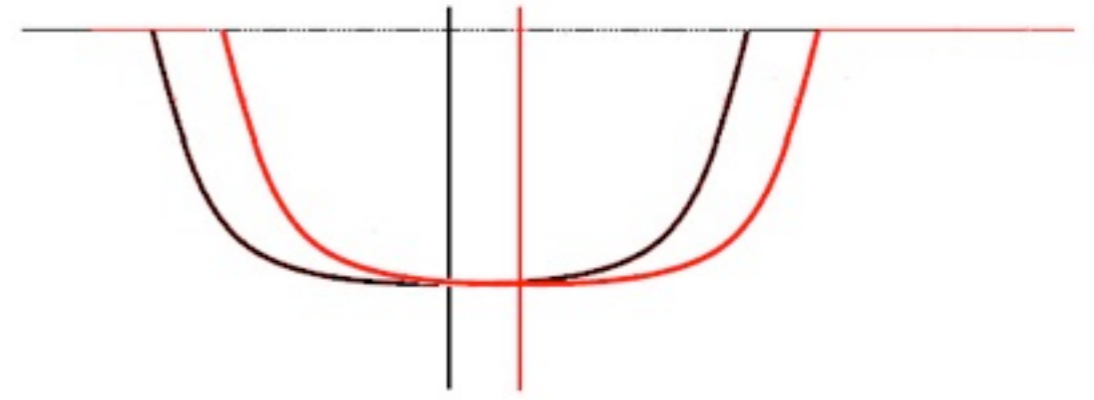
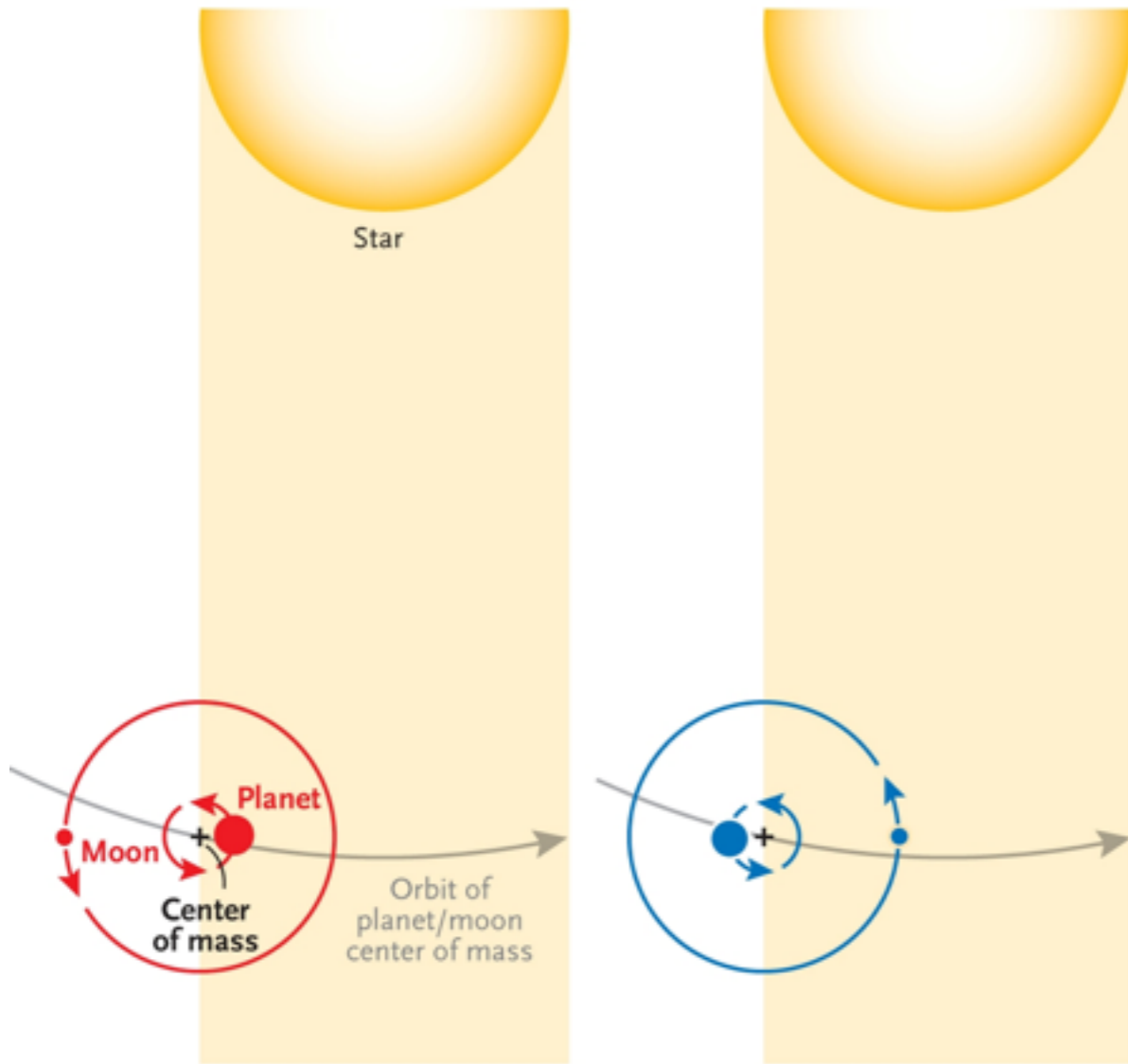
Orbit B Transit



Transit Timing Variation (TTV)

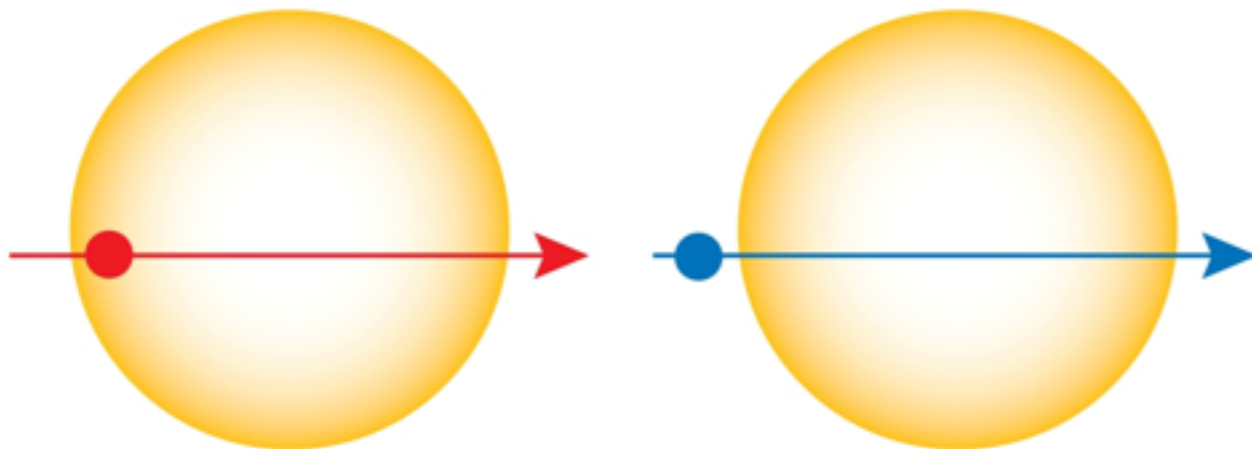
Orbit A Transit

Orbit B Transit



Orbit A Transit

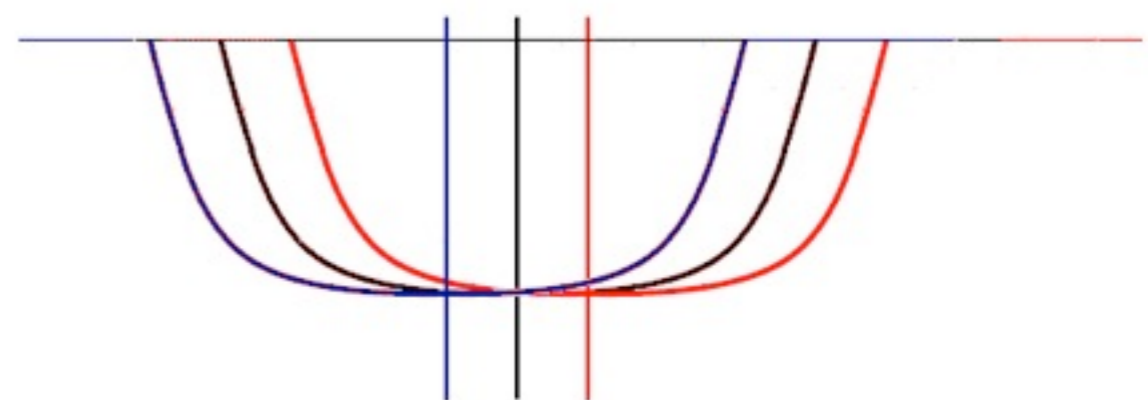
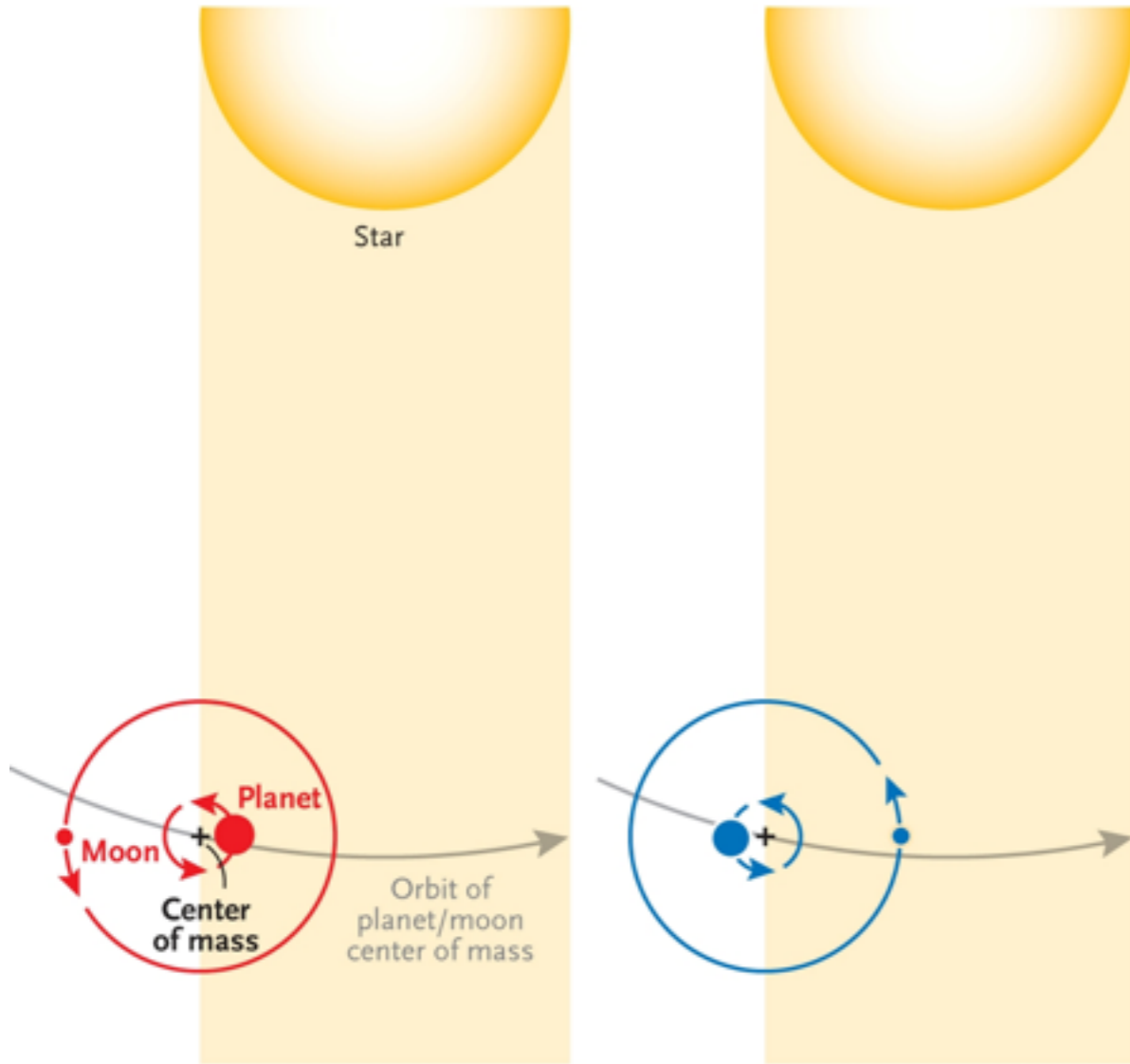
Orbit B Transit



Transit Timing Variation (TTV)

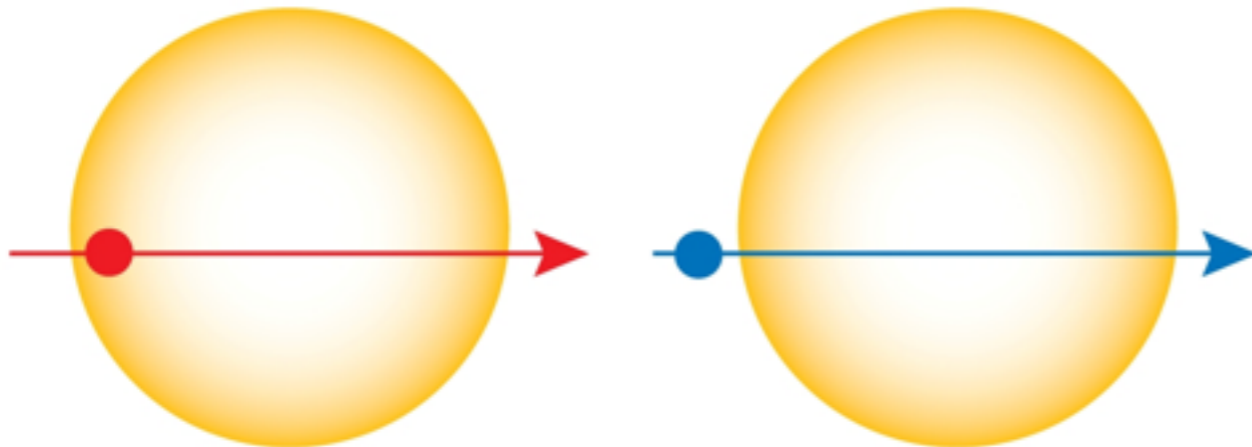
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Orbit B Transit

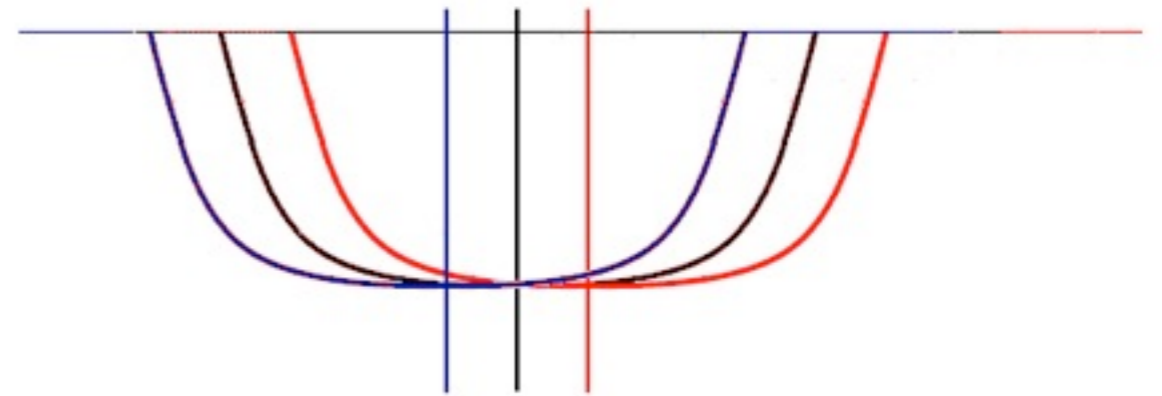
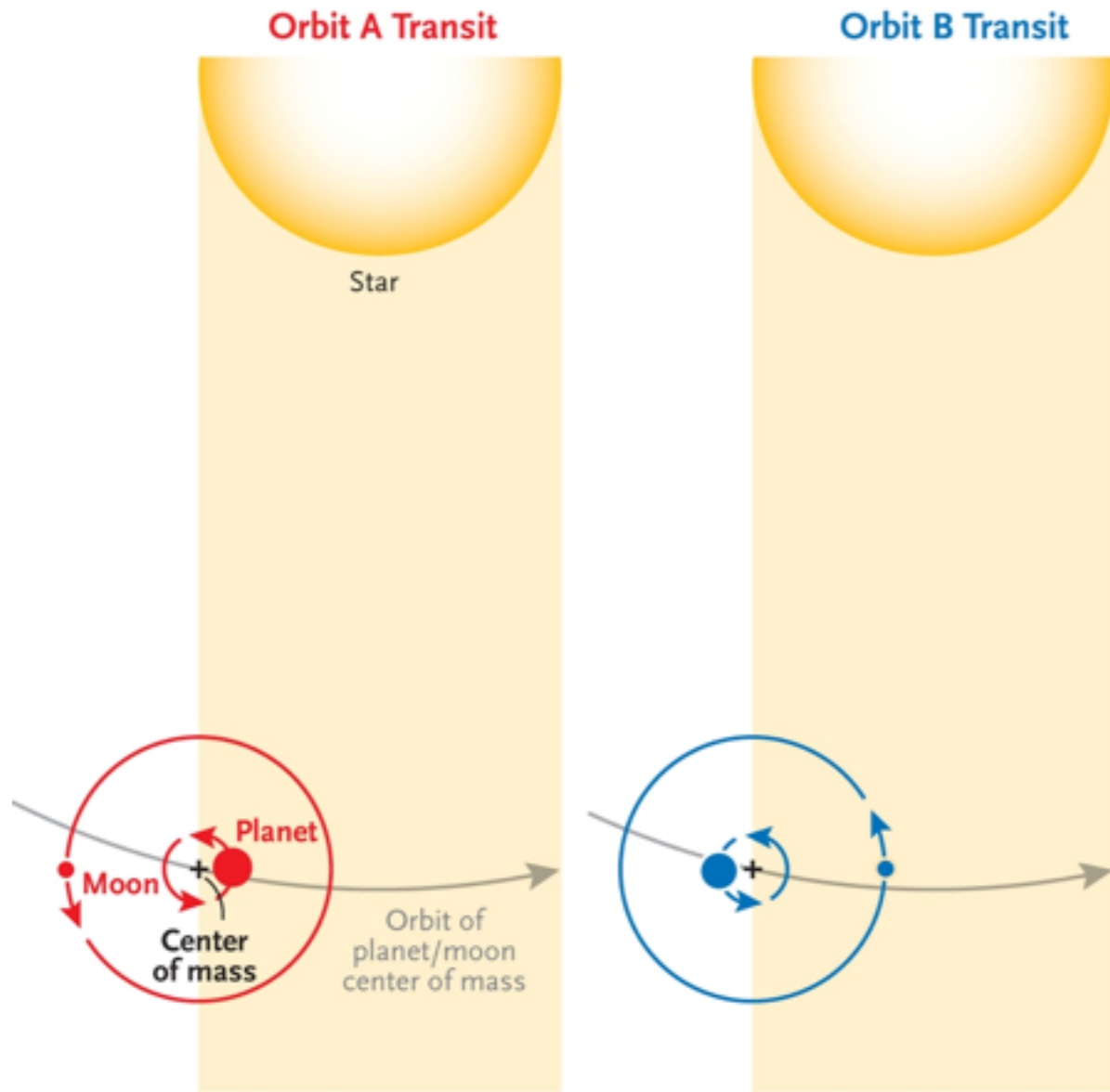


Orbit A Transit

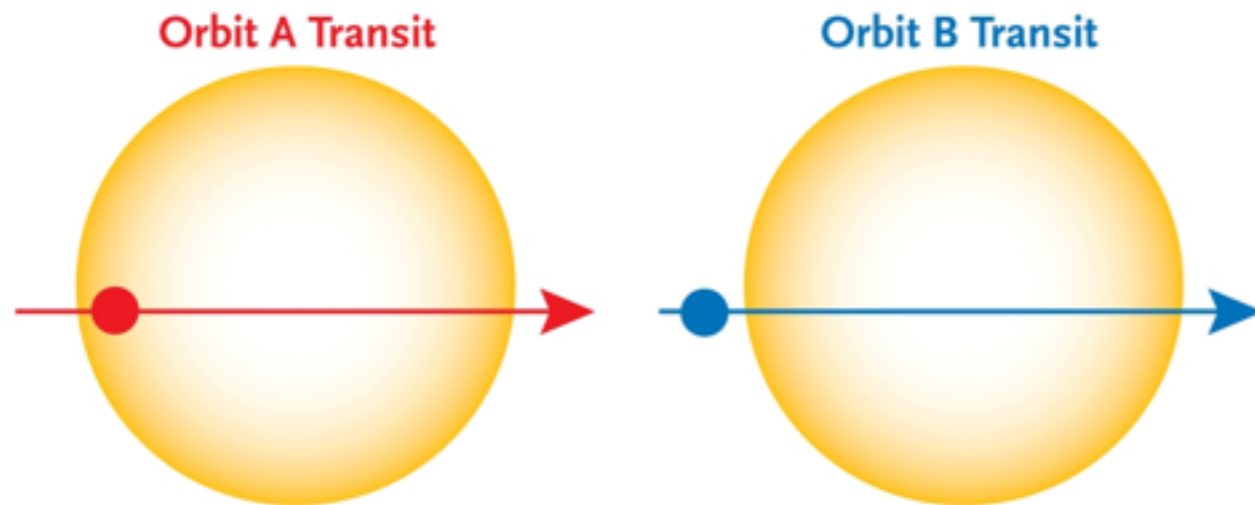
Orbit B Transit



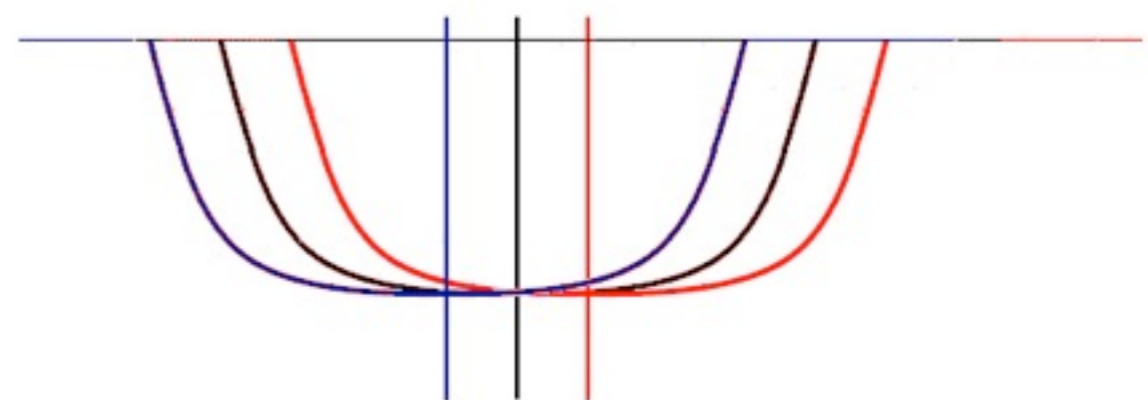
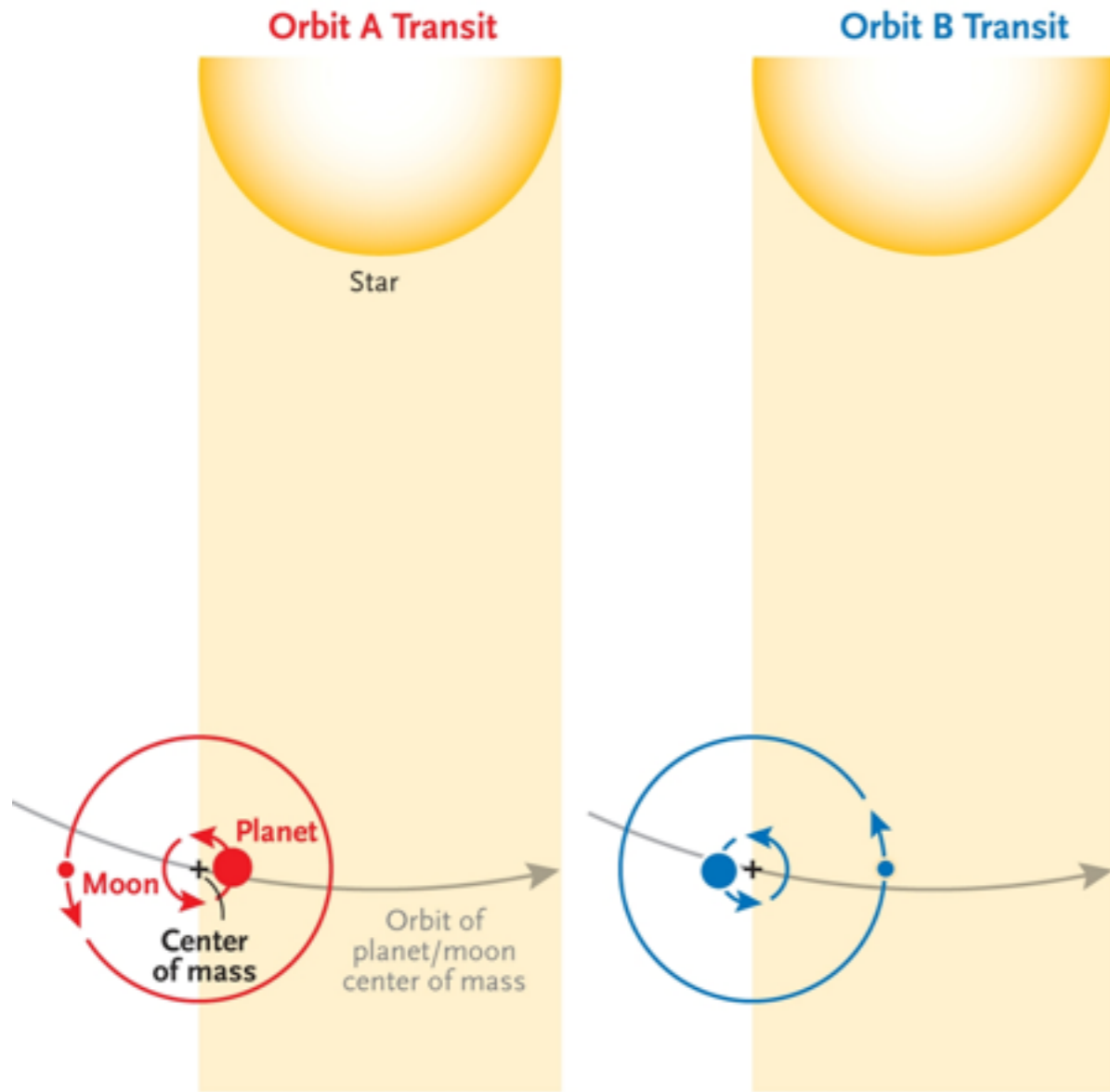
Transit Timing Variation (TTV)



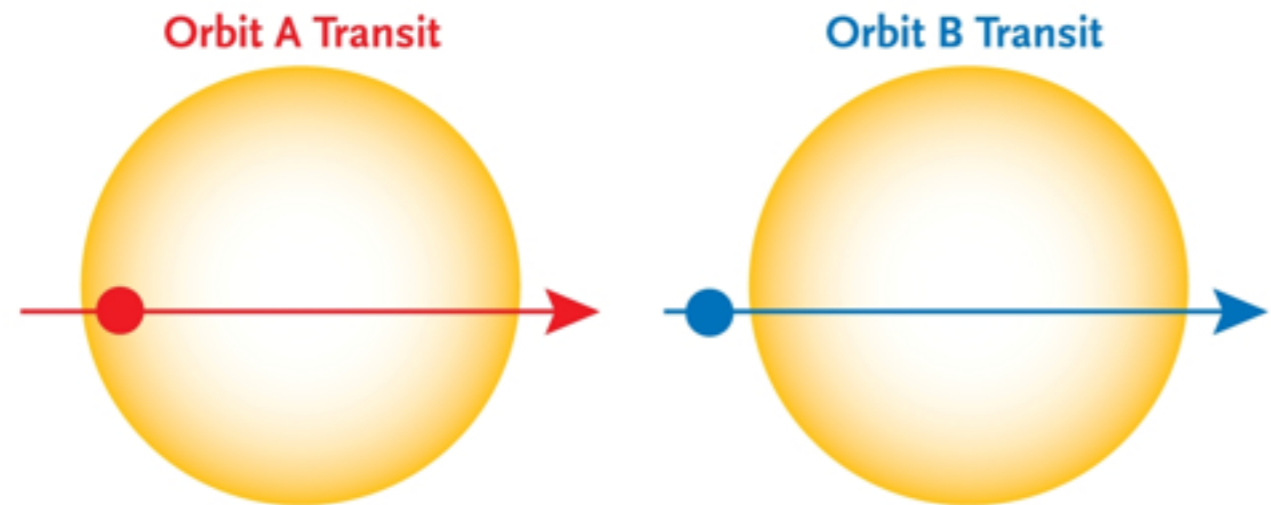
$$\delta_{\text{TTV}} = \frac{a_S M_S P_P (1 - e_S^2) \sqrt{1 - e_P^2}}{a_P M_P (1 + e_P \sin \omega_P)} \sqrt{\frac{\Phi_{\text{TTV}}}{2\pi}}$$



Transit Timing Variation (TTV)

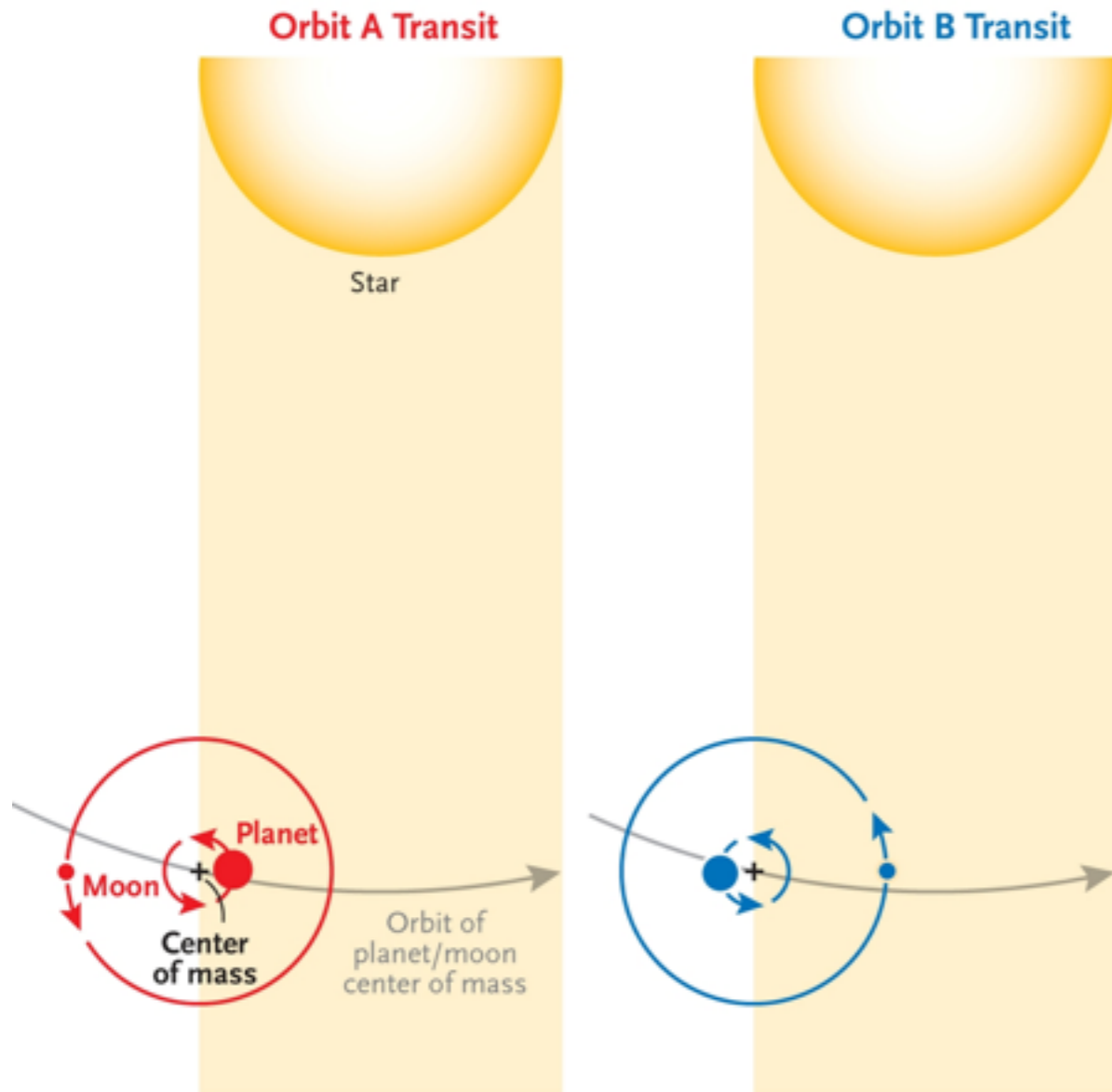


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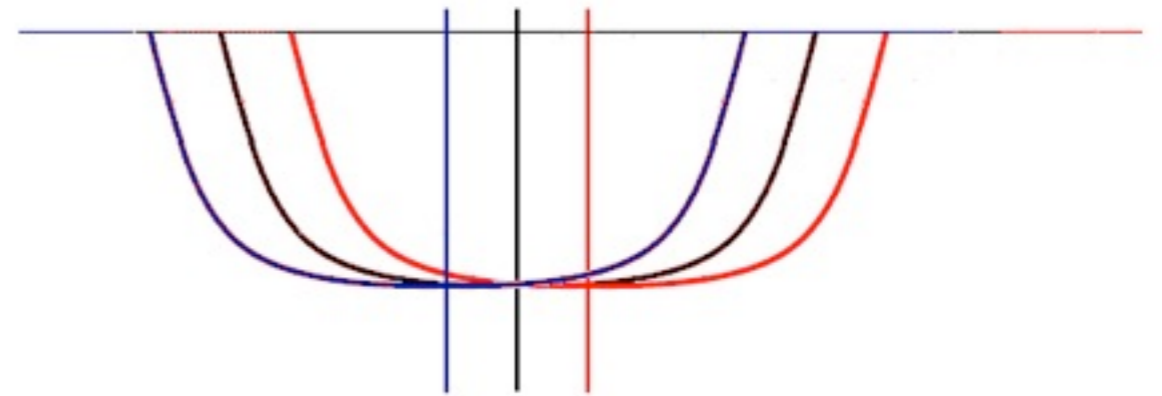


$$\text{TTV} \sim a_S M_S$$

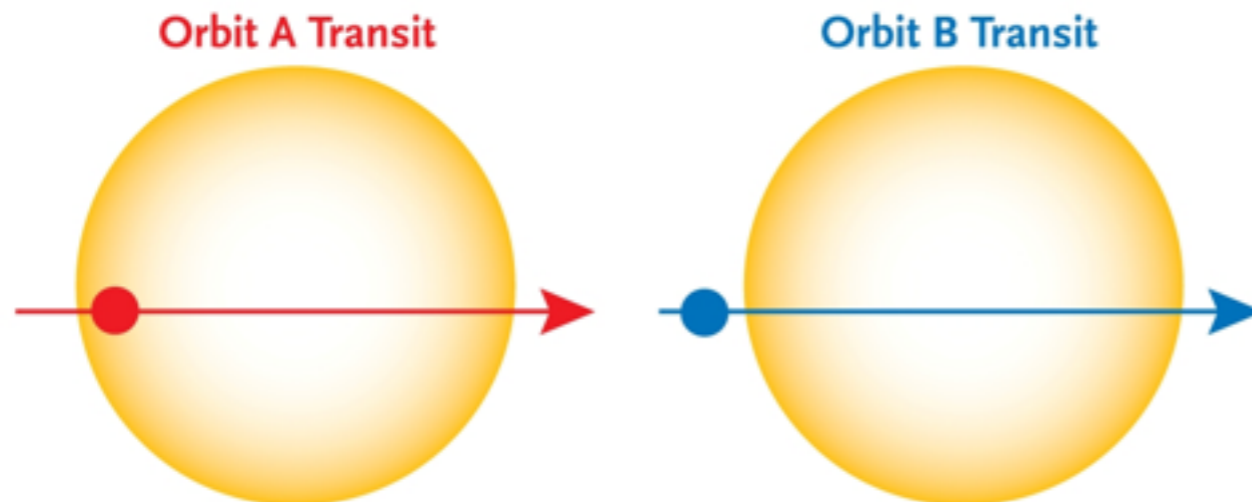
Transit Timing Variation (TTV)



TTV is analogous to astrometry



$$\delta_{\text{TTV}} = \frac{a_S M_S P_P (1 - e_S^2) \sqrt{1 - e_P^2}}{a_P M_P (1 + e_P \sin \omega_P)} \sqrt{\frac{\Phi_{\text{TTV}}}{2\pi}}$$

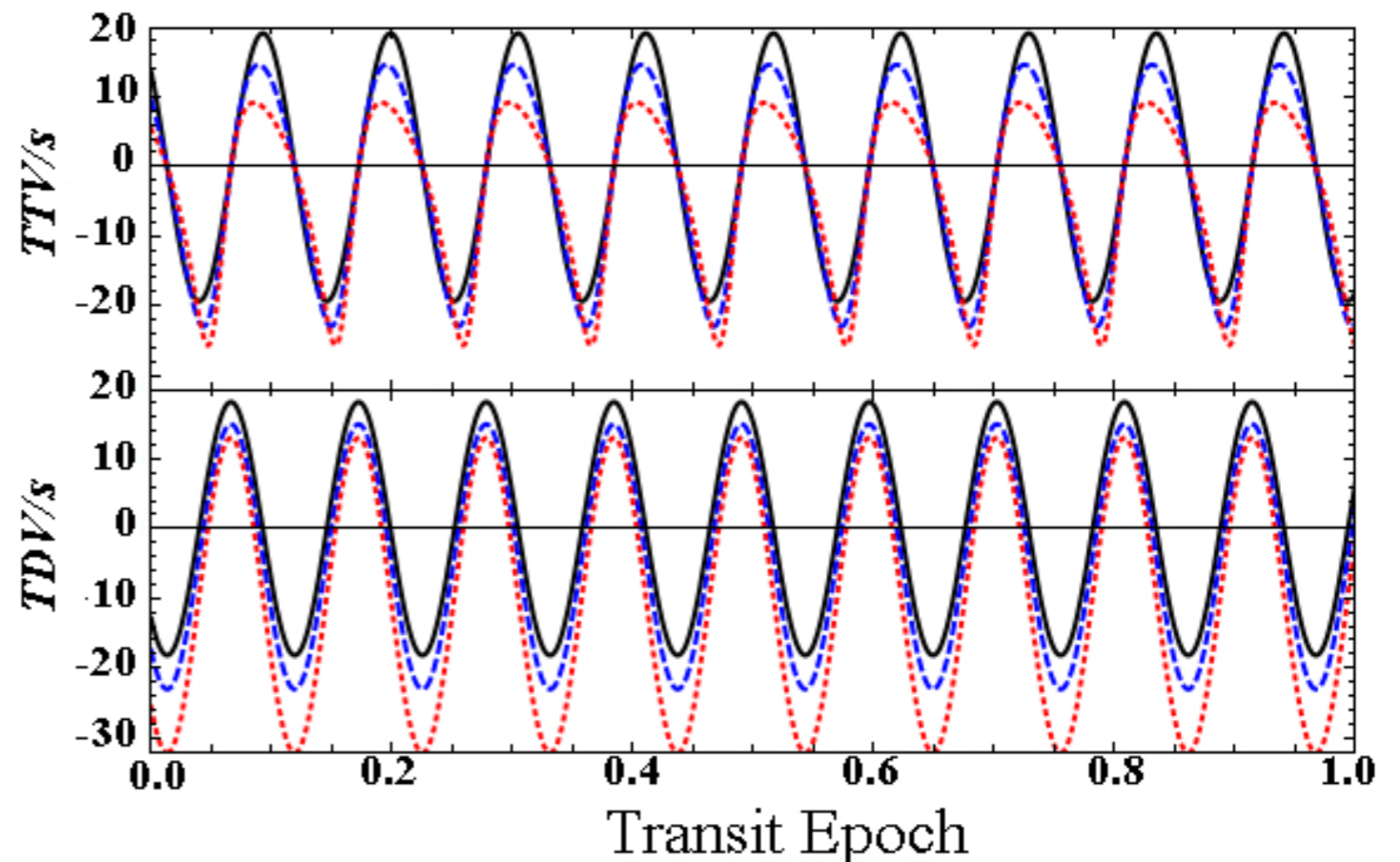


$$\text{TTV} \sim a_S M_S$$

Undersampling

- TTV $\sim a_s M_s$ and usually one gets a_s by measuring P_s and using Kepler's Third Law.
- But, $P_s < P_p$ and usually $P_s \ll P_p$
- We only measure a TTV once per $P_p \Rightarrow$ heavy undersampling

$$P_s = P_p \mathcal{D}^{3/2} \left(\frac{1}{3} \right)^{1/2}$$



Undersampling

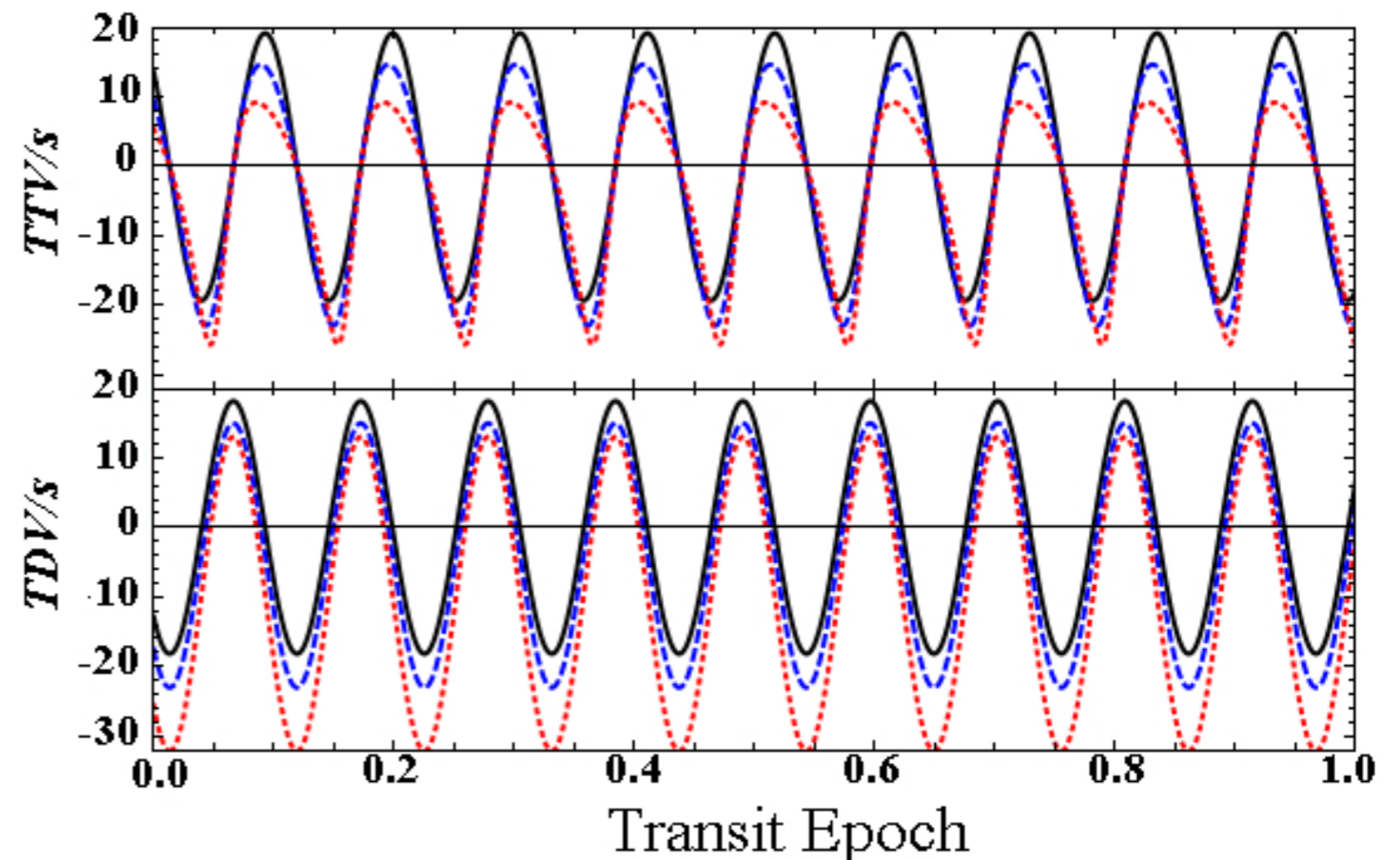
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$$P_s = P_p \mathcal{D}^{3/2} \left(\frac{1}{3} \right)^{1/2}$$

PROBLEM I:

\Rightarrow Cannot measure P_s !

\Rightarrow Cannot measure M_s !

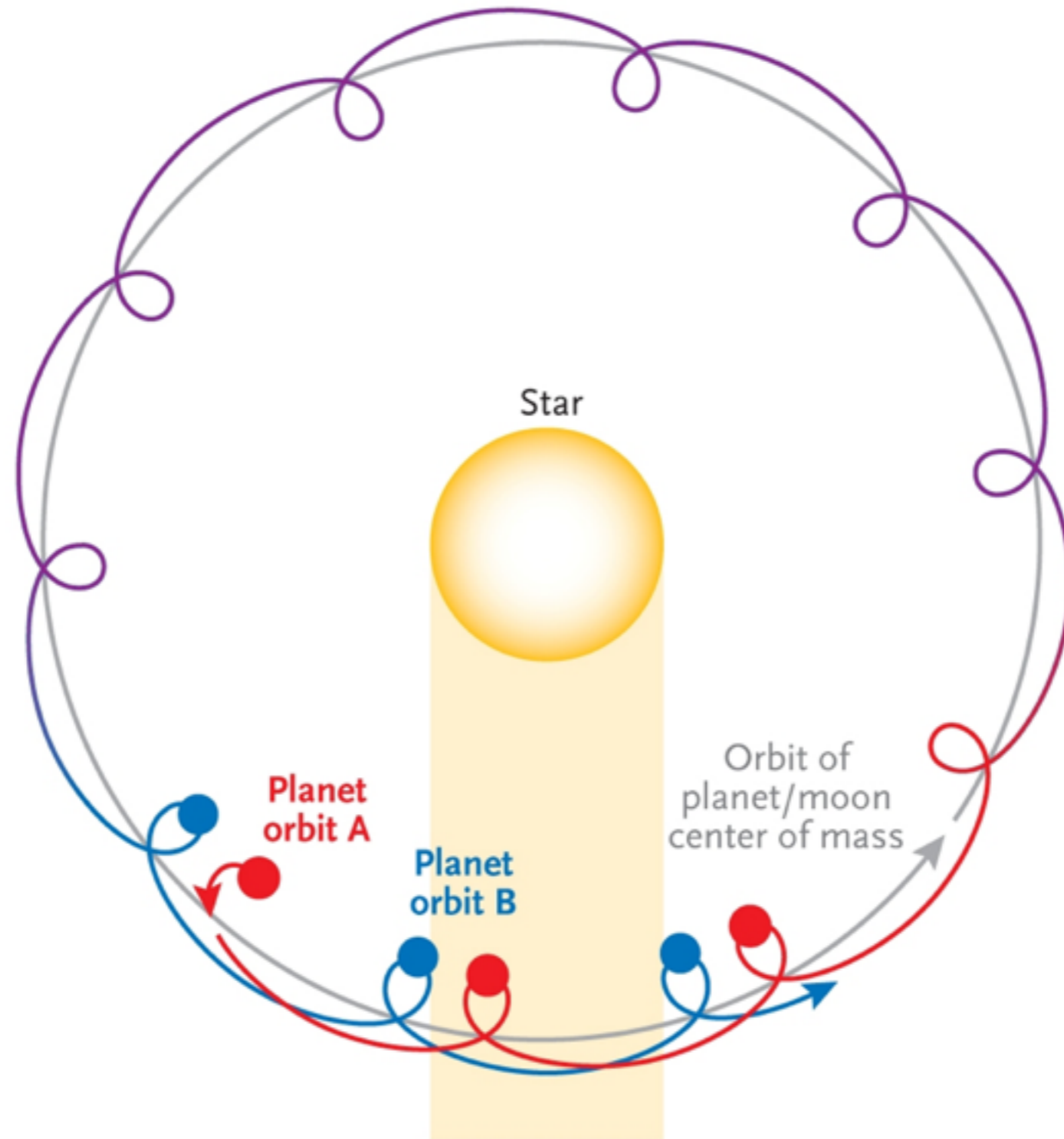


Also...

PROBLEM 2:

How do you tell the difference between an exomoon TTV and a second planet TTV?

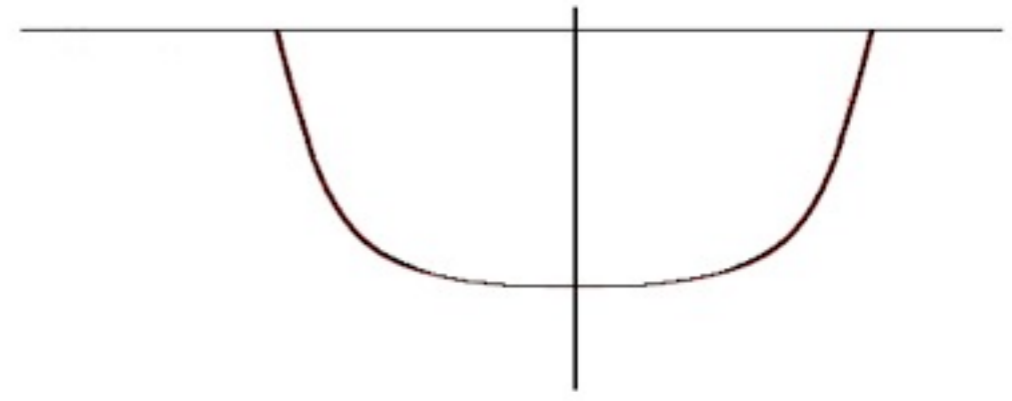
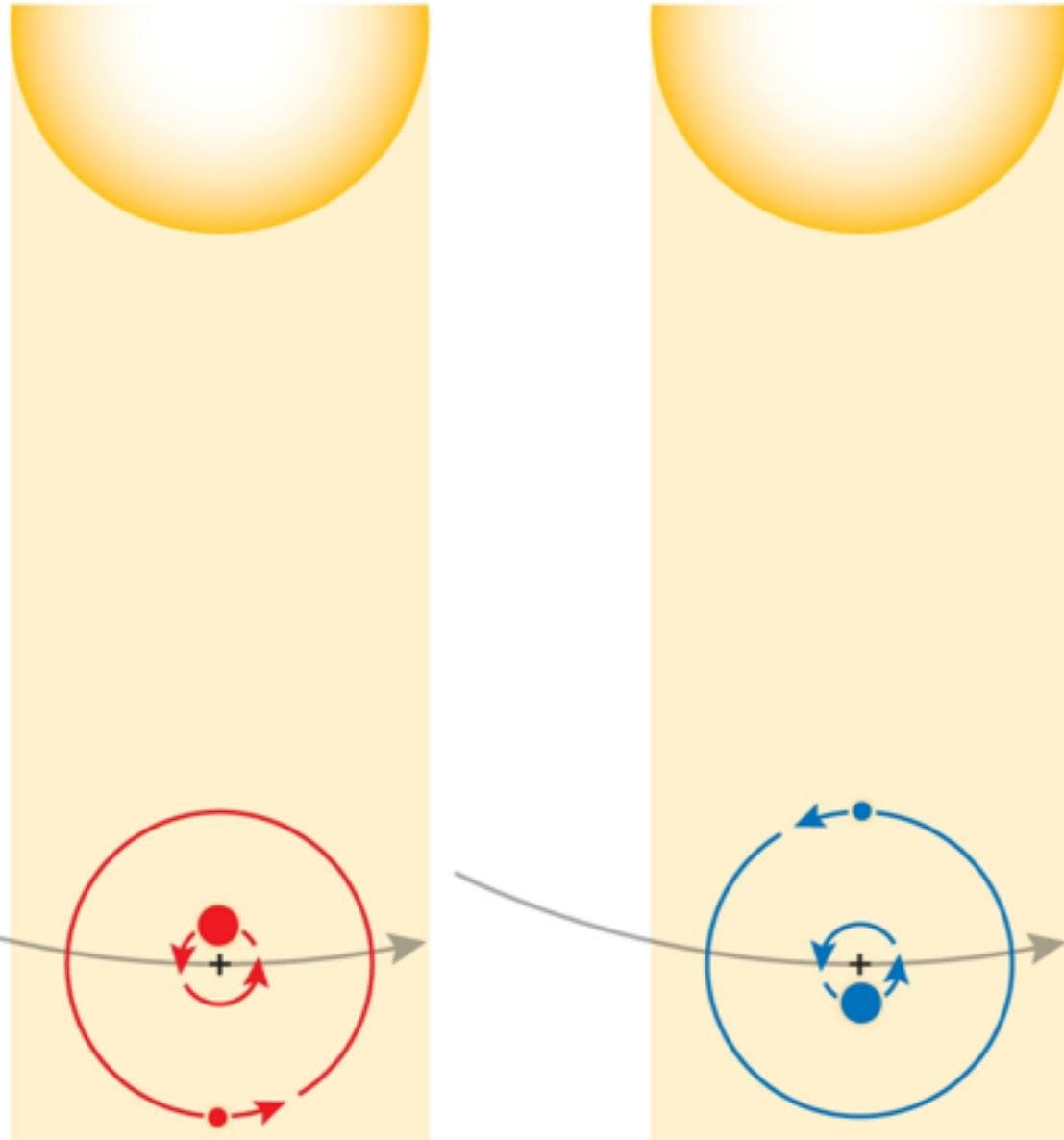
Velocity-induced transit duration variations (TDV-V)



Transit Duration Variation (TDV)

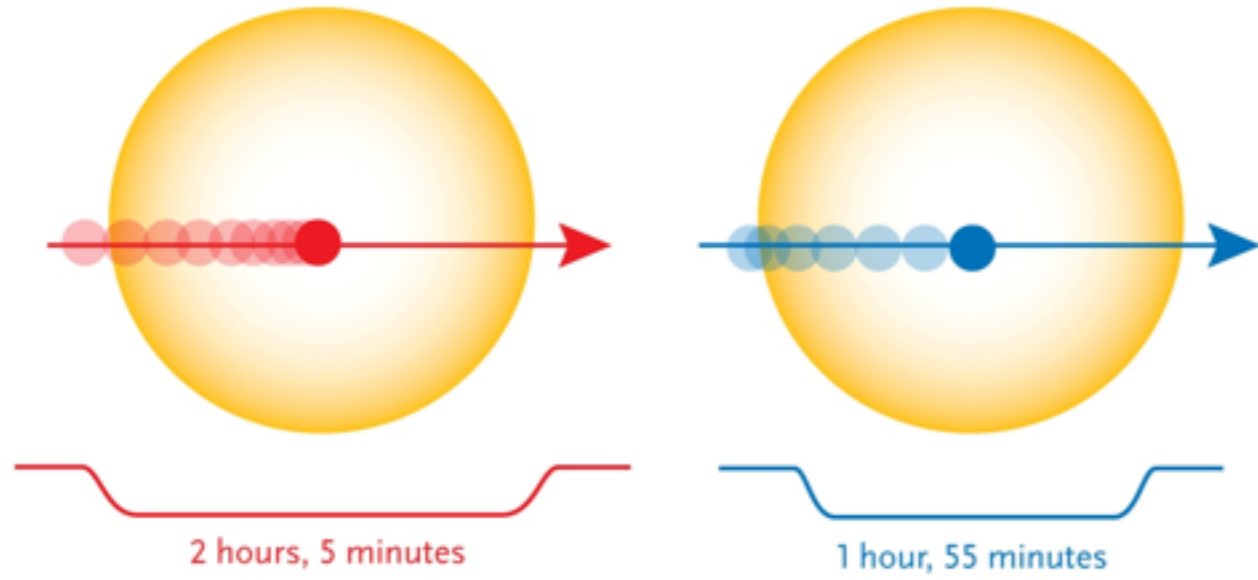
Orbit A Transit

Orbit B Transit



Orbit A Transit

Orbit B Transit



2 hours, 5 minutes

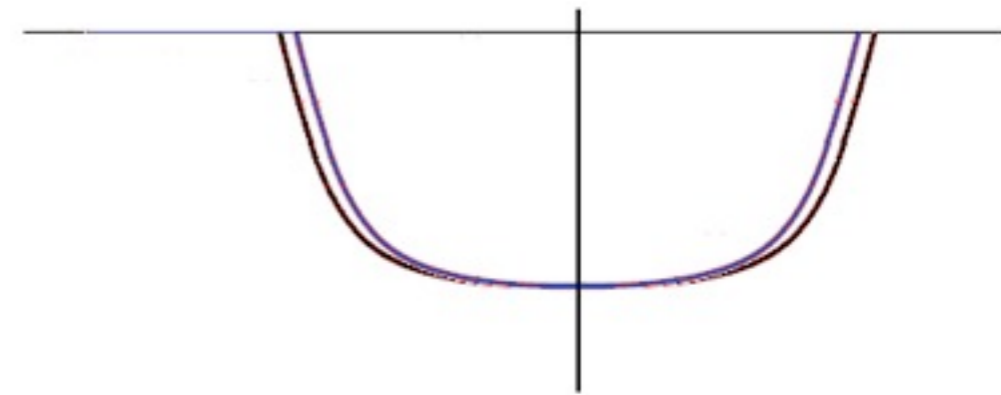
1 hour, 55 minutes

Transit Duration Variation (TDV)

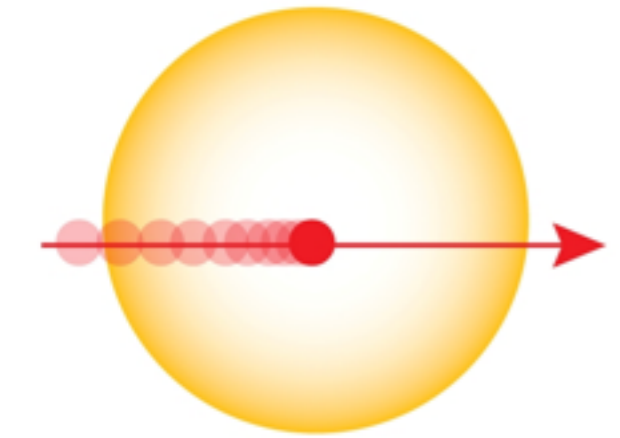
Orbit A Transit



Orbit B Transit

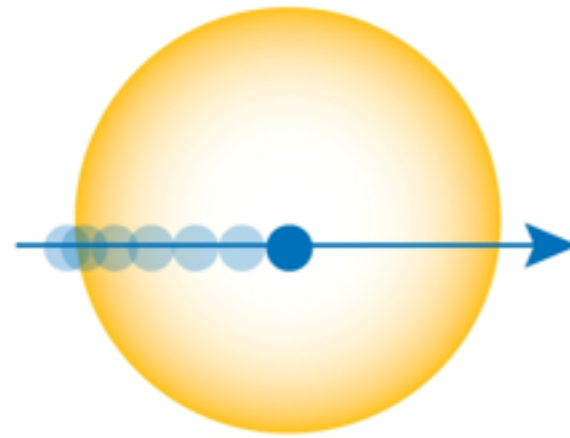


Orbit A Transit



2 hours, 5 minutes

Orbit B Transit



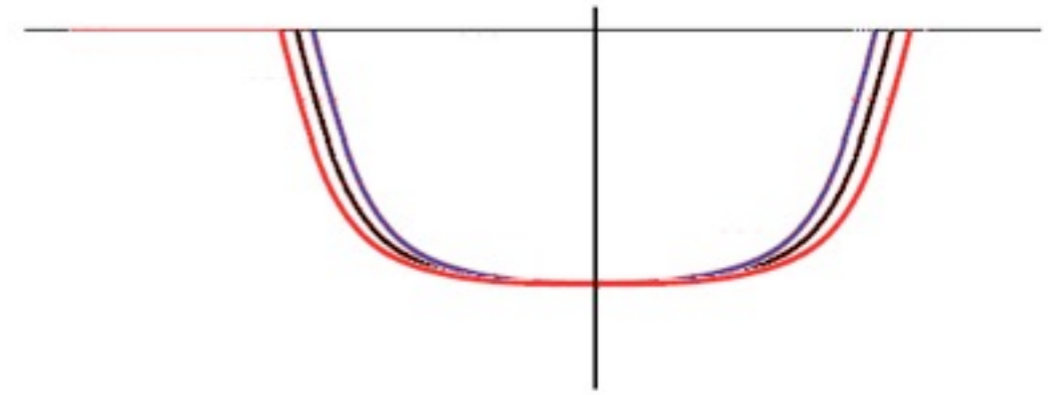
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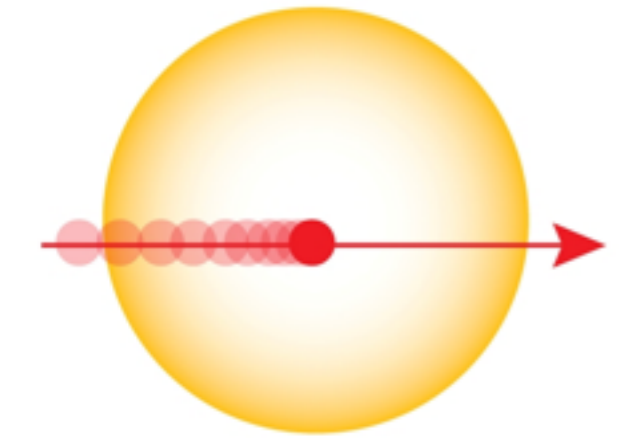
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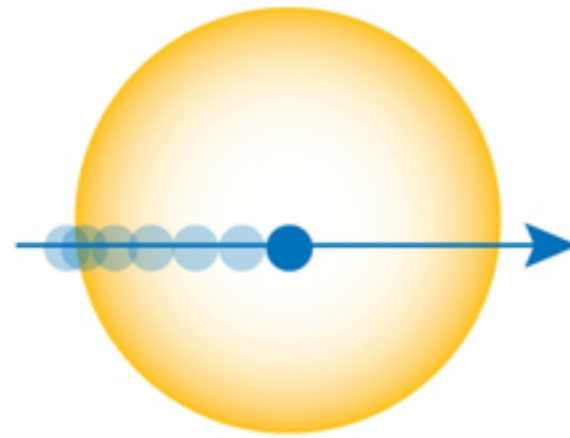


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Orbit B Transit



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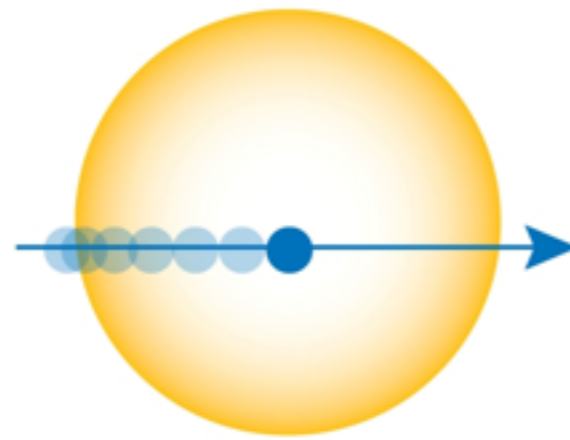
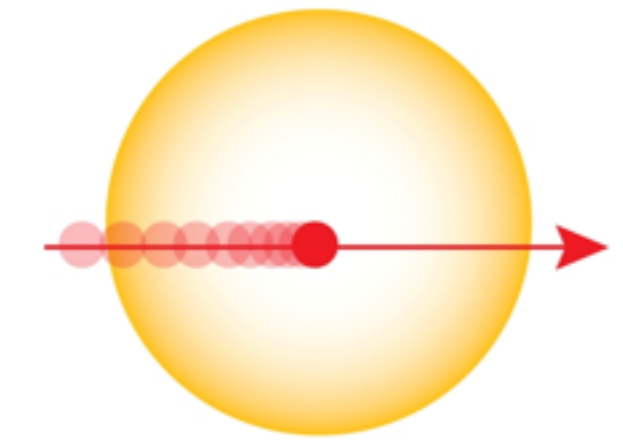
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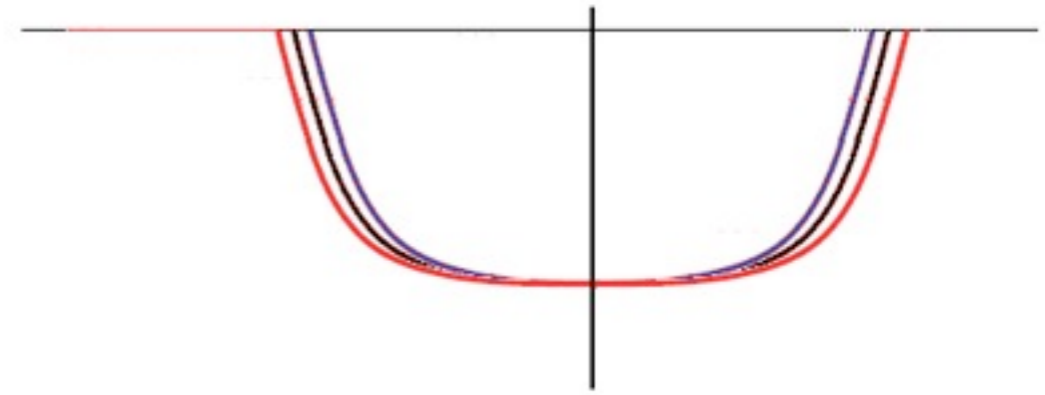
Orbit A Transit

Orbit B Transit



2 hours, 5 minutes

1 hour, 55 minutes



$$\delta_{\text{TDV-V}} = \tilde{T}_B \left(\frac{a_S M_S P_P}{a_P M_P P_S} \right) \left(\frac{\sqrt{1 - e_P^2}}{\sqrt{1 - e_S^2} (1 + e_P \sin \omega_P)} \right) \sqrt{\frac{\Phi_{\text{TDV-V}}}{2\pi}}$$

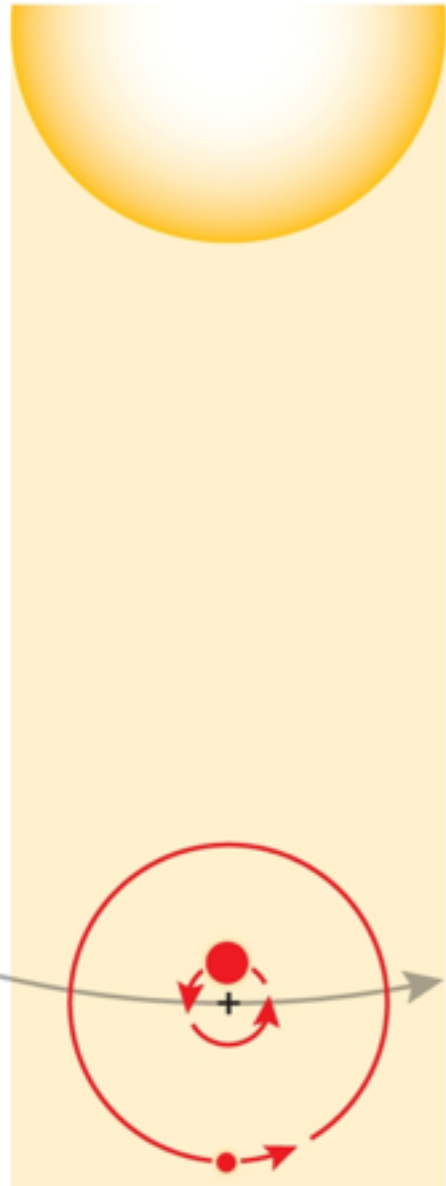
$$\text{TDV-V} \sim a_S M_S / P_S$$

$$\text{TDV-V} \sim a_S^{-1/2} M_S$$

Transit Duration Variation (TDV)

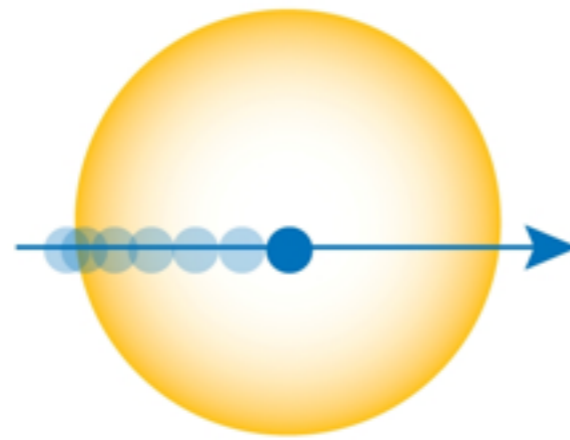
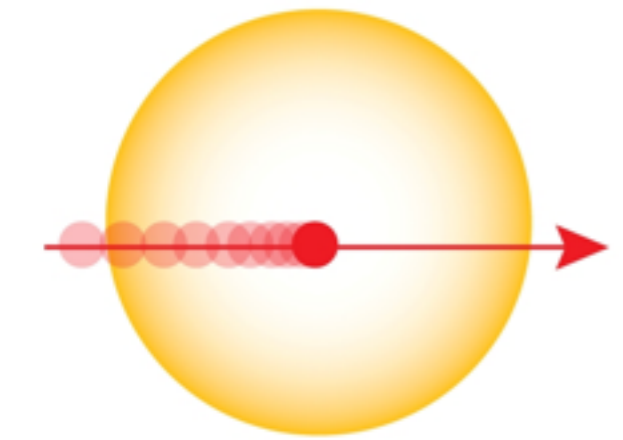
Orbit A Transit

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Orbit A Transit

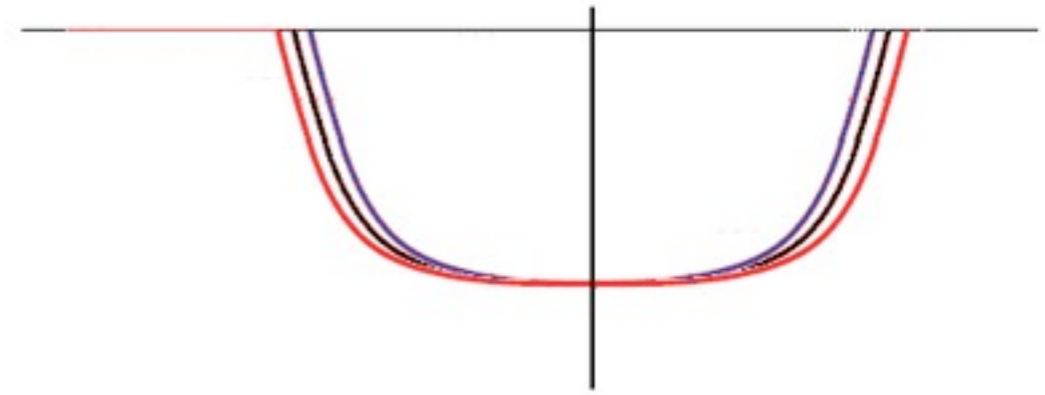
Orbit B Transit



2 hours, 5 minutes

1 hour, 55 minutes

TDV-V is analogous to radial velocity



$$\delta_{\text{TDV-V}} = \tilde{T}_B \left(\frac{a_S M_S P_P}{a_P M_P P_S} \right) \left(\frac{\sqrt{1 - e_P^2}}{\sqrt{1 - e_S^2} (1 + e_P \sin \omega_P)} \right) \sqrt{\frac{\Phi_{\text{TDV-V}}}{2\pi}}$$


$$\text{TDV-V} \sim a_S M_S / P_S$$

$$\text{TDV-V} \sim a_S^{-1/2} M_S$$

$$\text{TTV} \sim a_s M_s$$

$$\text{TDV-V} \sim a_s M_s / P_s$$

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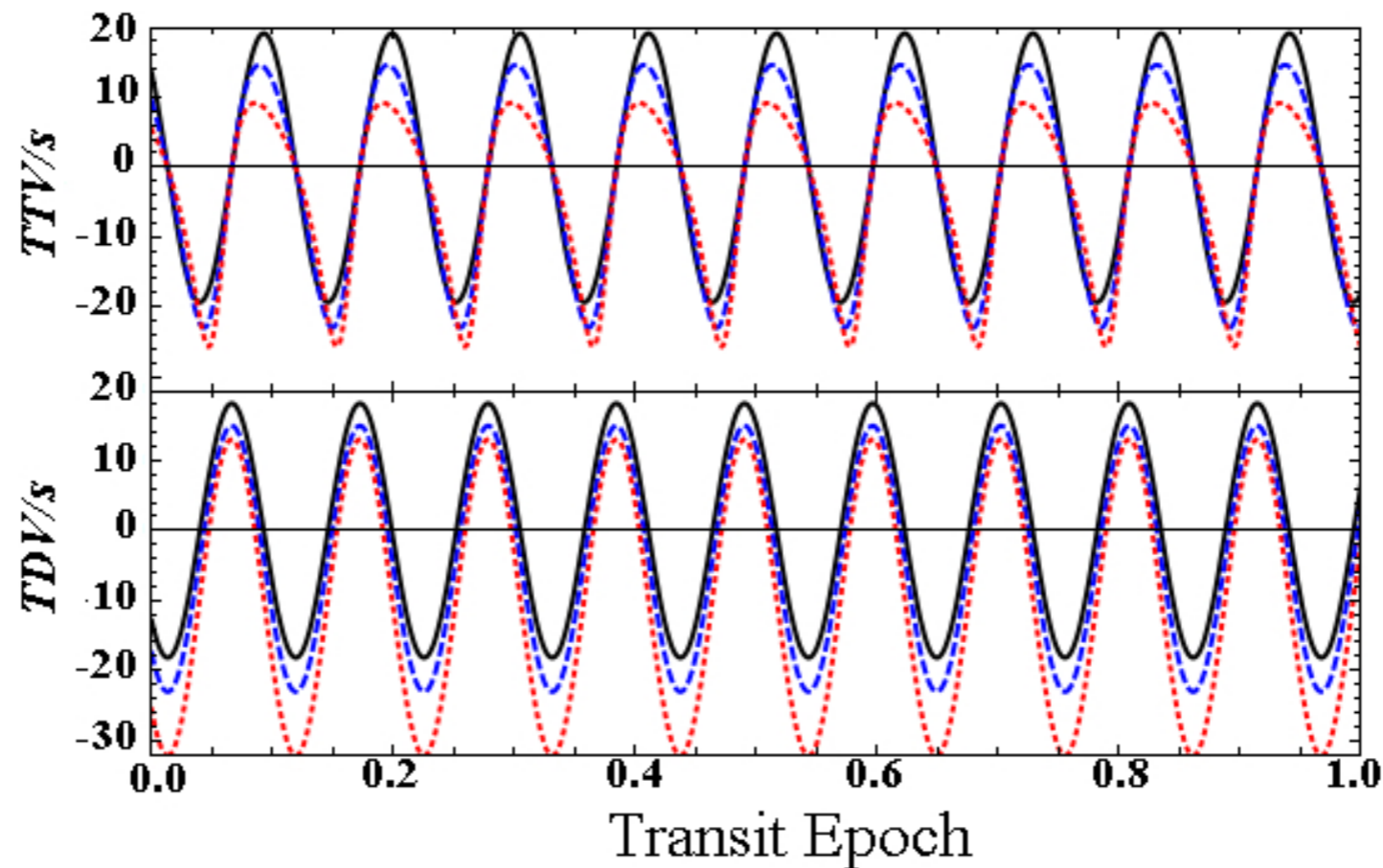

$$\eta = \frac{\delta_{\text{TDV}}}{\delta_{\text{TTV}}}$$

$$\lim_{e_s \rightarrow 0} \eta = \frac{\tilde{T}_B}{P_s}$$

TTV and TDV-V allow you determine P_s and thus M_s separately by measuring their amplitudes alone!

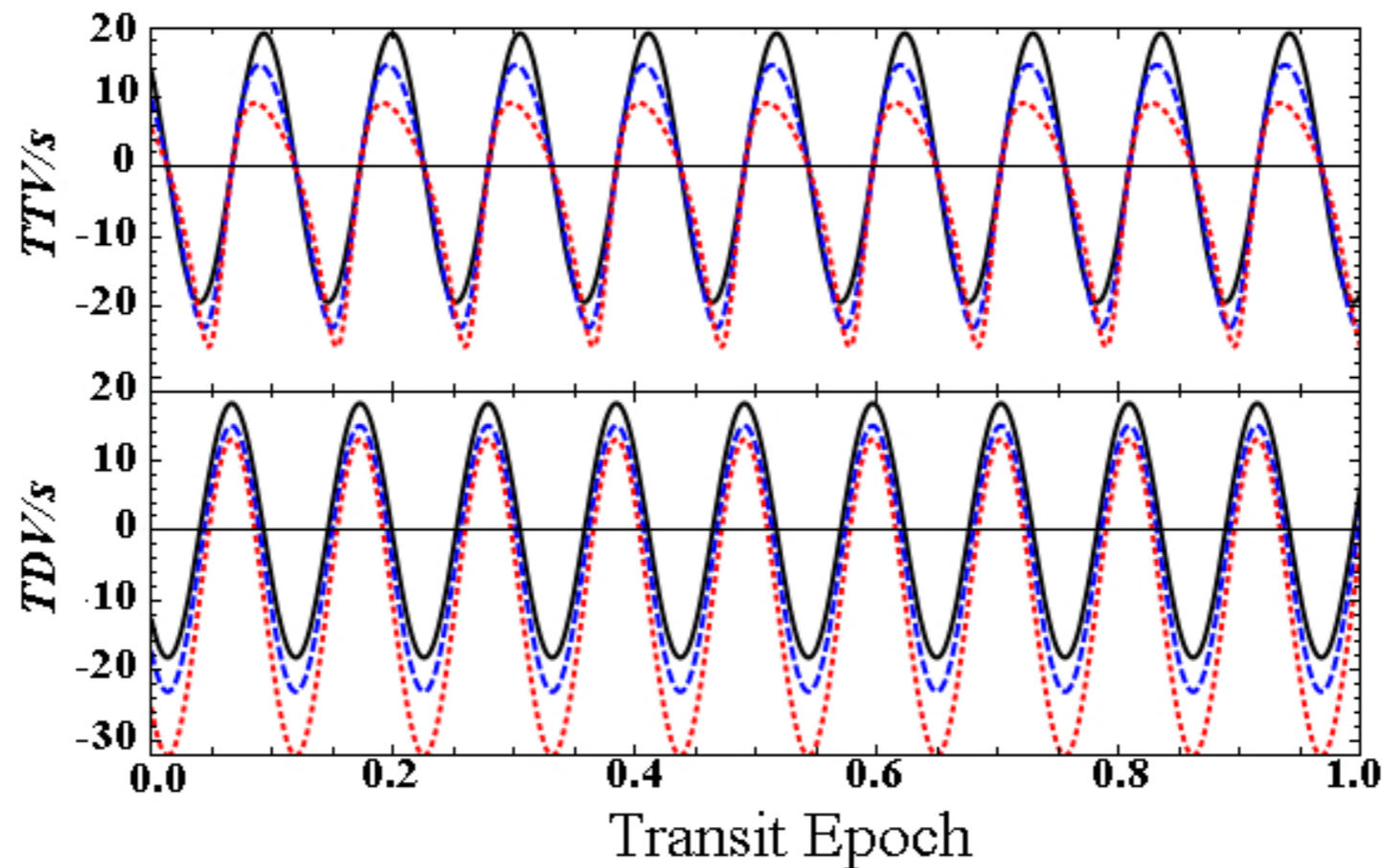
90° Phase Shift

- TTV leads TDV-V by 90 degrees in phase
- A unique signature we can look for



90° Phase Shift

- TTV leads TDV-V by 90 degrees in phase
- A unique signature we can look for



Solves problems 1 and 2

But wait, there's more...



Does TDV-TIP mess up η ?

$$\eta = \frac{\delta_{\text{TDV}}}{\delta_{\text{TIV}}}$$

$$\lim_{e_S \rightarrow 0} \eta = \frac{\tilde{T}_B}{P_S}$$

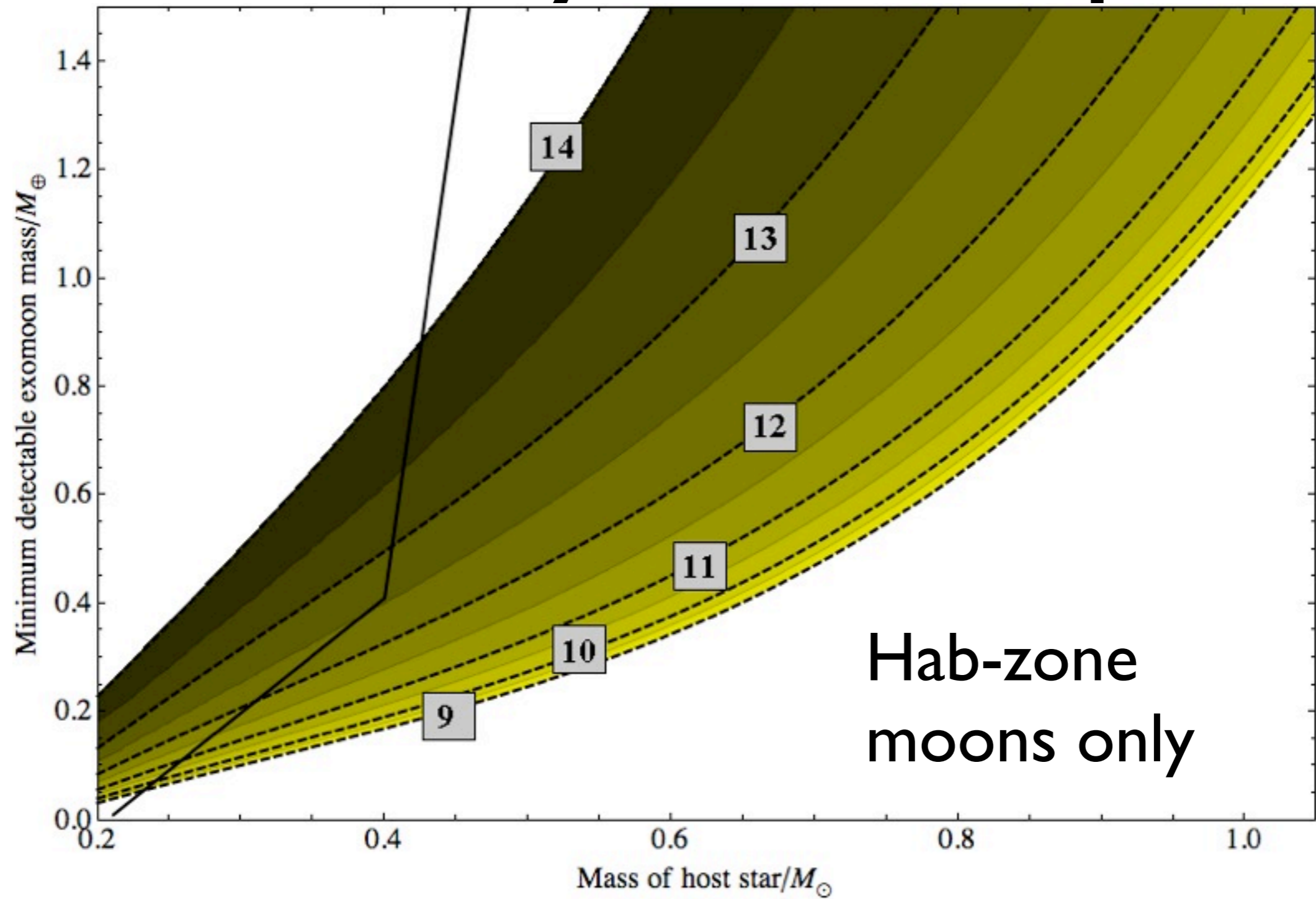
Does TDV-TIP mess up η ?

$$\eta = \frac{\delta_{\text{TDV}}}{\delta_{\text{TTV}}}$$

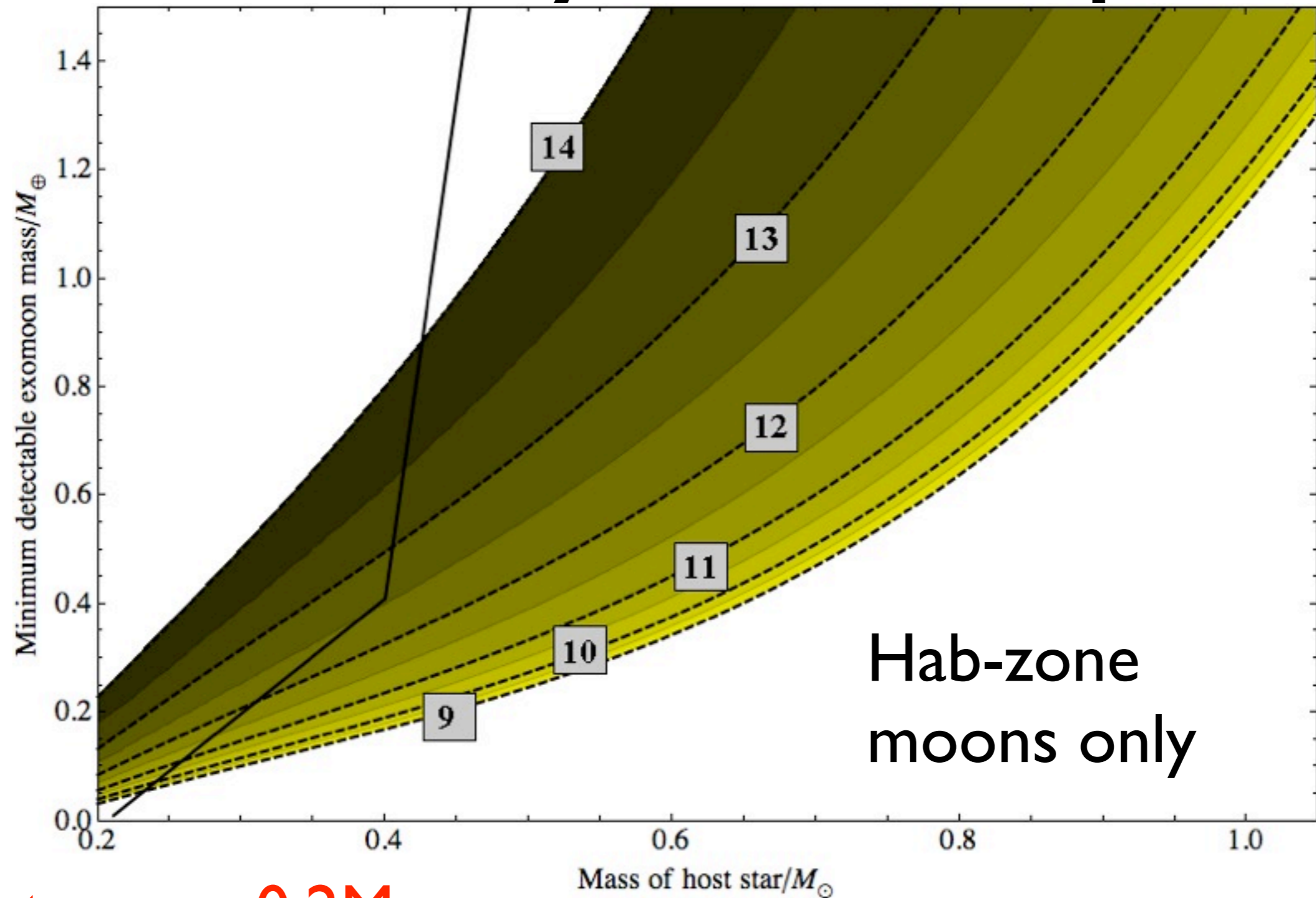
$$\lim_{e_S \rightarrow 0} \lim_{i_S \rightarrow \pi/2} \eta = \frac{\tilde{T}_B}{P_S} \pm \frac{\tilde{T}_B}{P_B} \left(\frac{b_{P,T}^2}{1 - b_{P,T}^2} \right)$$

⇒ We can distinguish between
prograde & retrograde moons!

Feasibility with Kepler



Feasibility with Kepler



- Best-case: $\sim 0.2M_{\oplus}$
- 25,000 stars bright enough to go for $1M_{\oplus}$

Observational Consequences

1. Dynamical effects (gives M_s)
 - (i) Transit timing variations (TTV)
 - (ii) Velocity induced transit duration variations (TDV-V)
 - (iii) Transit impact parameter induced transit duration variations (TDV-TIP)
2. Eclipse effects (gives R_s)

Observational Consequences

1. Dynamical effects (gives M_s)

(i) Transit timing variations (TTV)

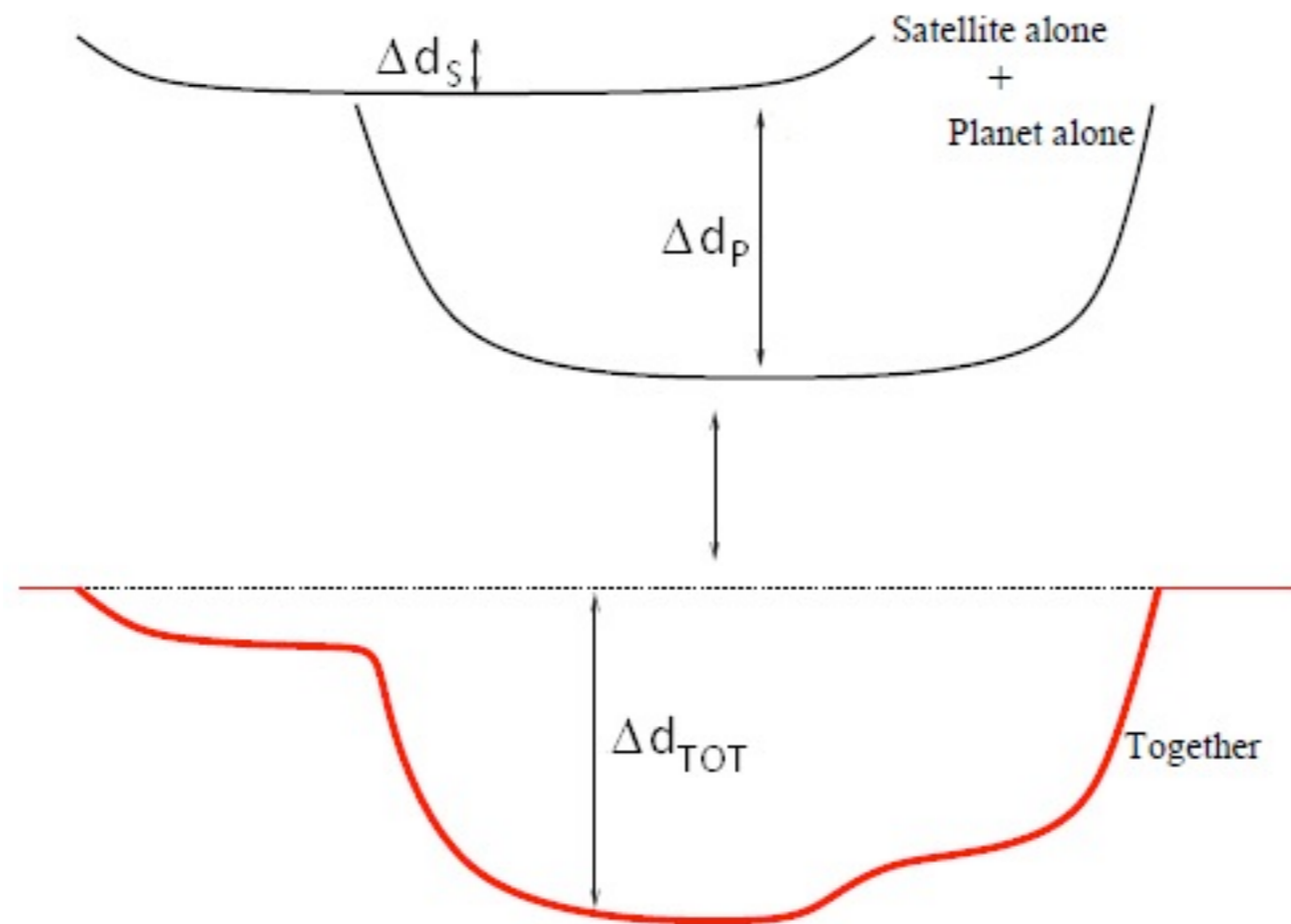
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2. Eclipse effects (gives R_s)

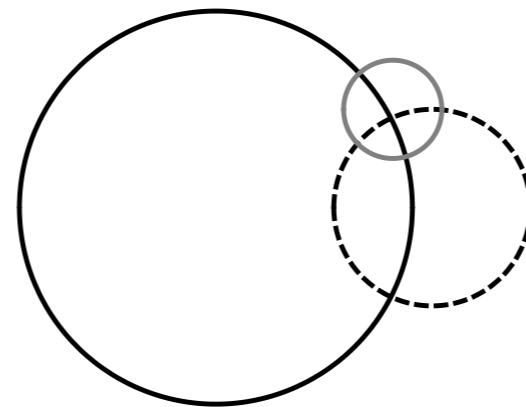
Auxiliary Transits

- At the simplest level, a moon can induce an auxiliary transit...



Mutual Events

- But if the moon, planet and star all overlap, we have a “mutual event”.
- Can no longer simply add two signals together.



Star-Planet System

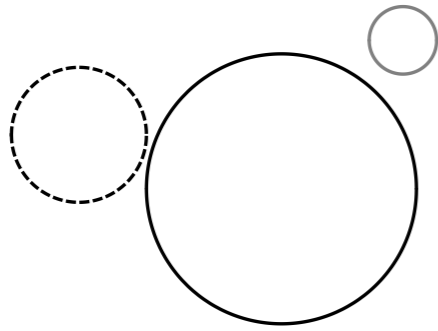
- Light curve is completely described by S_{P^*} , the sky-projected planet-star separation (in units of the stellar radius)
- This one parameter exists in 3 states, leading to $3^1 = 3$ cases:
 - (I) Out-of-transit: $1 + p \leq S_{P^*} < \infty$
 - (II) On-the-limb: $1 - p \leq S_{P^*} < 1 + p$
 - (III) In-transit: $0 \leq S_{P^*} < 1 - p$

Star-Planet-Moon System

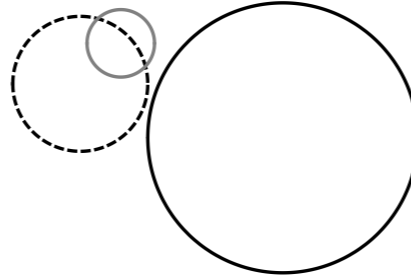
- Light curve now described by 3 parameters: S_{P^*} , S_{S^*} , S_{PS}
- Each parameter can still be in 3 states each
- Now $3^3 = 27$ cases

Case Number [\mathcal{E}]	S_P	S_S	S_{PS}	Physical?
1	$S_{P^*} \geq 1 + p$	$S_{S^*} \geq 1 + s$	$S_{PS} \geq p + s$	✓
2	$S_{P^*} \geq 1 + p$	$S_{S^*} \geq 1 + s$	$p - s < S_{PS} < p + s$	✓
3	$S_{P^*} \geq 1 + p$	$S_{S^*} \geq 1 + s$	$S_{PS} \leq p - s$	✓
4	$S_{P^*} \geq 1 + p$	$1 - s < S_{S^*} < 1 + s$	$S_{PS} \geq p + s$	✓
5	$S_{P^*} \geq 1 + p$	$1 - s < S_{S^*} < 1 + s$	$p - s < S_{PS} < p + s$	✓
6	$S_{P^*} \geq 1 + p$	$1 - s < S_{S^*} < 1 + s$	$S_{PS} \leq p - s$	×
7	$S_{P^*} \geq 1 + p$	$S_{S^*} \leq 1 - s$	$S_{PS} \geq p + s$	✓
8	$S_{P^*} \geq 1 + p$	$S_{S^*} \leq 1 - s$	$p - s < S_{PS} < p + s$	×
9	$S_{P^*} \geq 1 + p$	$S_{S^*} \leq 1 - s$	$S_{PS} \leq p - s$	×
10	$1 - p < S_{P^*} < 1 + p$	$S_{S^*} \geq 1 + s$	$S_{PS} \geq p + s$	✓
11	$1 - p < S_{P^*} < 1 + p$	$S_{S^*} \geq 1 + s$	$p - s < S_{PS} < p + s$	✓
12	$1 - p < S_{P^*} < 1 + p$	$S_{S^*} \geq 1 + s$	$S_{PS} \leq p - s$	✓
13	$1 - p < S_{P^*} < 1 + p$	$1 - s < S_{S^*} < 1 + s$	$S_{PS} \geq p + s$	✓
14**	$1 - p < S_{P^*} < 1 + p$	$1 - s < S_{S^*} < 1 + s$	$p - s < S_{PS} < p + s$	✓
15	$1 - p < S_{P^*} < 1 + p$	$1 - s < S_{S^*} < 1 + s$	$S_{PS} \leq p - s$	✓
16	$1 - p < S_{P^*} < 1 + p$	$S_{S^*} \leq 1 - s$	$S_{PS} \geq p + s$	✓
17*	$1 - p < S_{P^*} < 1 + p$	$S_{S^*} \leq 1 - s$	$p - s < S_{PS} < p + s$	✓
18	$1 - p < S_{P^*} < 1 + p$	$S_{S^*} \leq 1 - s$	$S_{PS} \leq p - s$	✓
19	$S_{P^*} \leq 1 - p$	$S_{S^*} \geq 1 + s$	$S_{PS} \geq p + s$	✓
20	$S_{P^*} \leq 1 - p$	$S_{S^*} \geq 1 + s$	$p - s < S_{PS} < p + s$	×
21	$S_{P^*} \leq 1 - p$	$S_{S^*} \geq 1 + s$	$S_{PS} \leq p - s$	×
22	$S_{P^*} \leq 1 - p$	$1 - s < S_{S^*} < 1 + s$	$S_{PS} \geq p + s$	✓
23*	$S_{P^*} \leq 1 - p$	$1 - s < S_{S^*} < 1 + s$	$p - s < S_{PS} < p + s$	✓
24	$S_{P^*} \leq 1 - p$	$1 - s < S_{S^*} < 1 + s$	$S_{PS} \leq p - s$	×
25	$S_{P^*} \leq 1 - p$	$S_{S^*} \leq 1 - s$	$S_{PS} \geq p + s$	✓
26*	$S_{P^*} \leq 1 - p$	$S_{S^*} \leq 1 - s$	$p - s < S_{PS} < p + s$	✓
27	$S_{P^*} \leq 1 - p$	$S_{S^*} \leq 1 - s$	$S_{PS} \leq p - s$	✓

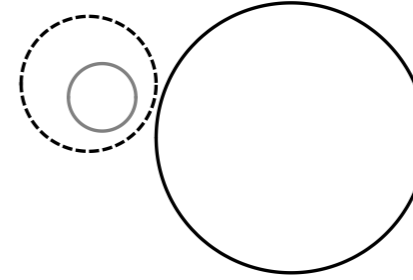
CASE 1



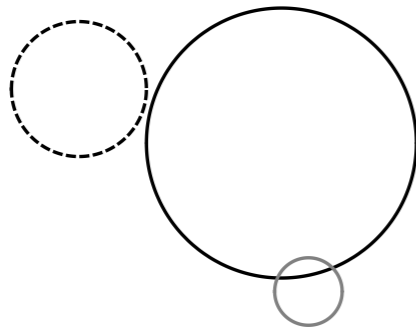
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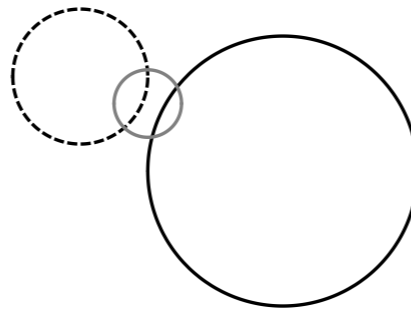
CASE 3



CASE 4



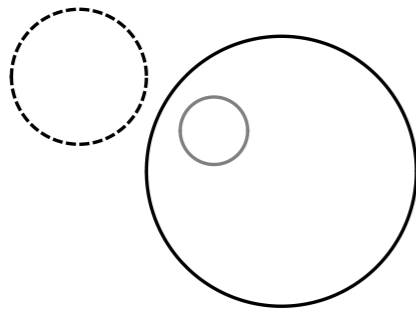
CASE 5



CASE 6

UNPHYSICAL

CASE 7



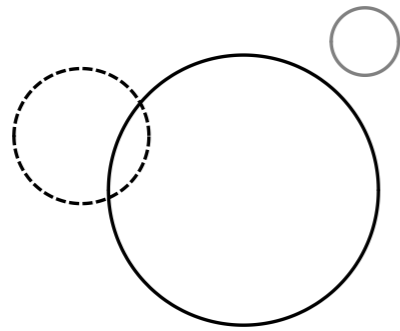
CASE 8

UNPHYSICAL

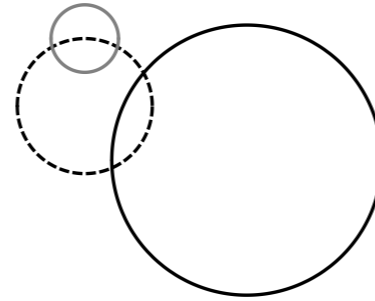
CASE 9

UNPHYSICAL

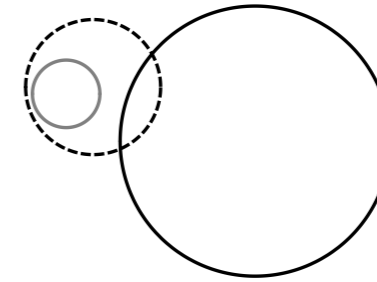
CASE 10



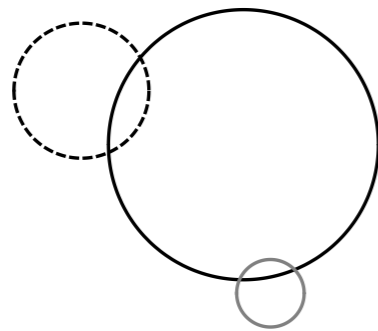
CASE 11



CASE 12



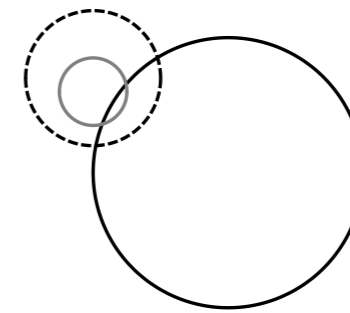
CASE 13



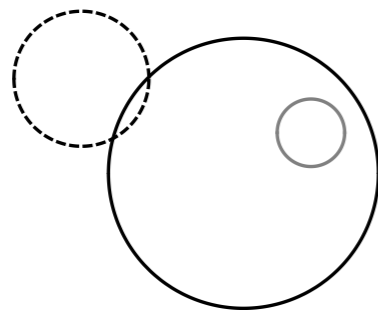
CASE 14

MULTIPLE SUB-CASES

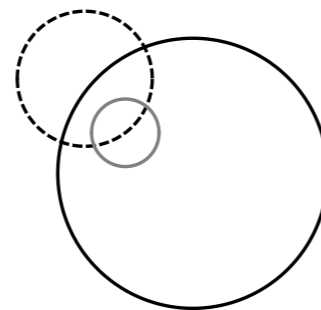
CASE 15



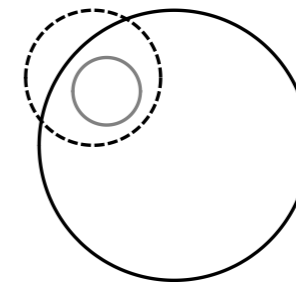
CASE 16



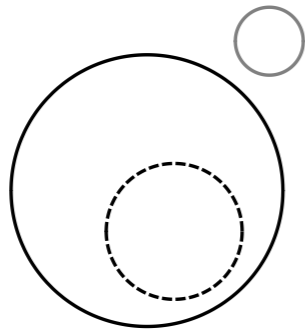
CASE 17



CASE 18



CASE 19



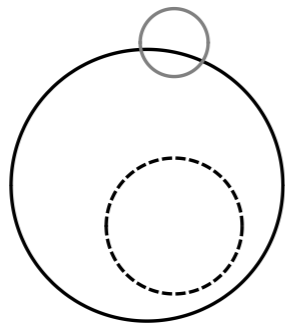
CASE 20

UNPHYSICAL

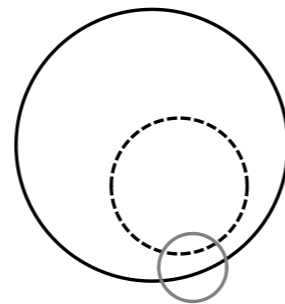
CASE 21

UNPHYSICAL

CASE 22



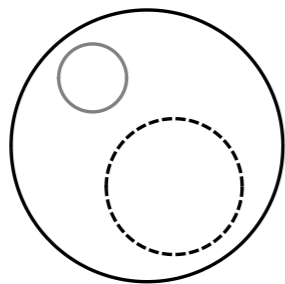
CASE 23



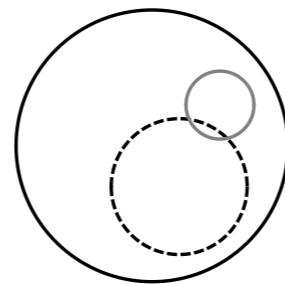
CASE 24

UNPHYSICAL

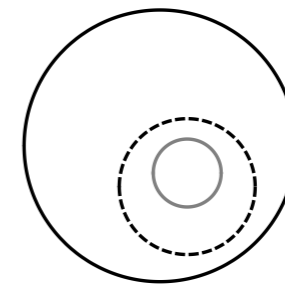
CASE 25



CASE 26



CASE 27



Case 14

- Case 14 has all three discs on the limb
- We need to calculate the area of overlap
- Could be done numerically, but this would be very slow and inefficient
- Is there an analytic solution?

Some in-depth research
is done...

Google

Google Search

I'm Feeling Lucky

Some in-depth research is done...

The Google logo is displayed in its characteristic multi-colored font: blue 'G', red 'o', yellow 'o', blue 'g', green 'l', and red 'e'.

area of common overlap of three circles

Google Search

I'm Feeling Lucky

Some in-depth research is done...

The Google logo is displayed in its characteristic multi-colored font: blue 'G', red 'o', yellow 'o', blue 'g', green 'l', and red 'e'.

area of common overlap of three circles

Google Search

I'm Feeling Lucky





Australian Government
Department of Defence
Defence Science and
Technology Organisation

Area of Common Overlap of Three Circles

M.P. Fewell

Maritime Operations Division
Defence Science and Technology Organisation

DSTO-TN-0722

ABSTRACT

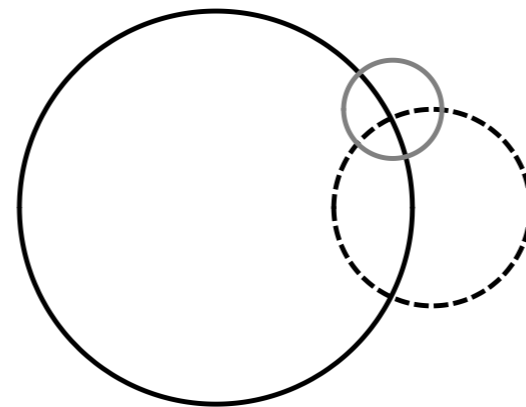
This Note presents the solution to an apparently hitherto unsolved geometrical problem: the derivation of a closed-form algebraic expression of the area of common overlap of three circles, such as can occur in a three-circle Venn diagram. The results presented here have general significance in the corpus of mensuration formulae, and could be of specific use in any quantitative application of the three-circle Venn diagram such as, for example, in search and screening problems.

RELEASE LIMITATION

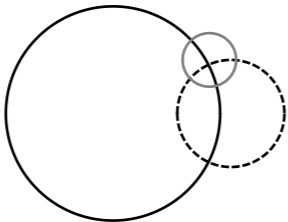
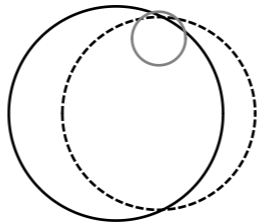
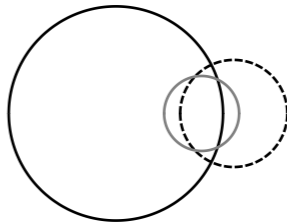
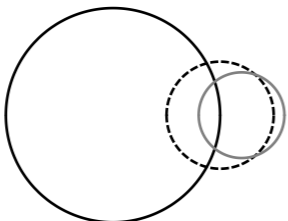
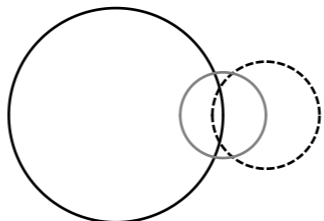
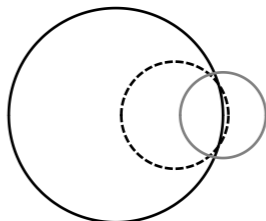
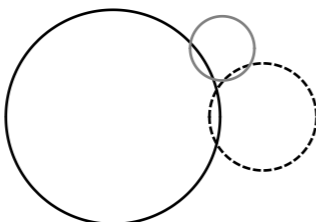
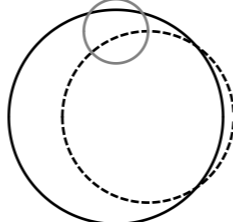
Approved for public release

Fewell (2006) Solution

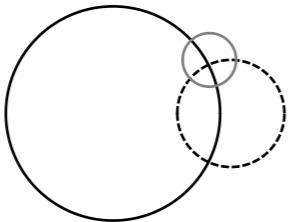
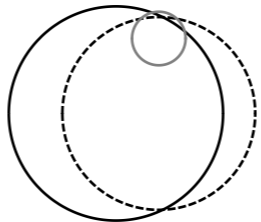
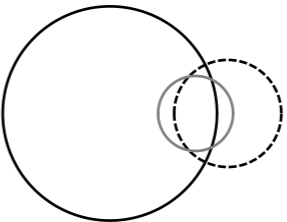
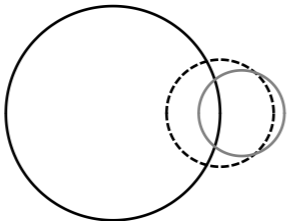
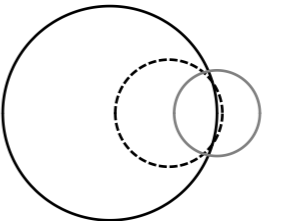
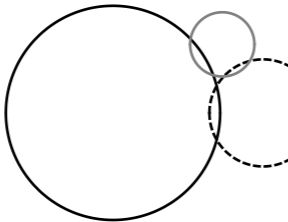
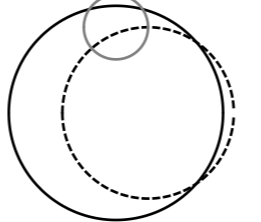
- In 2006, Michael Fewell, presented the first analytic solution to this problem.
- The Fewell solution solves the most critical problem in modeling exomoon signals.



Additional cases solved too

<p>CASE 14.1 <i>a</i></p> 	<p>CASE 14.1 <i>b</i></p> 	<p>CASE 14.2 <i>a</i></p> 
<p>CASE 14.2 <i>b</i></p> 	<p>CASE 14.3 <i>a</i></p> 	<p>CASE 14.3 <i>b</i></p> 
<p>CASE 14.7 <i>a</i></p> 	<p>CASE 14.7 <i>b</i></p> 	

Additional cases solved too

<p>CASE 14.1 <i>a</i></p> 	<p>CASE 14.1 <i>b</i></p> 	<p>CASE 14.2 <i>a</i></p> 
<p>CASE 14.2 <i>b</i></p> 	<p>CASE 14.2</p> <div data-bbox="1059 947 1739 1297" style="border: 2px solid black; padding: 10px; text-align: center;"><p>Also see Pal (2012)</p></div>	<p>CASE 14.3 <i>b</i></p> 
<p>CASE 14.7 <i>a</i></p> 	<p>CASE 14.7 <i>b</i></p> 	

Observational Consequences

1. Dynamical effects (gives M_s)
 - (i) Transit timing variations (TTV)
 - (ii) Velocity induced transit duration variations (TDV-V)
 - (iii) Transit impact parameter induced transit duration variations (TDV-TIP)
2. Eclipse effects (gives R_s)
 - (i) Auxiliary transits
 - (ii) Mutual events

**Moon Detections Allow
Us to Measure M_* & R_***

Moon Detections Allow Us to Measure M_* & R_*

How to Weigh a Star Using a Moon

David M. Kipping^{1,2*}

¹*Department of Physics and Astronomy, University College London, Gower St., London WC1E 6BT*

²*Harvard-Smithsonian Center for Astrophysics, 60, Garden St., Cambridge, MA 02138, USA*

Accepted 2010 September 21. Received 2010 September 17; in original form 2010 August 24

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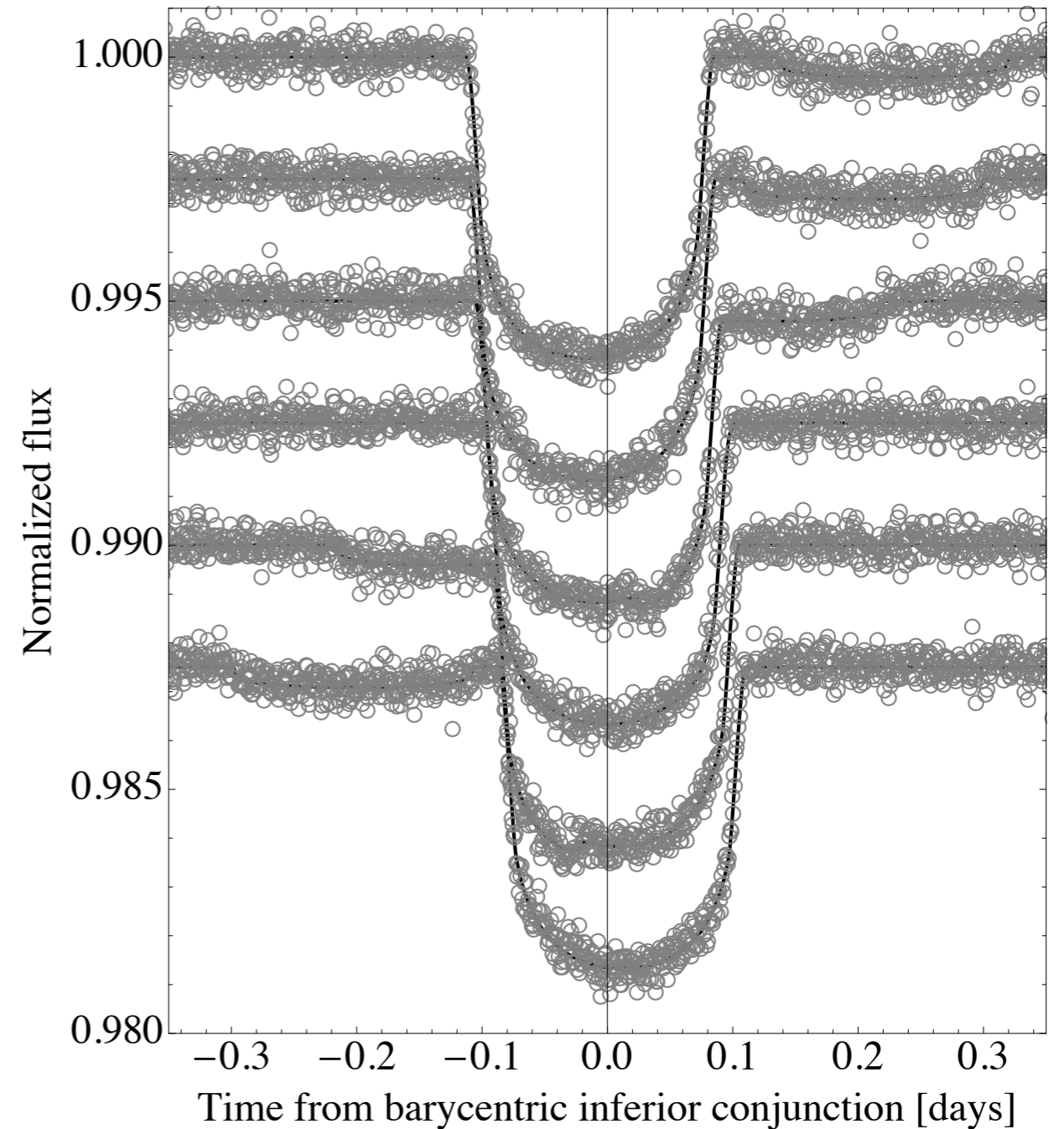
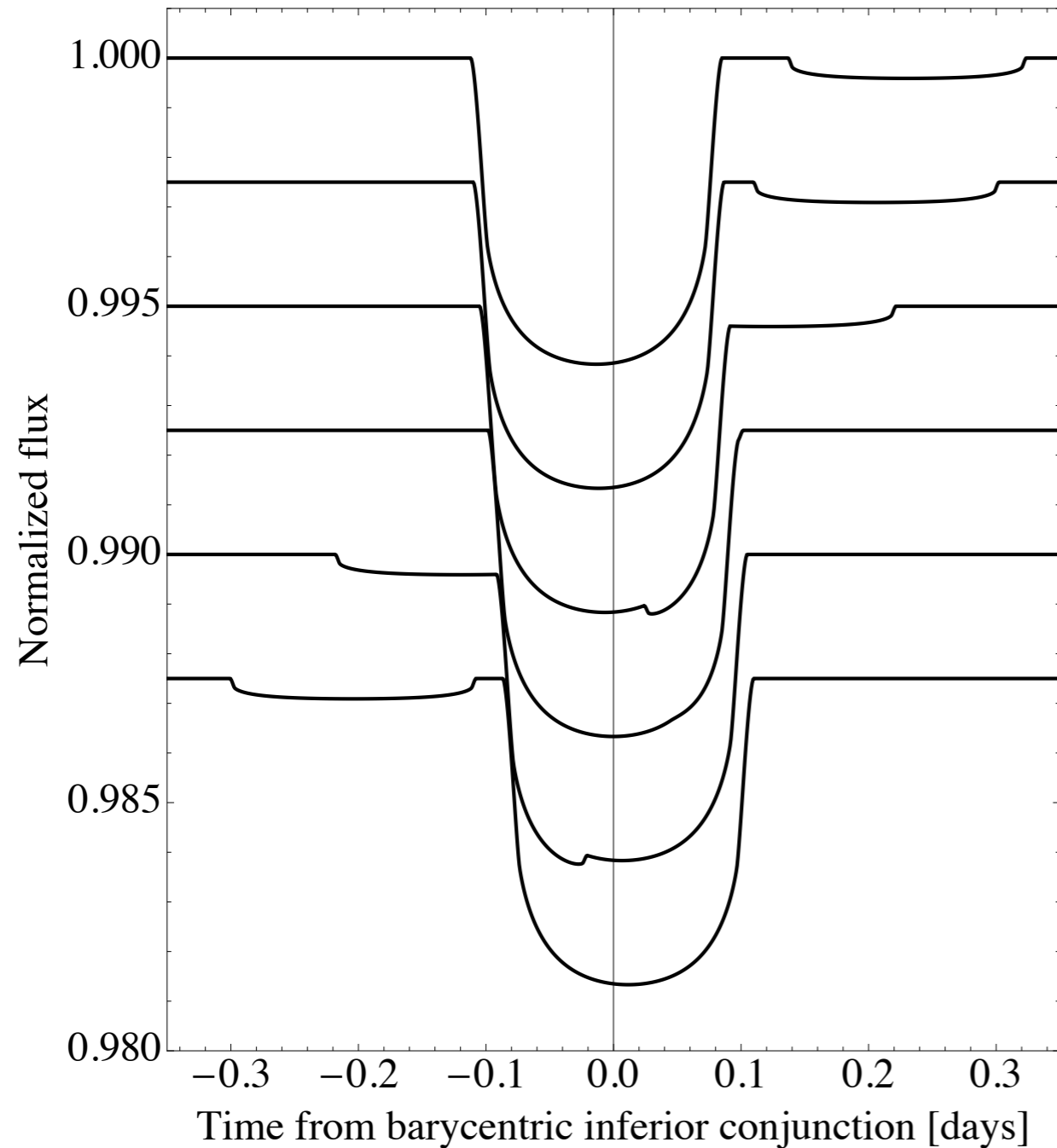
¹*Department of Physics and Astronomy, University College London, Gower St., London WC1E 6BT*

²*Harvard-Smithsonian Center for Astrophysics, 60, Garden St., Cambridge, MA 02138, USA*

Accepted 2010 September 21. Received 2010 September 17; in original form 2010 August 24

$$M_* = \left[\frac{(a_B/R_*)^6}{(a_S/R_*)^9} \right] \left[\frac{P_S^4}{P_B^5} \right] \left[\frac{(1 - e_B^2)^{3/2} K_*^3}{2\pi G \sin^3 i_B} \right]$$
$$\times \left[\frac{(a_B/R_*)^3 P_S^2 - (a_S/R_*)^3 (1 + \mathcal{M}_{SP})^3 P_B^2}{(1 + \mathcal{M}_{SP})^9} \right]$$
$$R_* = \frac{(a_B/R_*)^2 \sqrt{1 - e_B^2} K_* P_S^2}{2\pi \sin i_B (a_S/R_*)^3 (1 + \mathcal{M}_{SP})^3 P_B}$$

Neptune in hab-zone of M2 dwarf with **far-out retrograde** Earth-mass and radius moon



~10% uncertainties on M_*

~5% uncertainties on R_*

Physical params.

M_* [M_\odot]	0.400	$0.399^{+0.061}_{-0.064}$
R_* [R_\odot]	0.500	$0.504^{+0.025}_{-0.029}$
M_P [M_J]	0.0540	$0.0537^{+0.0055}_{-0.0061}$
R_P [M_J]	0.346	$0.350^{+0.018}_{-0.020}$
M_S [M_\oplus]	1.00	$1.05^{+0.13}_{-0.12}$
R_S [R_\oplus]	1.000	$1.011^{+0.059}_{-0.064}$
ρ_S [g cm^{-3}]	5.50	$5.62^{+1.03}_{-0.85}$

~10% uncertainties on M_*

~5% uncertainties on R_*

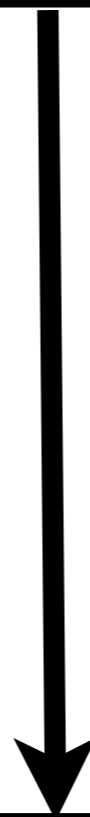
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ρ_S [g cm^{-3}]	5.50	$5.62^{+1.03}_{-0.85}$

Moons directly yield density of the planet, useful for vetting.

III. Modeling

**Observational
Consequences**



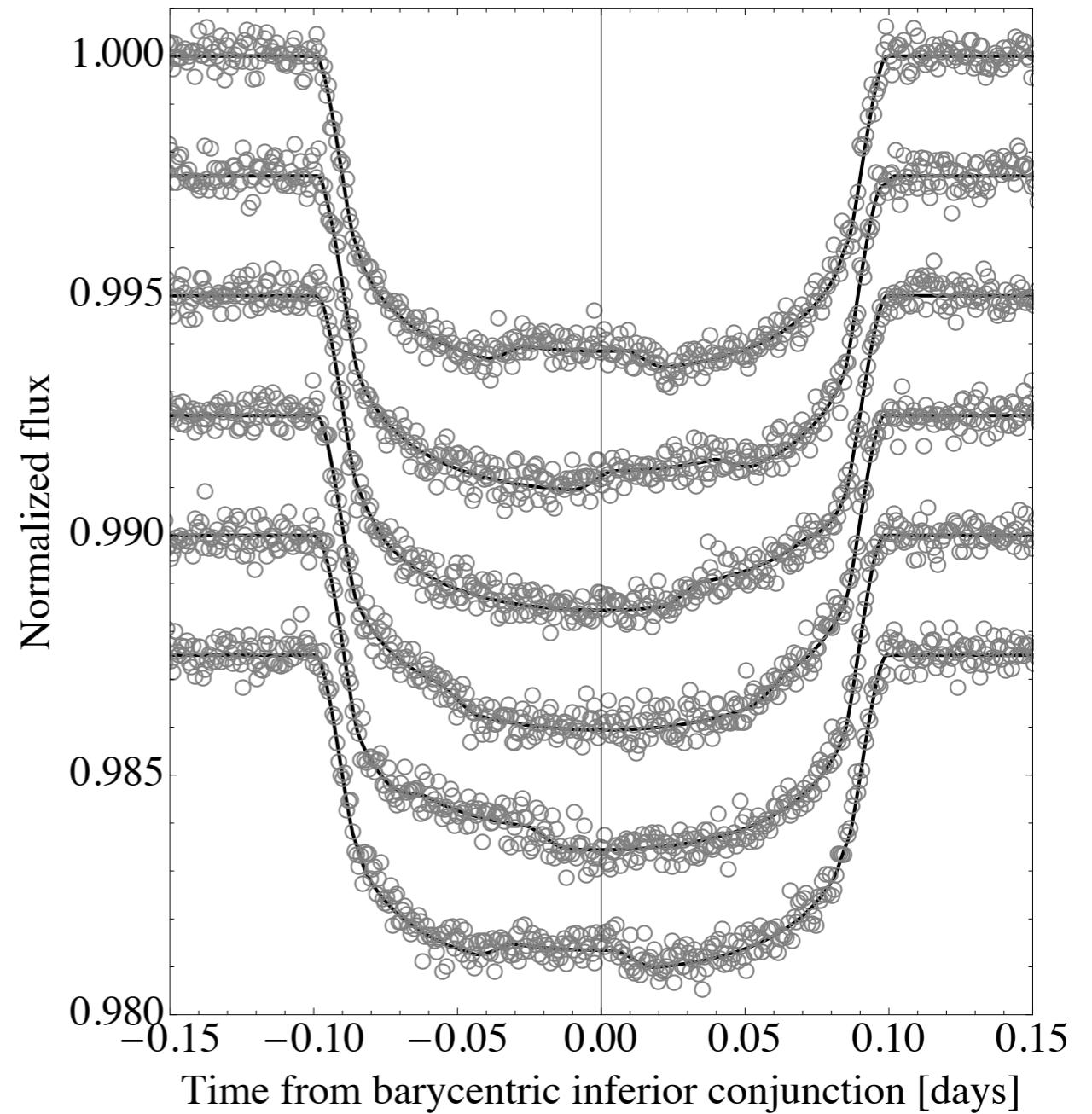
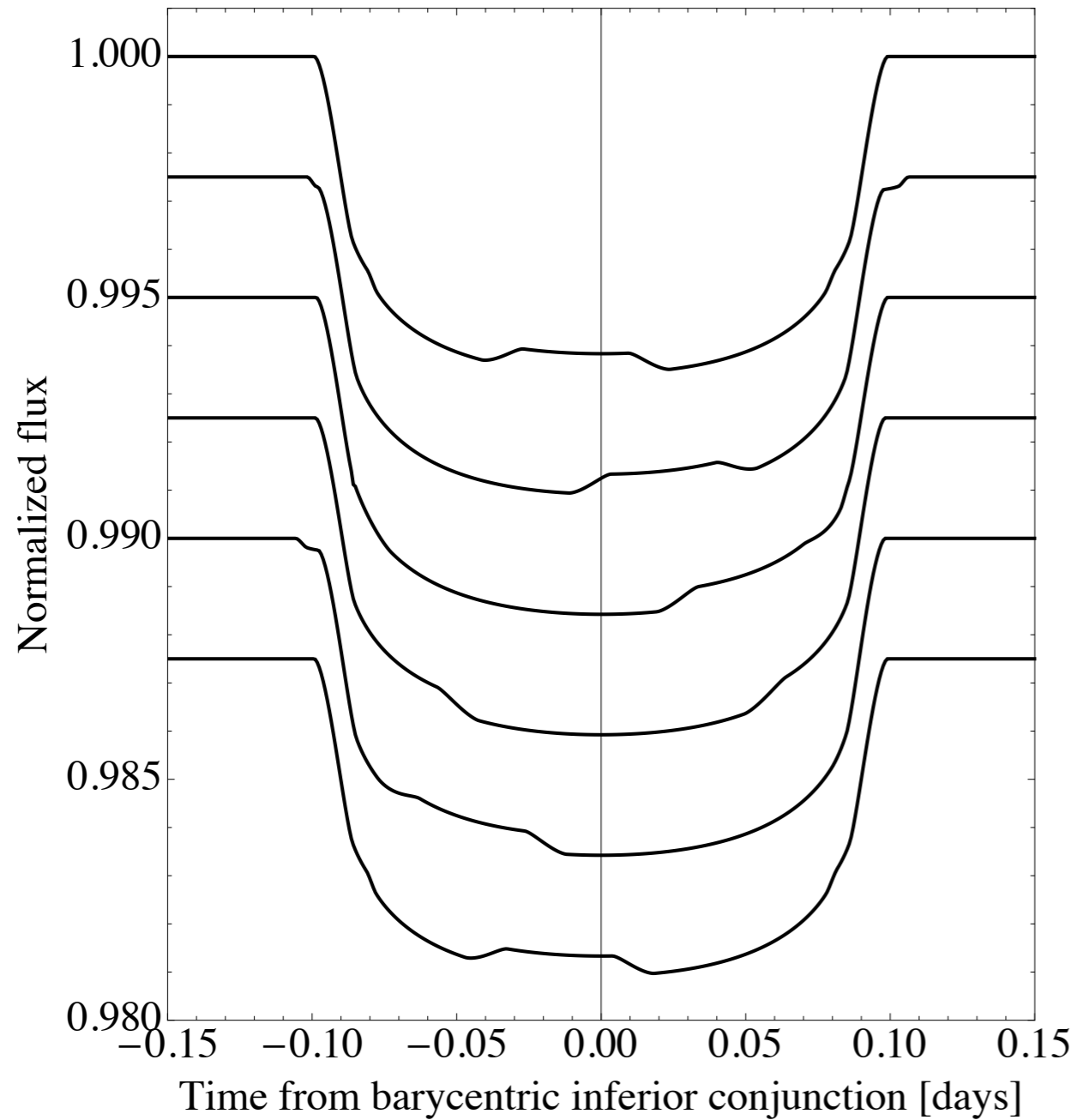
**Modeling
Algorithm**

Modeling Algorithms

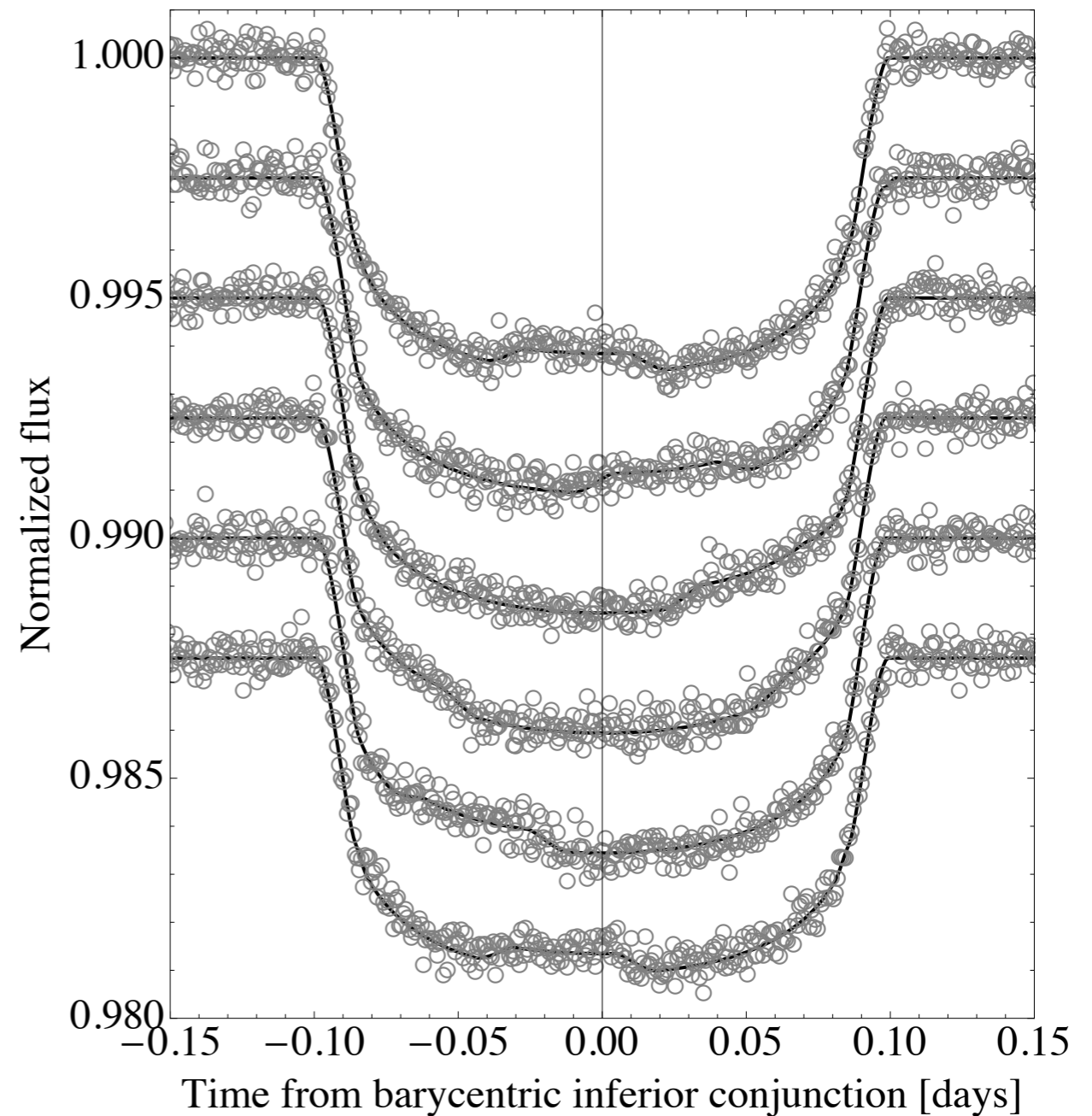
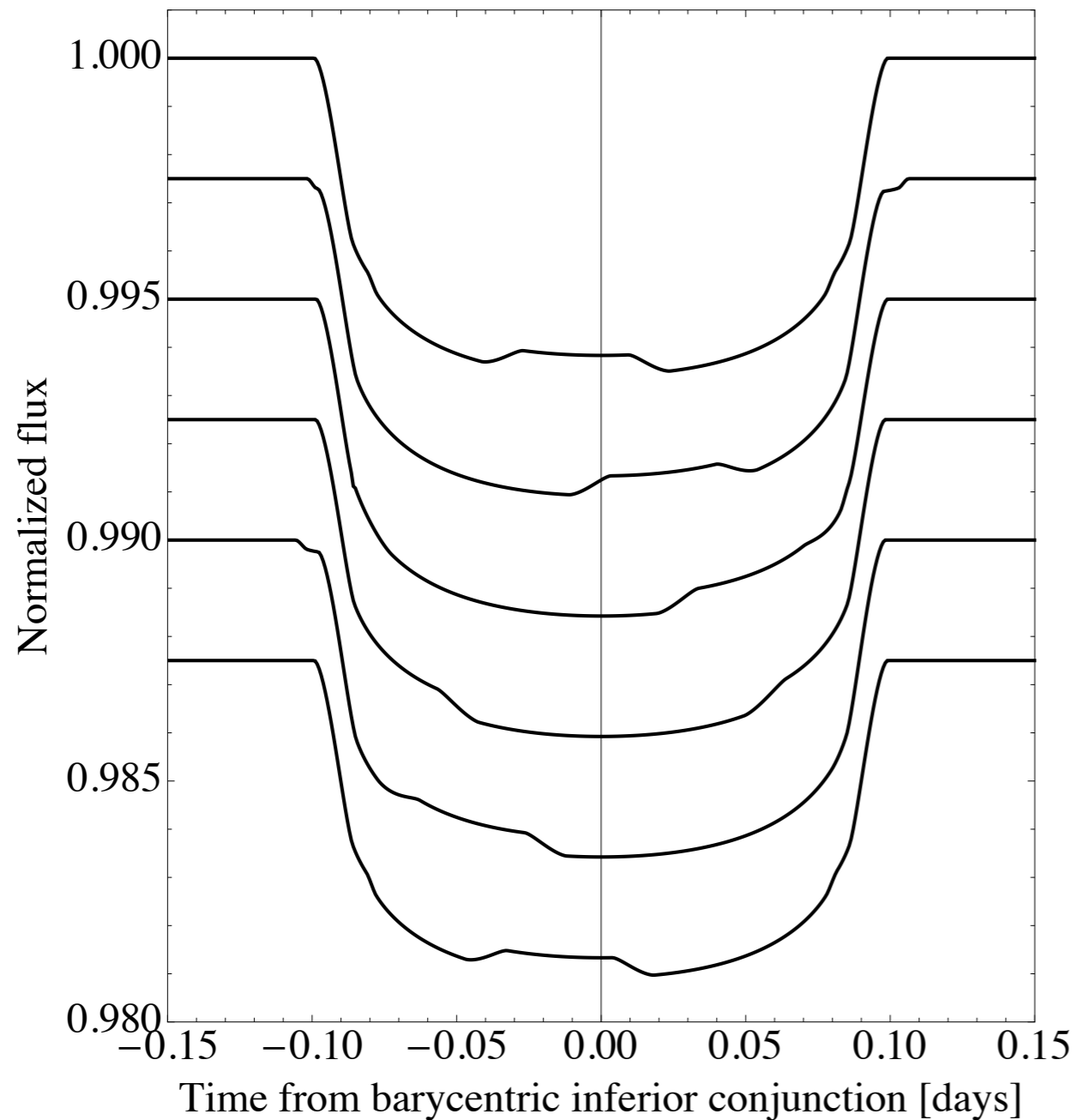
- Kipping (2012); analytic, dynamic algorithm called *LUNA* [analytic solution is public]
- Tusnksi & Valio (2011); circular, coplanar moons only [availability unknown]
- Pal (2012); not specific for moons, simulates mutual events [code is public]
- Sato & Asada (2009); circular, coplanar, no LD [availability unknown]
- Simon, Szabó & Szatmáry (2009); sparse details
- Sartoretti & Schneider (1999); sparse details

Neptune in hab-zone of M2 dwarf with close-in
prograde Earth-mass and radius moon

Neptune in hab-zone of M2 dwarf with close-in prograde Earth-mass and radius moon

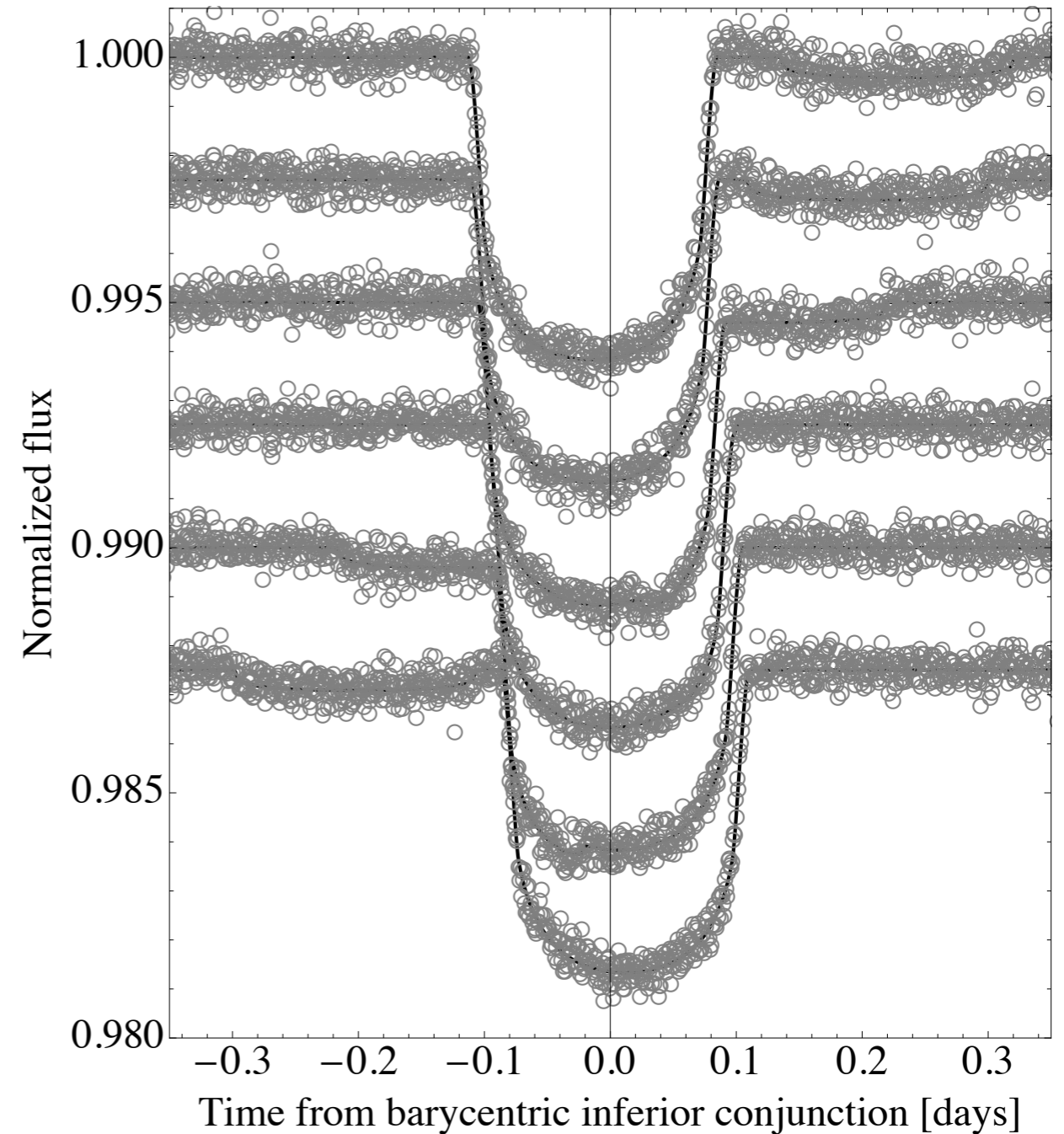
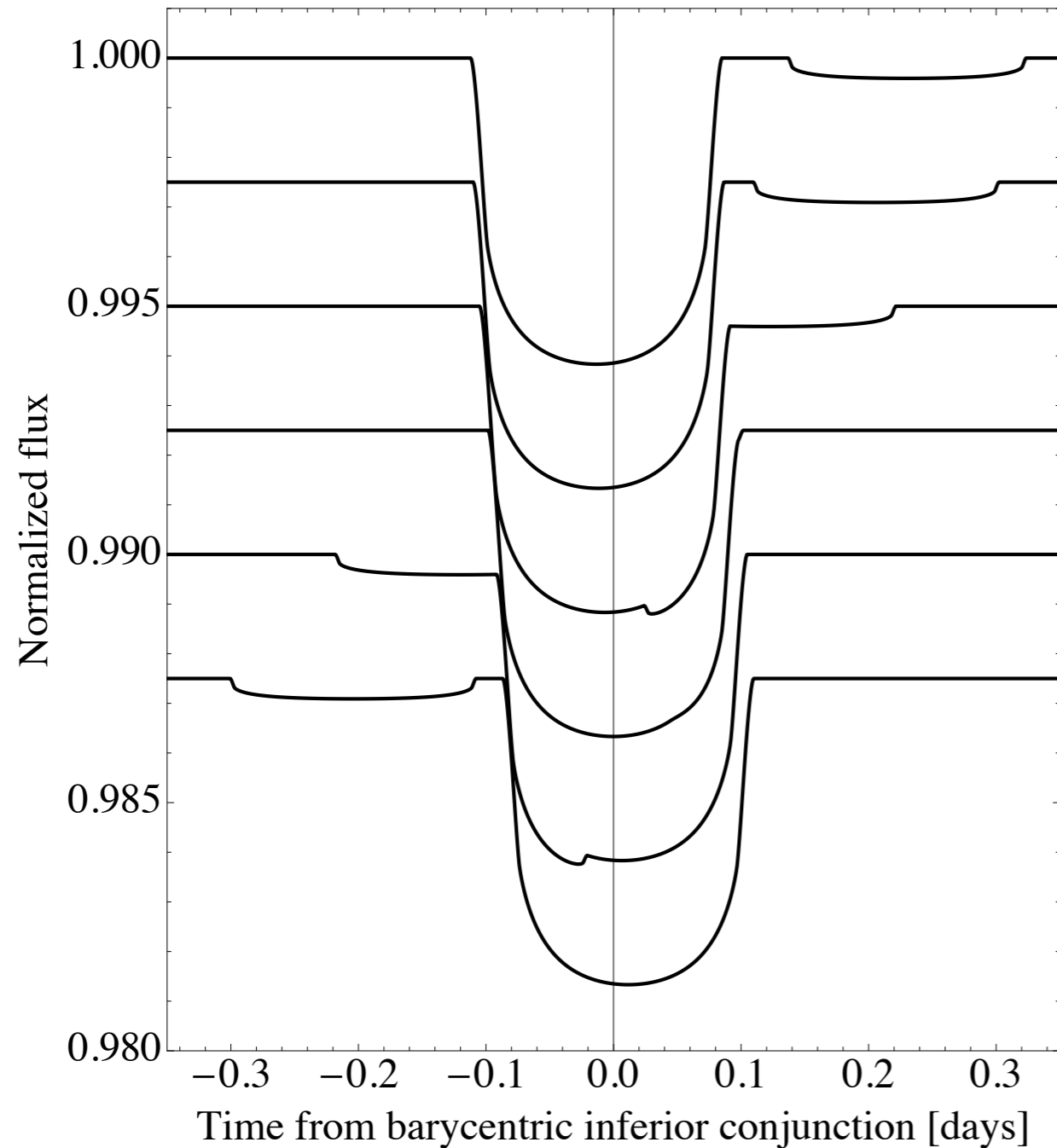


Neptune in hab-zone of M2 dwarf with close-in prograde Earth-mass and radius moon

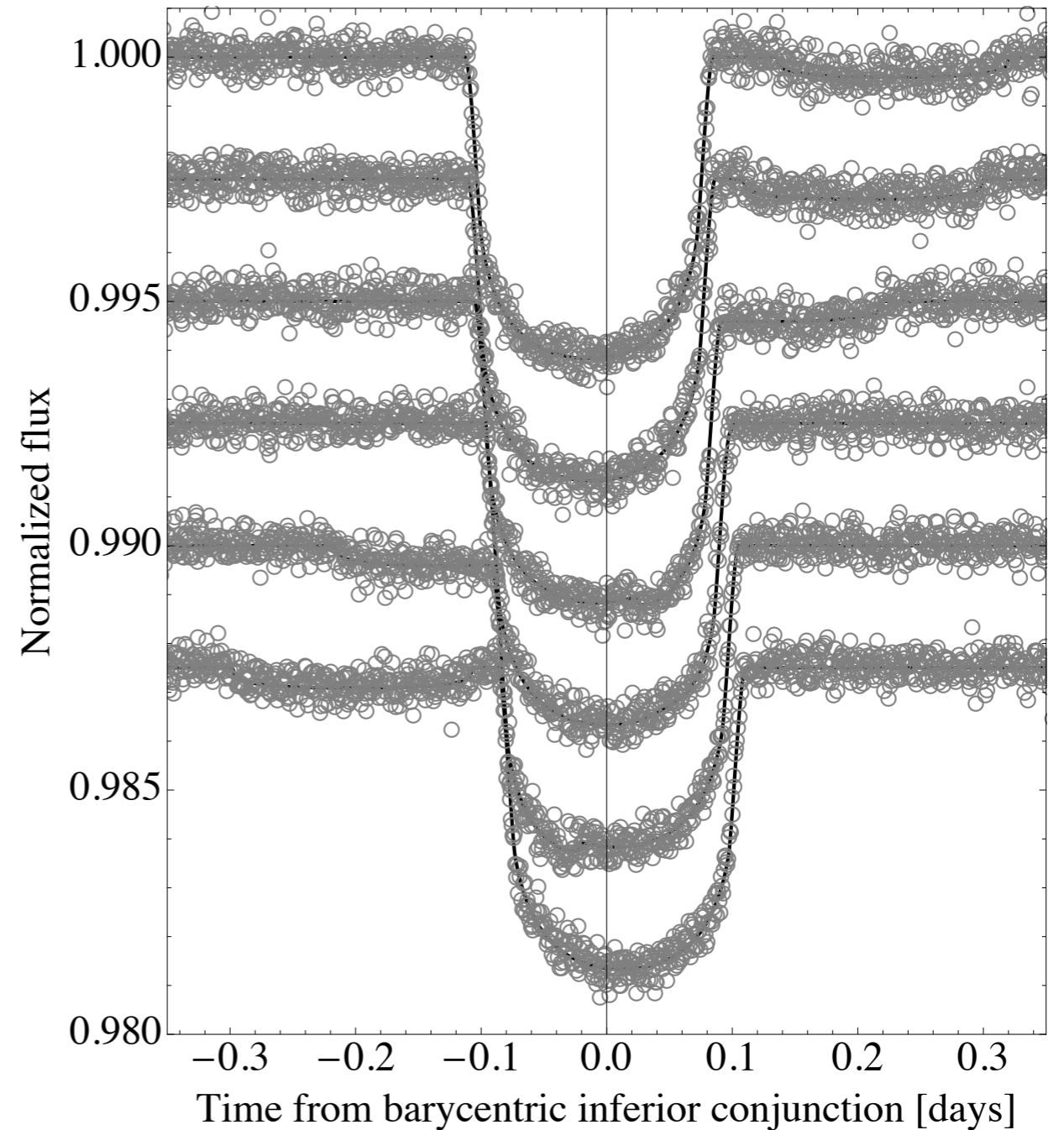
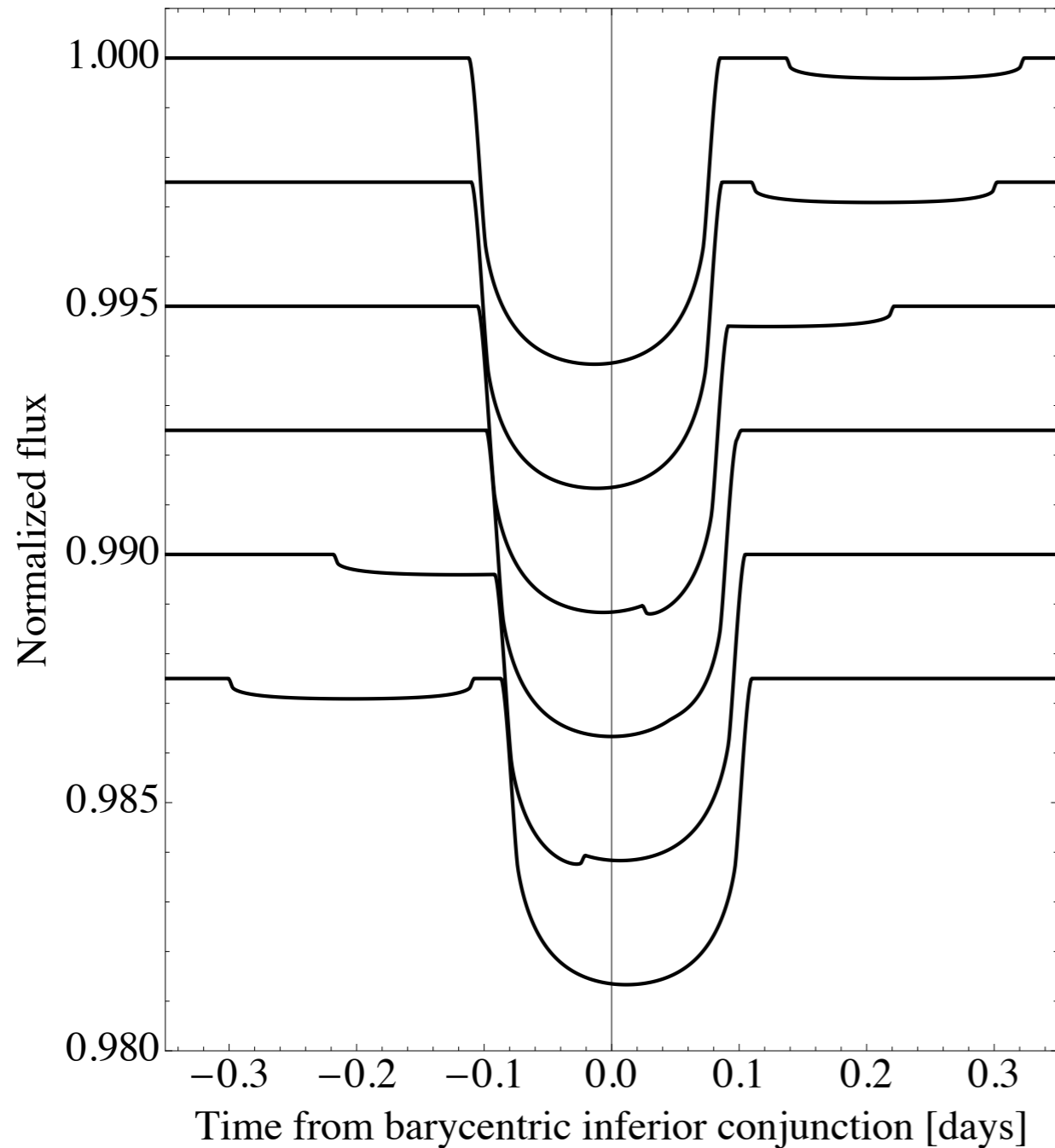


24-sigma detection for typical Kepler noise

Neptune in hab-zone of M2 dwarf with **far-out retrograde** Earth-mass and radius moon



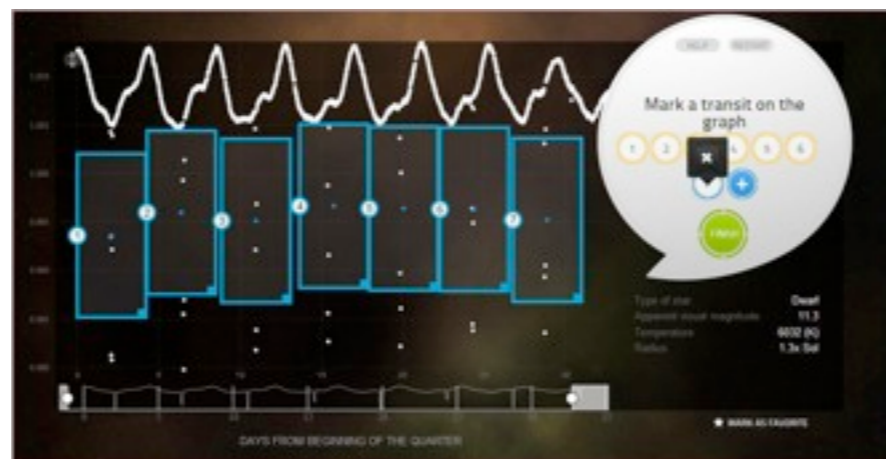
Neptune in hab-zone of M2 dwarf with **far-out retrograde** Earth-mass and radius moon



50-sigma detection for typical Kepler noise

Ongoing Searches

- *Hunt for Exomoons with Kepler* (HEK) project using public Kepler data (Kipping et al. 2012) [see www.exomoon.eu]
- PlanetHunters.org (Fischer et al. 2011)
- Kepler Science Team (Borucki et al. 2009)



HEK: The Hunt for Exomoons with Kepler

- The first systematic search for transiting exomoons.
- Using public Kepler data
- Utilizing LUNA to identify exomoons
- Primary goal: detect a transiting exomoon(s)
- Secondary goal: obtain upper limits
- Tertiary goal: determine the frequency of large moons around viable planet hosts, η_{C}

Search Methods

- Visual inspection e.g. PlanetHunters.org (Fischer et al. 2011)
- Scatter-peak (Simon et al. 2011)
- Epicyclic folding (Parker 2012, see POP presentation by Alex)
- Full model regression e.g. HEK project (Kipping et al. 2012)

Search Methods



org

OP

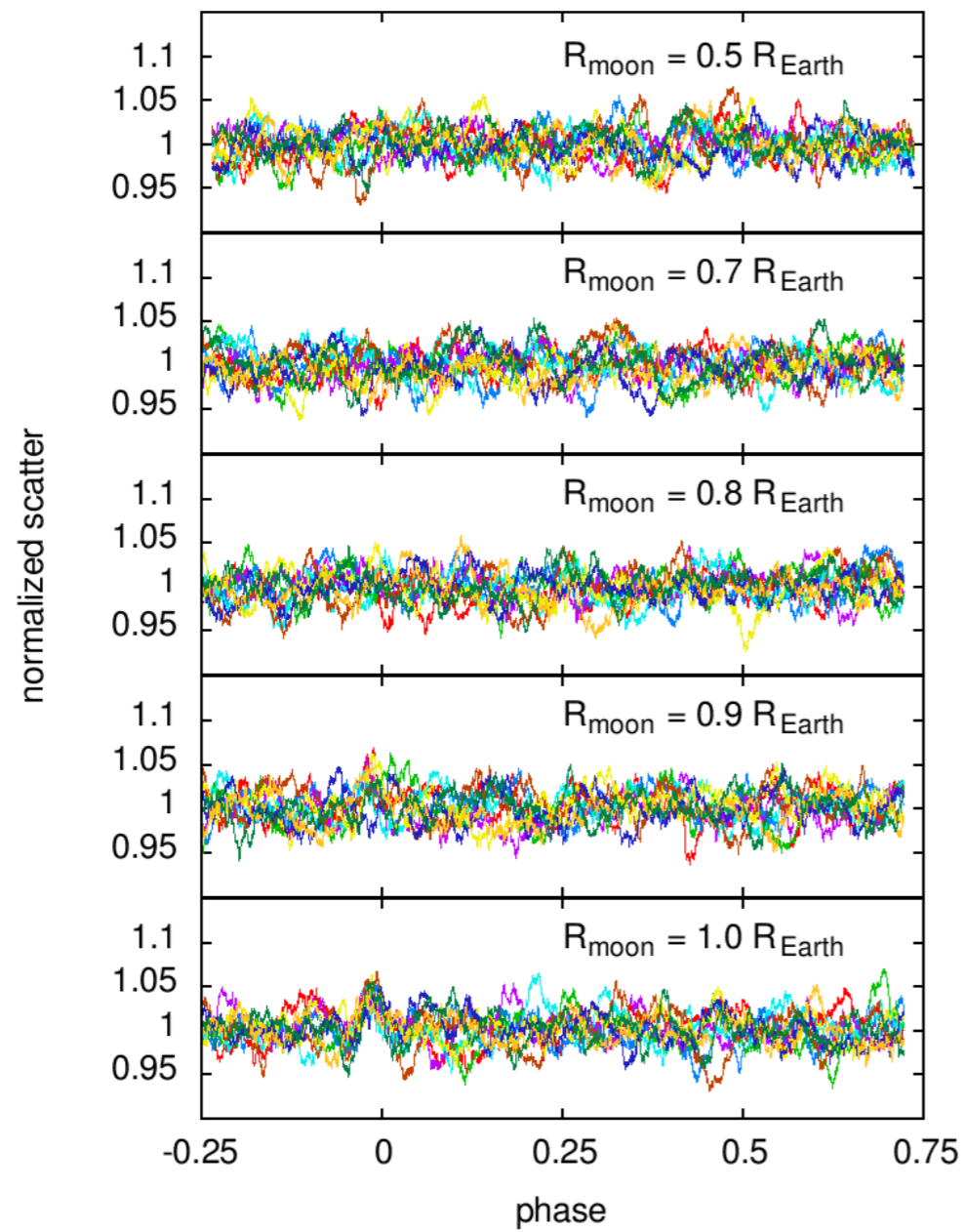
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Search Methods

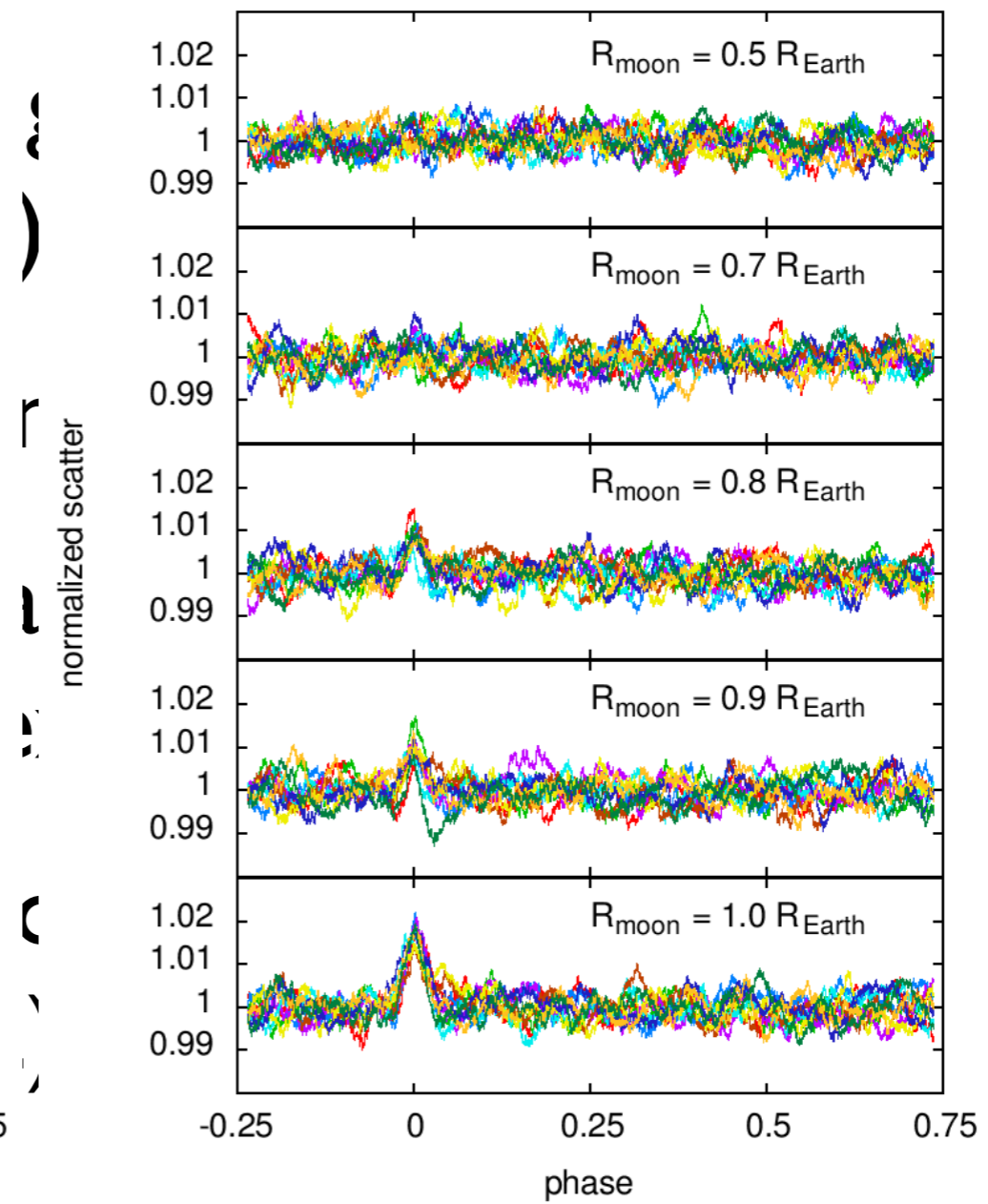
- Visual inspection e.g. PlanetHunters.org (Fischer et al. 2011)
- Scatter-peak (Simon et al. 2011)
- Epicyclic folding (Parker 2012, see POP presentation by Alex)
- Full model regression e.g. HEK project (Kipping et al. 2012)

Search Methods

Kepler LC



Kepler SC

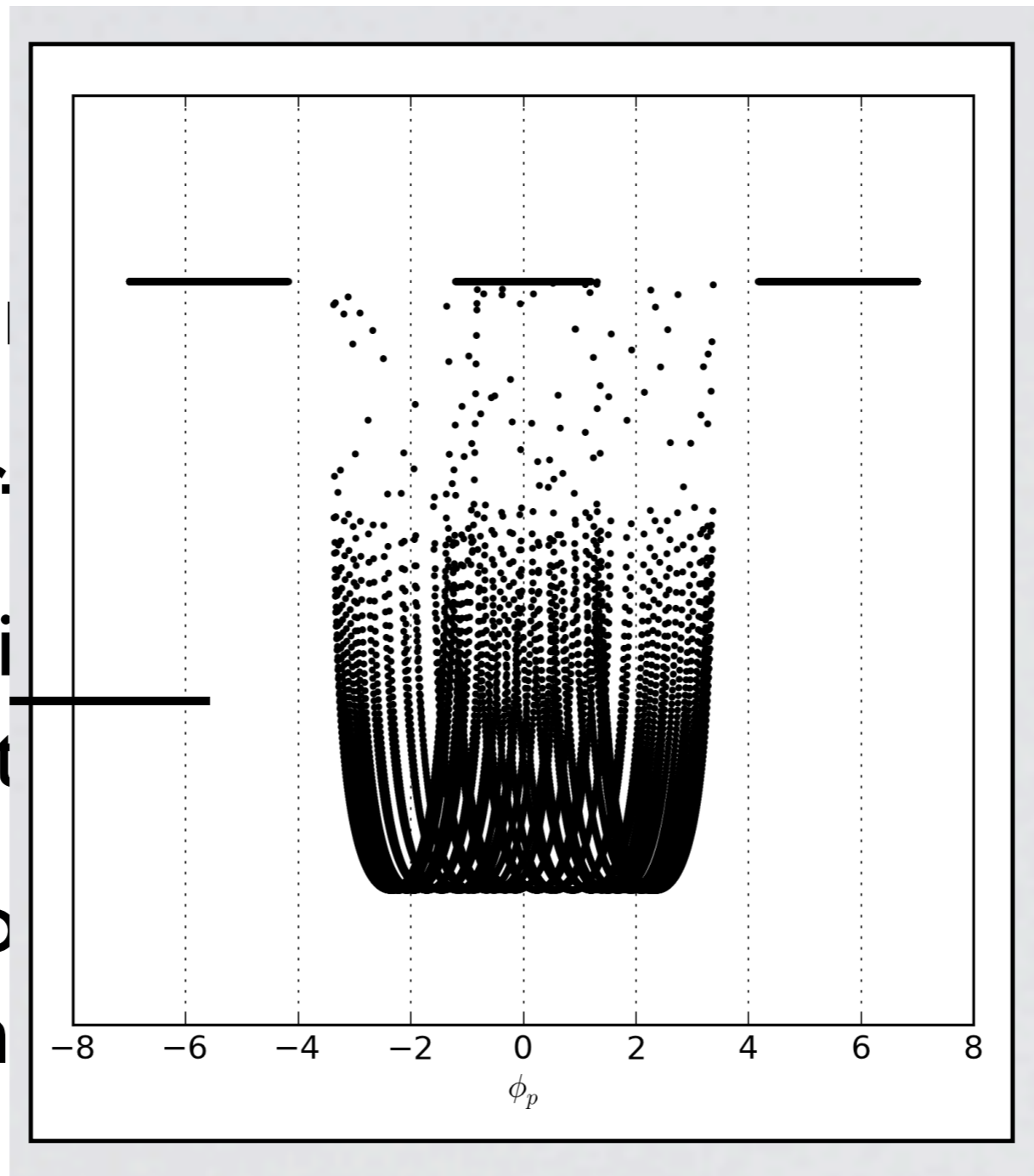


Search Methods

- Visual inspection e.g. PlanetHunters.org (Fischer et al. 2011)
- Scatter-peak (Simon et al. 2011)
- Epicyclic folding (Parker 2012, see POP presentation by Alex)
- Full model regression e.g. HEK project (Kipping et al. 2012)

Search Methods

- Visual inspection (Fischer)
- Scatter plots
- Epicyclic frequencies present
- Full model (Kipping)



s.org

POP

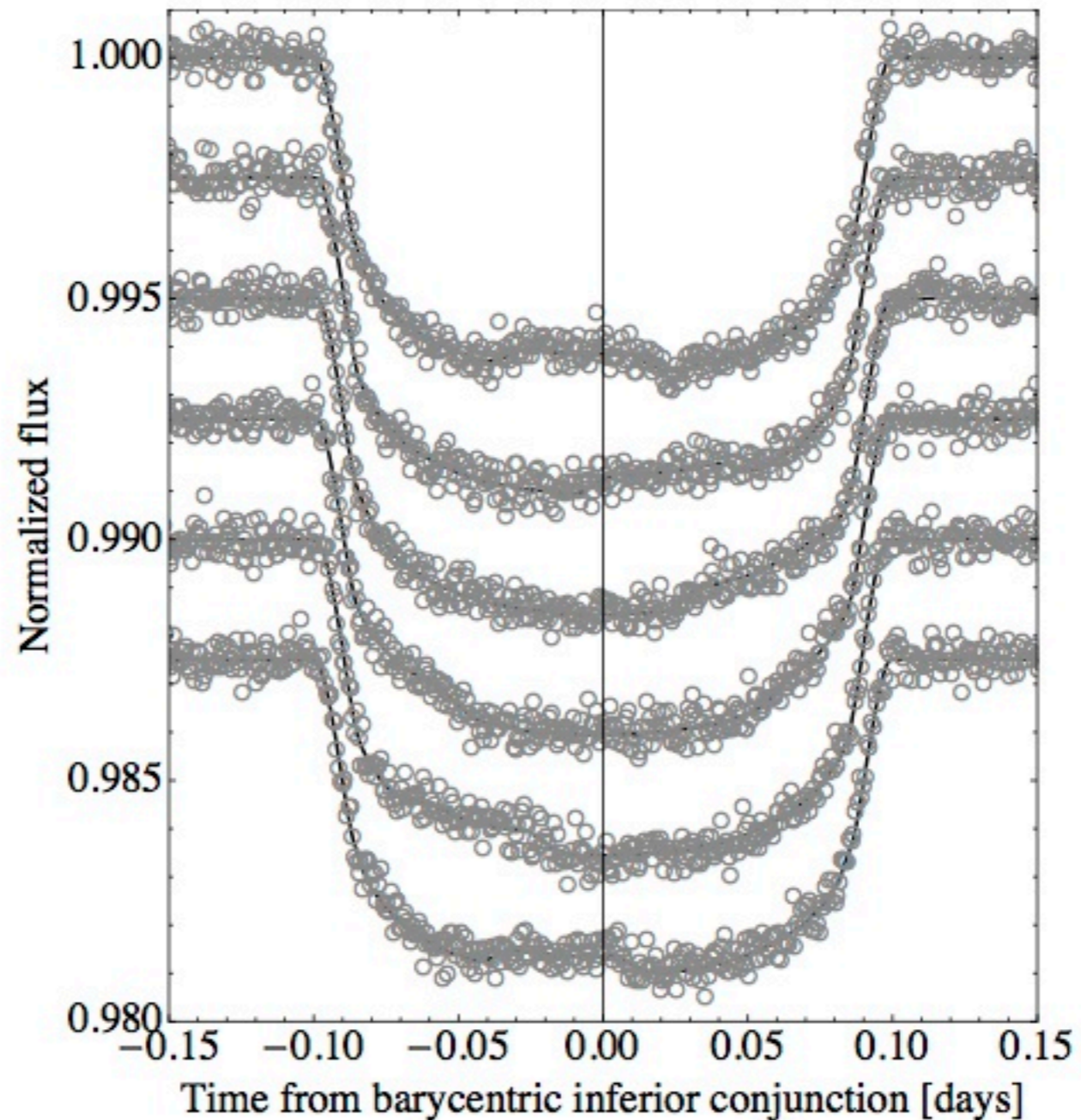
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Search Methods

- Visual inspection e.g. PlanetHunters.org (Fischer et al. 2011)
- Scatter-peak (Simon et al. 2011)
- Epicyclic folding (Parker 2012, see POP presentation by Alex)
- Full model regression e.g. HEK project (Kipping et al. 2012)

Search Methods

- Visual inspection (Fischer)
- Scatter plot
- Eccentricity present
- Full model (Kipping)



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OP

ect

Search Methods

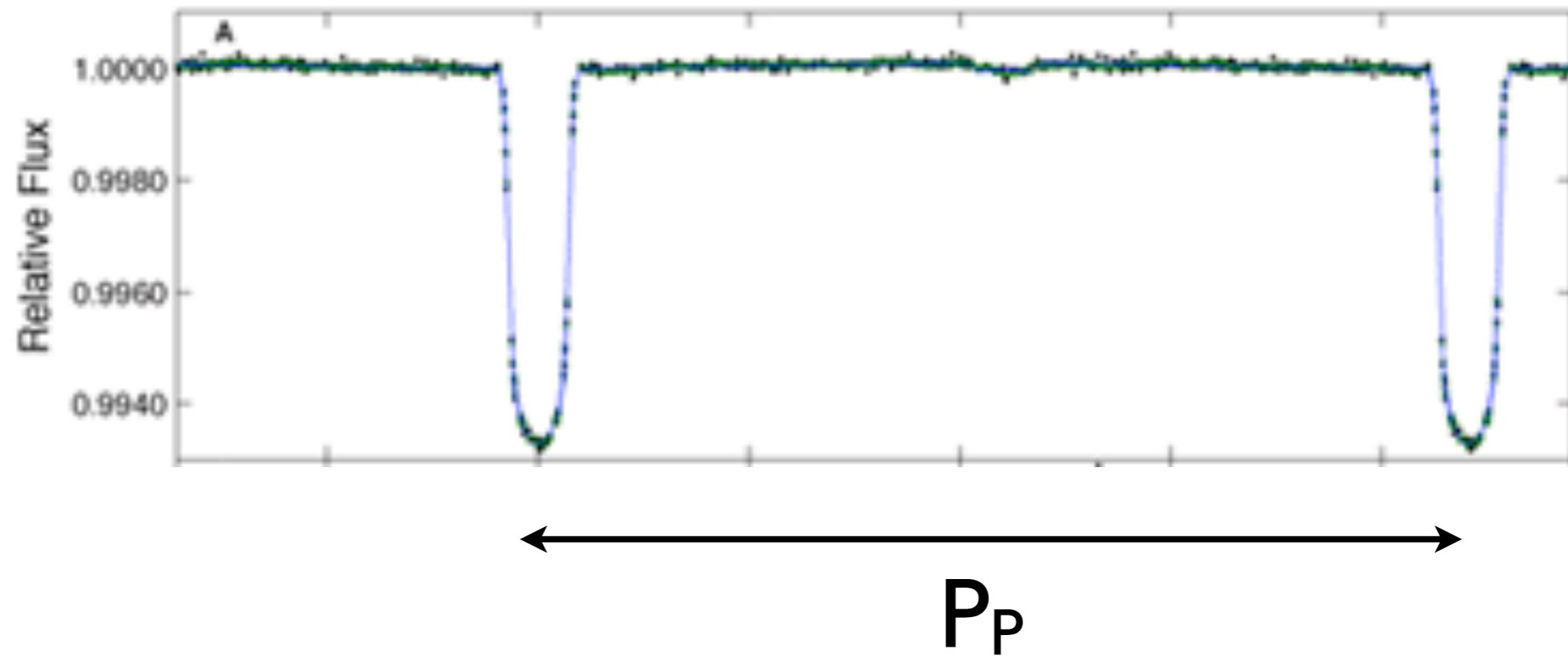
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- Scatter-peak (Simon et al. 2011)
- Epicyclic folding (Parker 2012, see POP presentation by Alex)
- Full model regression e.g. HEK project (Kipping et al. 2012)

IV. Challenges

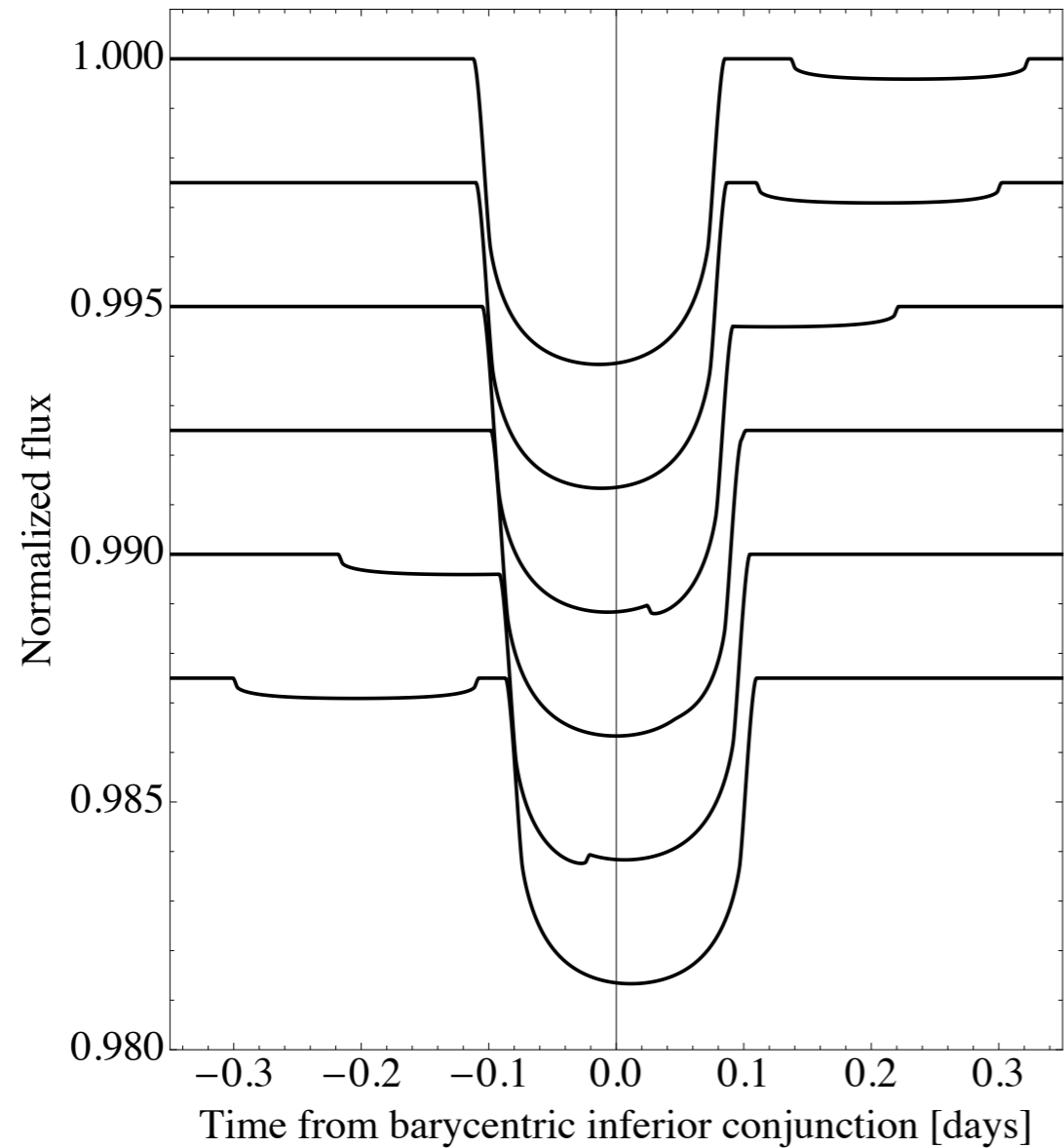
I. Target Selection

- There are >2300 KOIs to choose from.
- Depending on the efficiency of your search, only a fraction of these can be practically analyzed.
- Target selection by dynamics, visual anomalies, bright/quiet stars, etc often required

2. Period Searches Are Tough

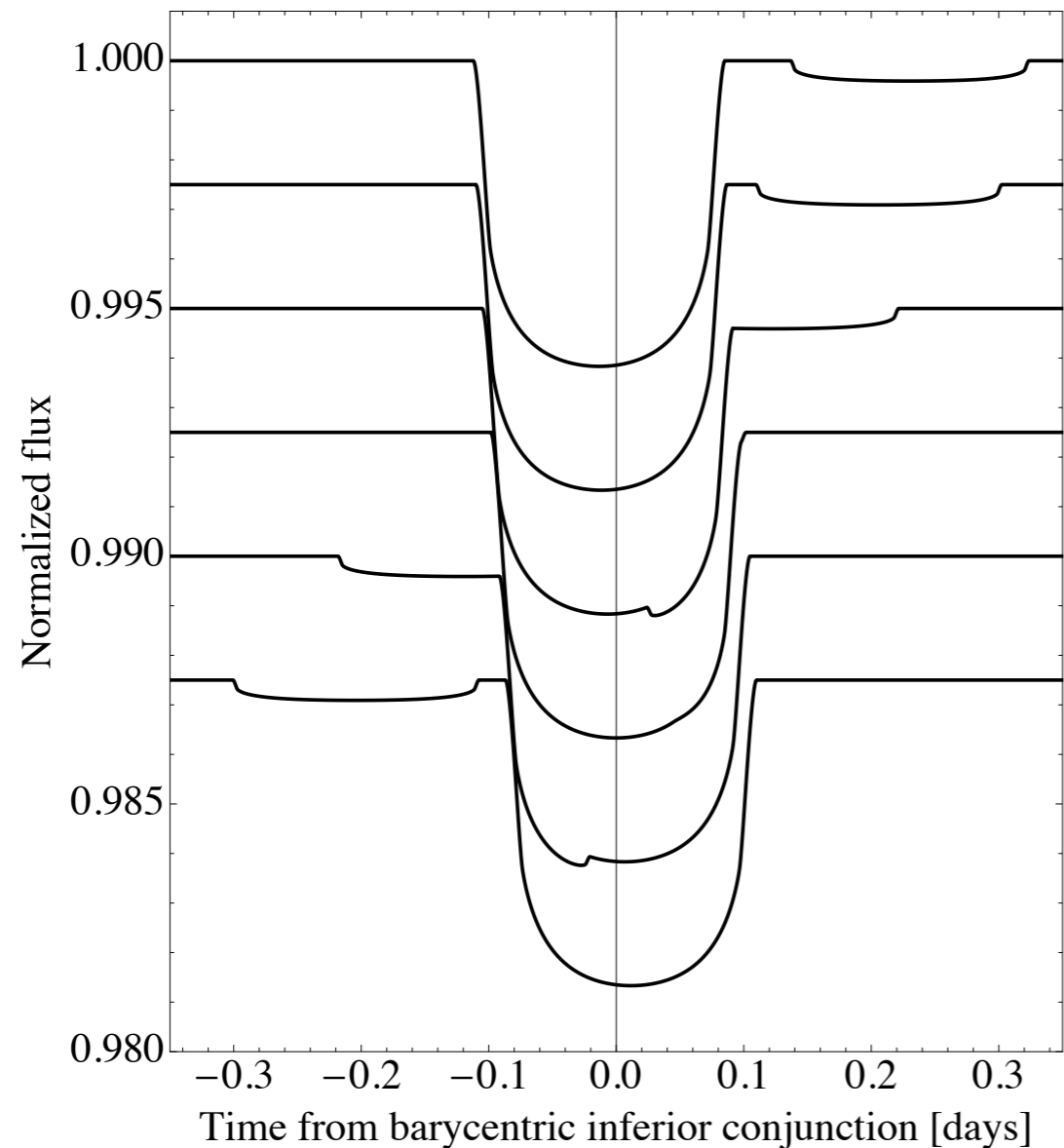


2. Period Searches Are Tough



$$P_S = ?$$

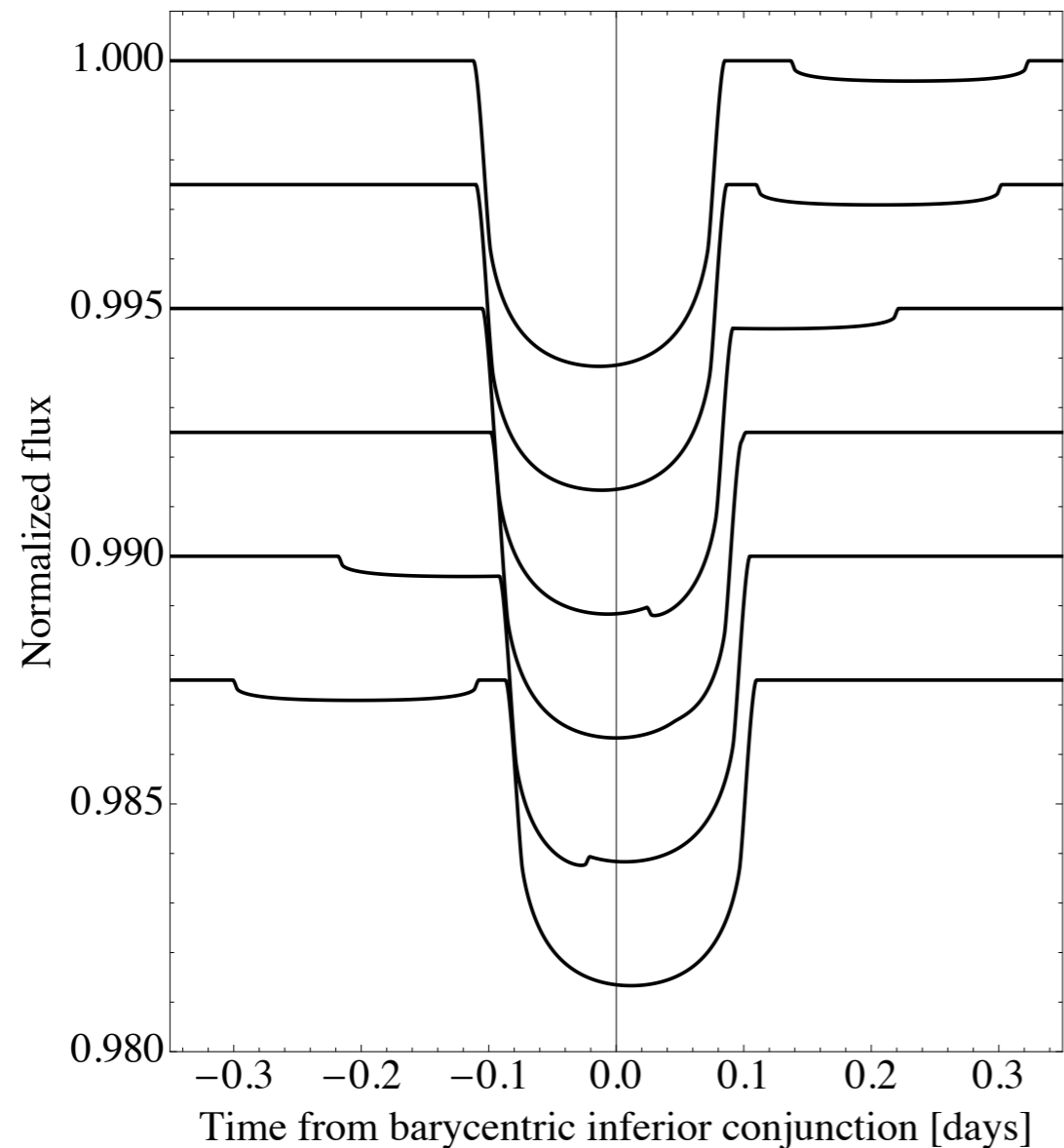
2. Period Searches Are Tough



- Multiple modes present

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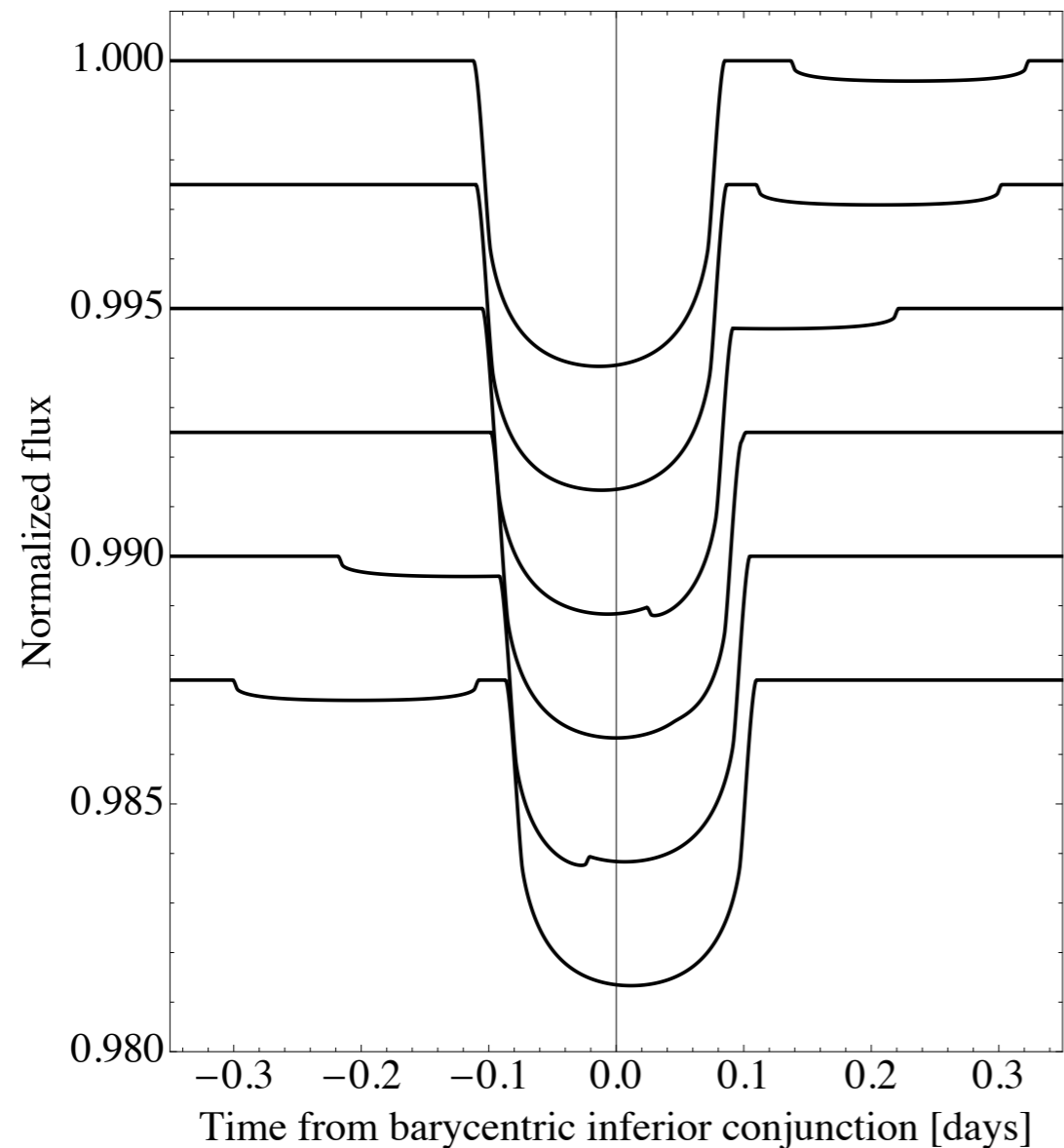
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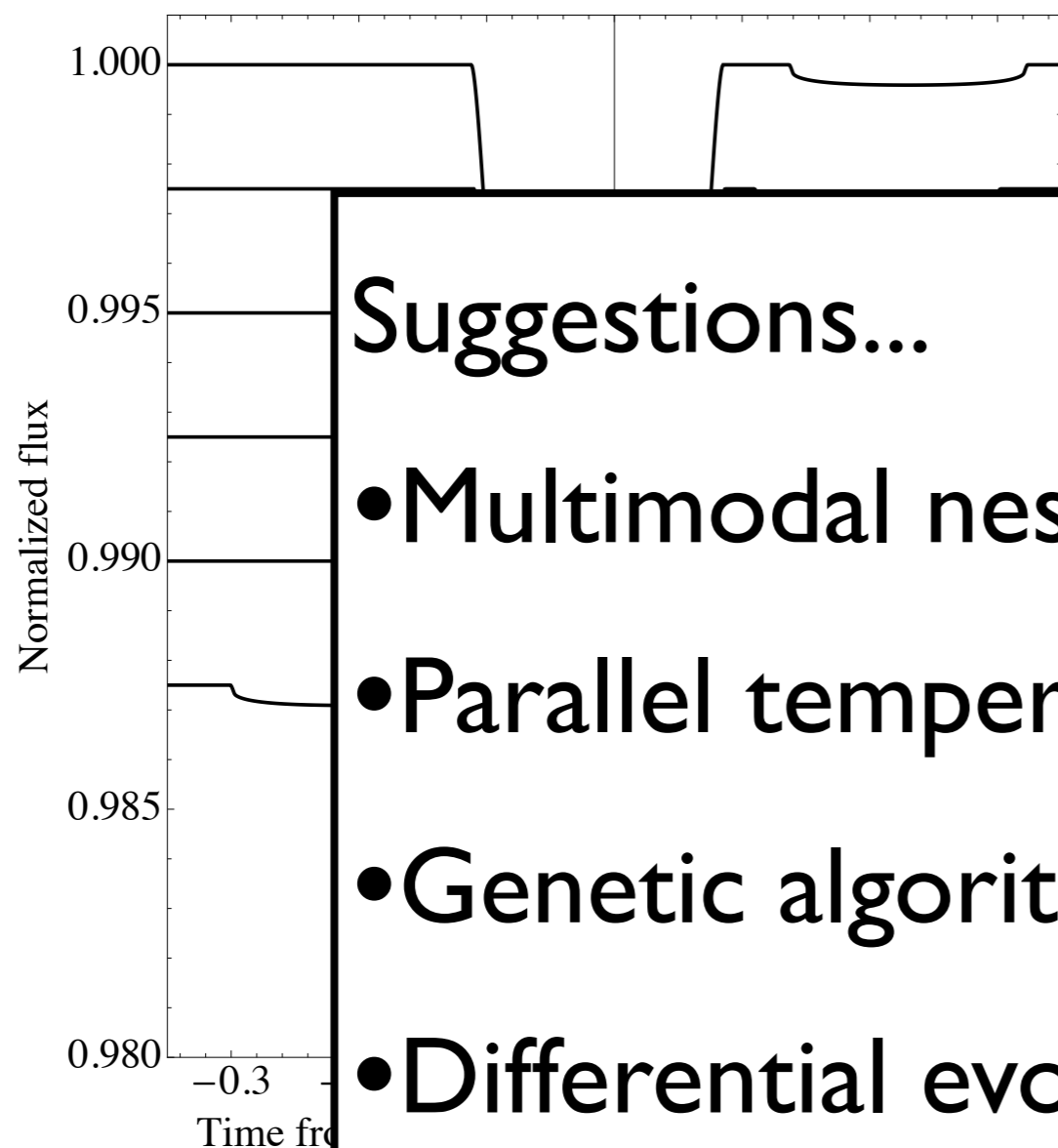
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- Multiple modes present
- Very challenging to visually guess where these modes will occur
- Requires a **comprehensive** and **multimodal** parameter search

2. Period Searches Are Tough



Suggestions...

- Multimodal nested sampling
- Parallel tempering
- Genetic algorithms
- Differential evolution

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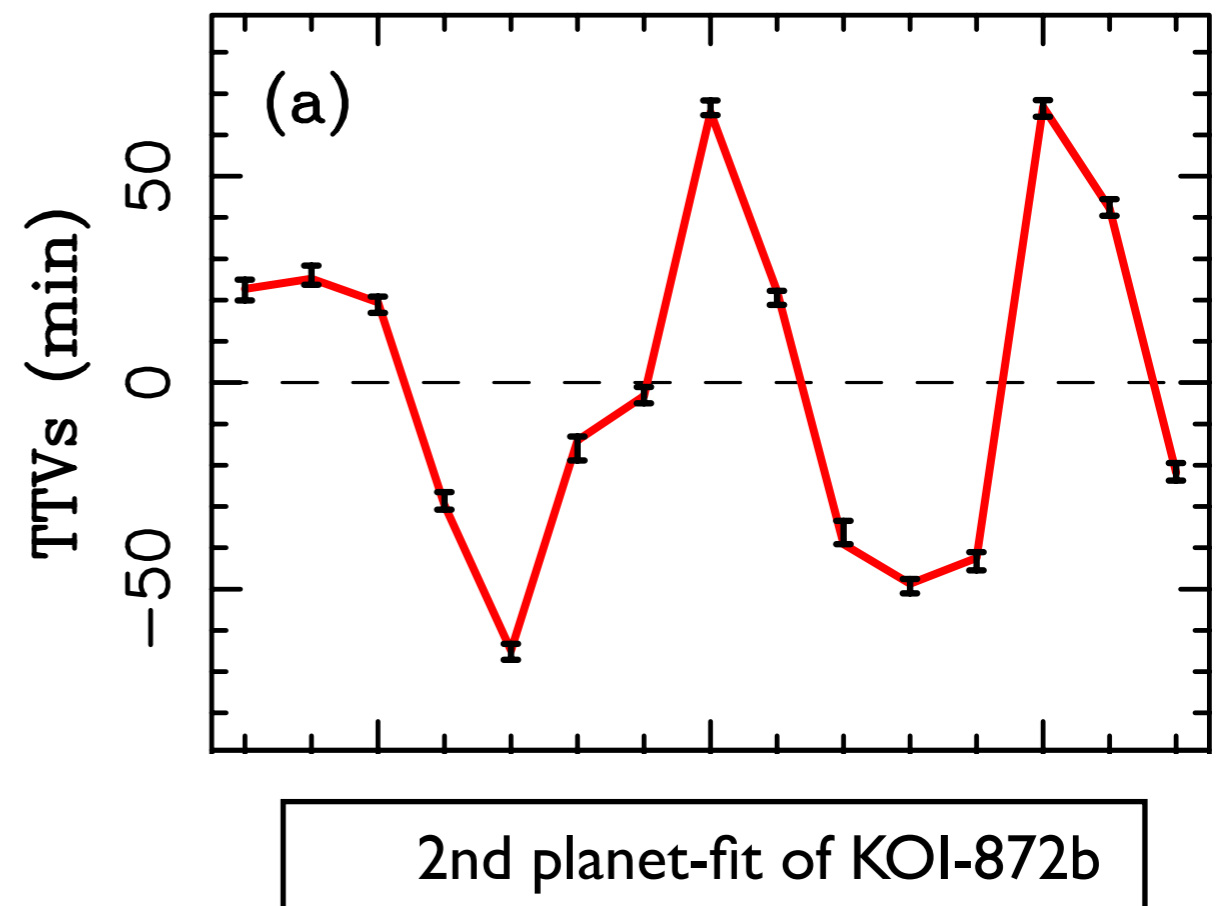
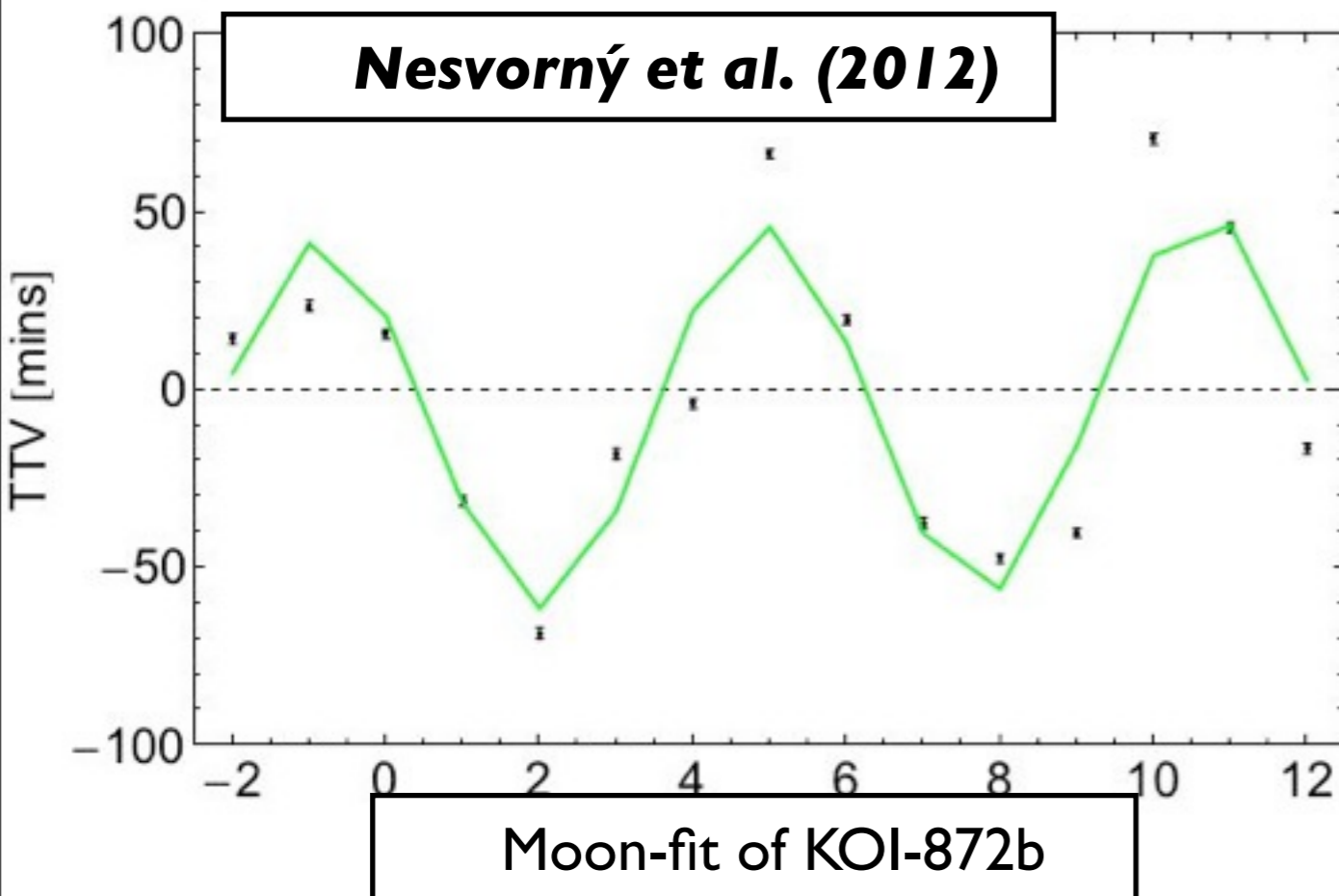
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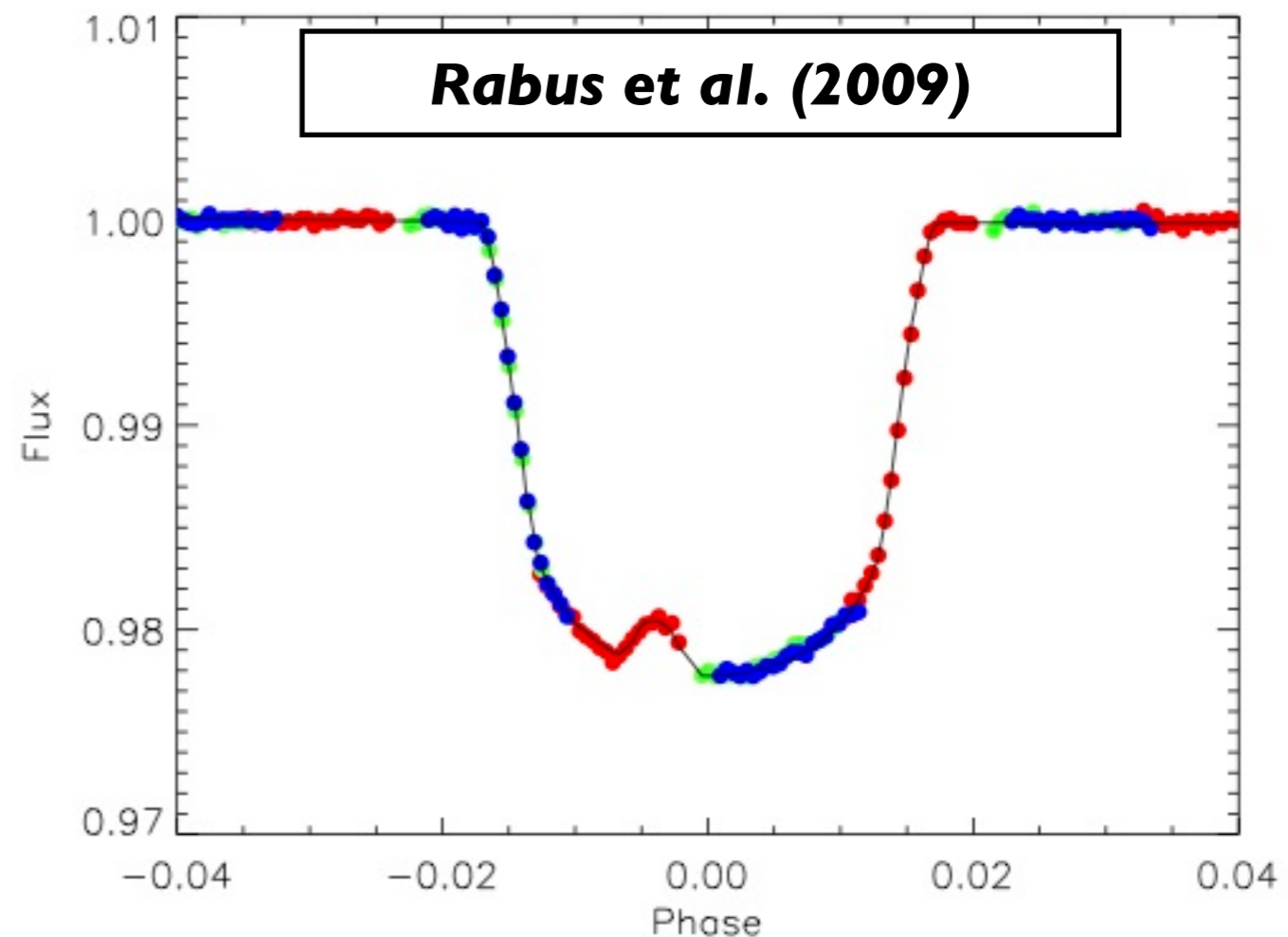
3. Confounding Effects

- A second planet in the system may also induce TTVs.
- If TDVs exist, one can use the phase-trick.
- If not, one must compare whether a moon or a second planet explain the data better:



3. Confounding Effects

- Starspot crossings morphologically resemble an exomoon mutual transit.
- Spots can reveal spin-orbit alignments (see talk by Roberto)...
- ...but for moon-hunters they are a pain!



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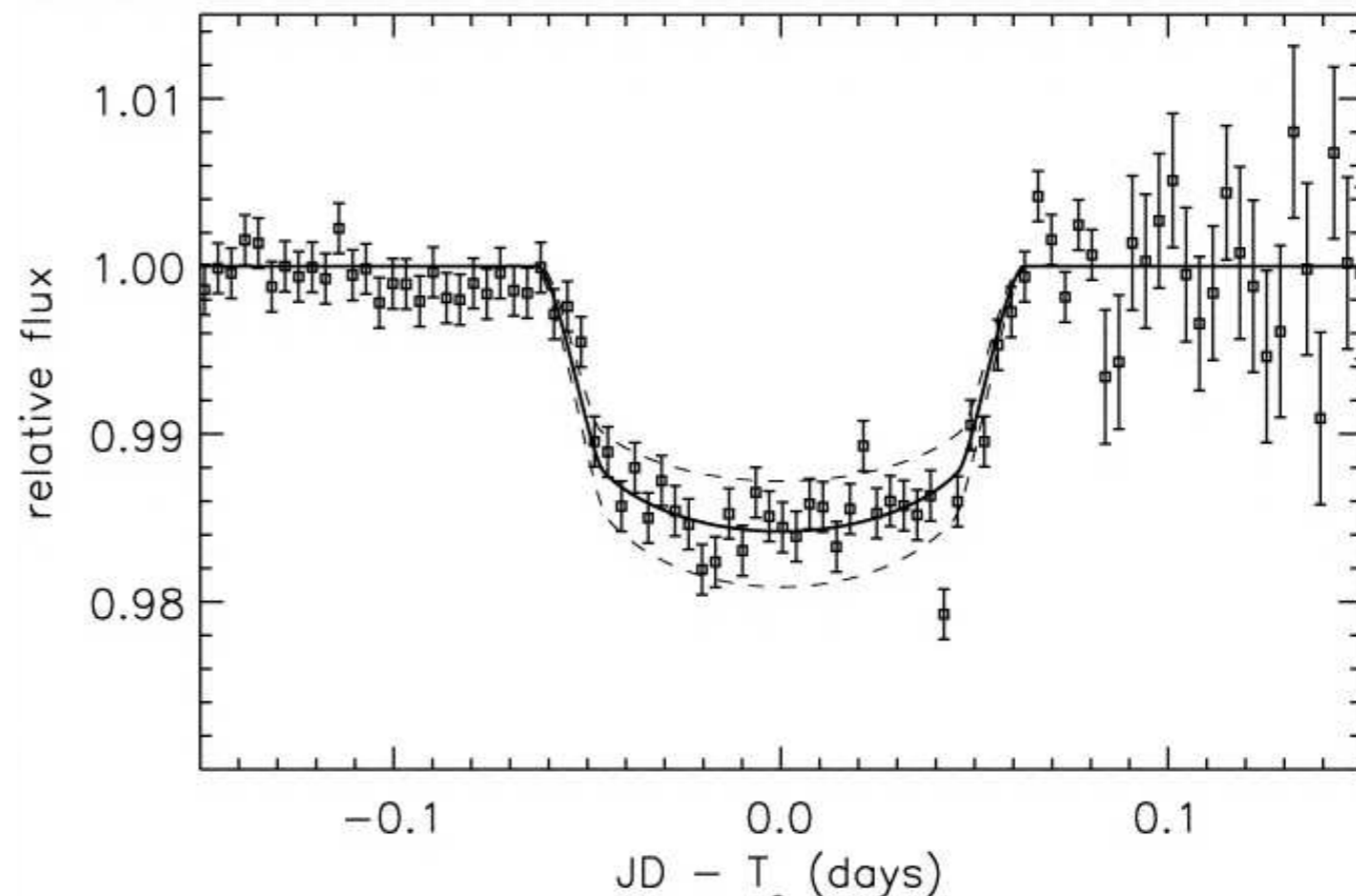
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- Moons allow us to determine the density of the planet, which can be used in vetting.
- Ultimately it would be advantageous to have a full starspot model for comparison

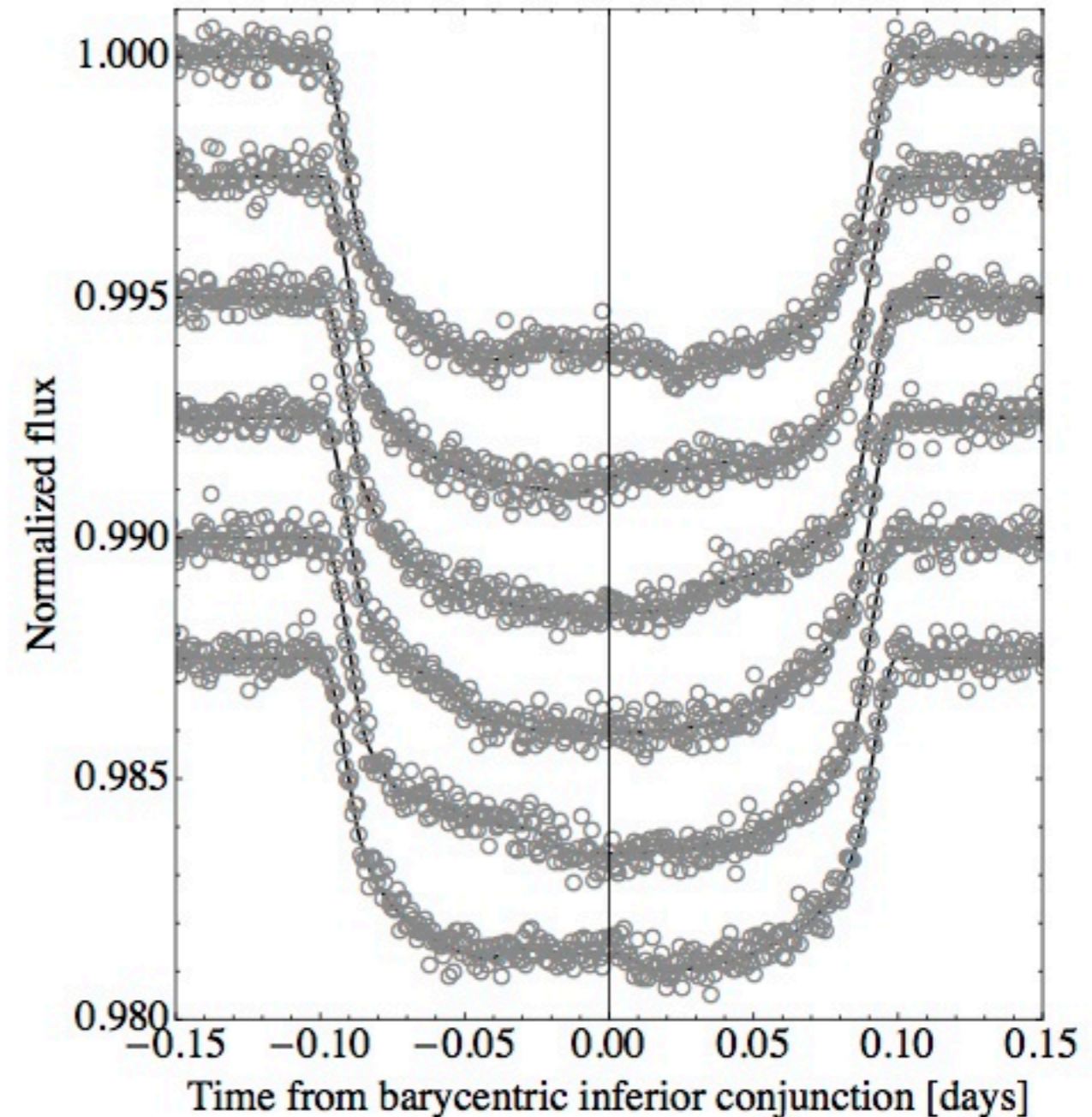
4. What is a “detection”?

- First transiting planet detection, HD 209458b (Charbonneau et al. 2000)
- Simple signal, high SNR, few alternative explanations



4. What is a “detection”?

- Exomoons induce complex signals
- Low SNR
- Several alternative explanations



4. What is a “detection”?

- Data could be due to a planet-with-moon, a planet with correlated noise, a planet and starspots, a planet + perturbing planet, etc...
- We need to perform **model selection** between these options.

What is model selection?

- Bayesian model selection compares the probability of model 1, given data D , versus the probability of model 2, given data D .

What is model selection?

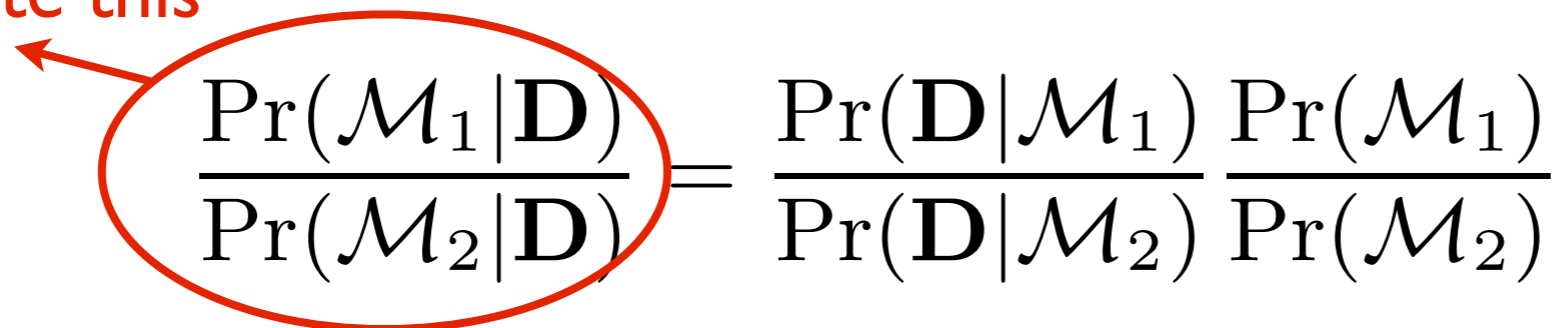
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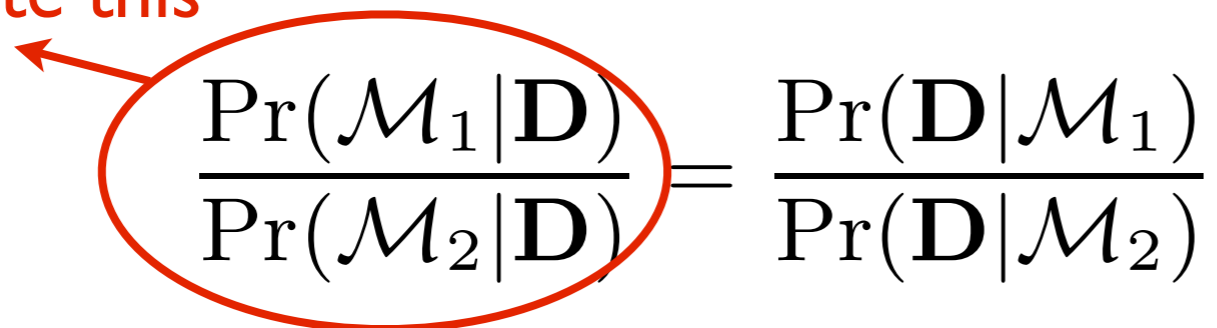
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=> need to calculate these aka the **Bayesian evidence**

What is the Bayesian evidence?

- We need calculate the **Bayesian evidence**.
- You may be asking yourself - *Why have I not heard of this before?*

$$\Pr(\Theta|\mathbf{D}, \mathcal{M}) = \frac{\Pr(\mathbf{D}|\Theta, \mathcal{M})\Pr(\Theta|\mathcal{M})}{\Pr(\mathbf{D}|\mathcal{M})}$$

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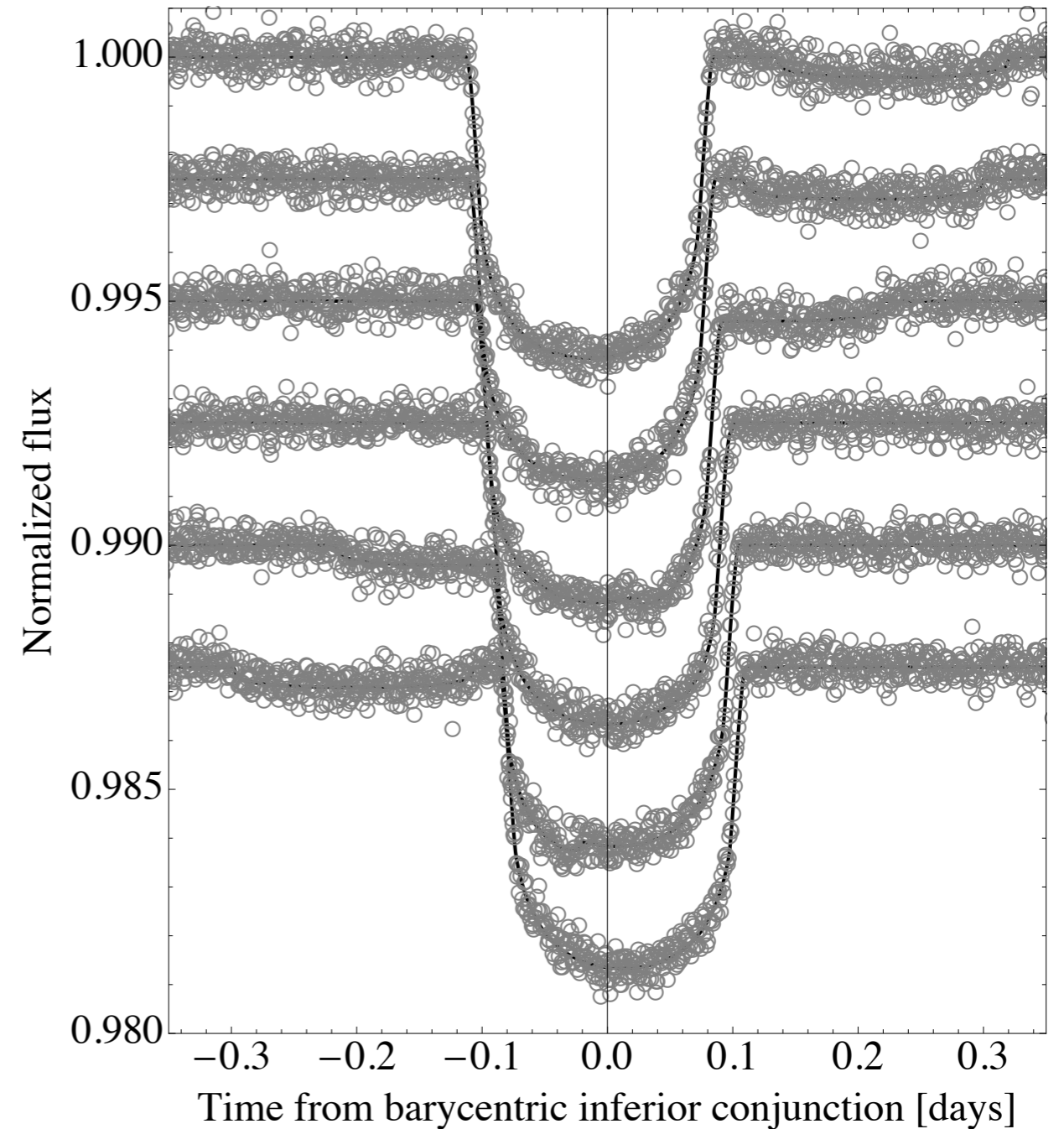
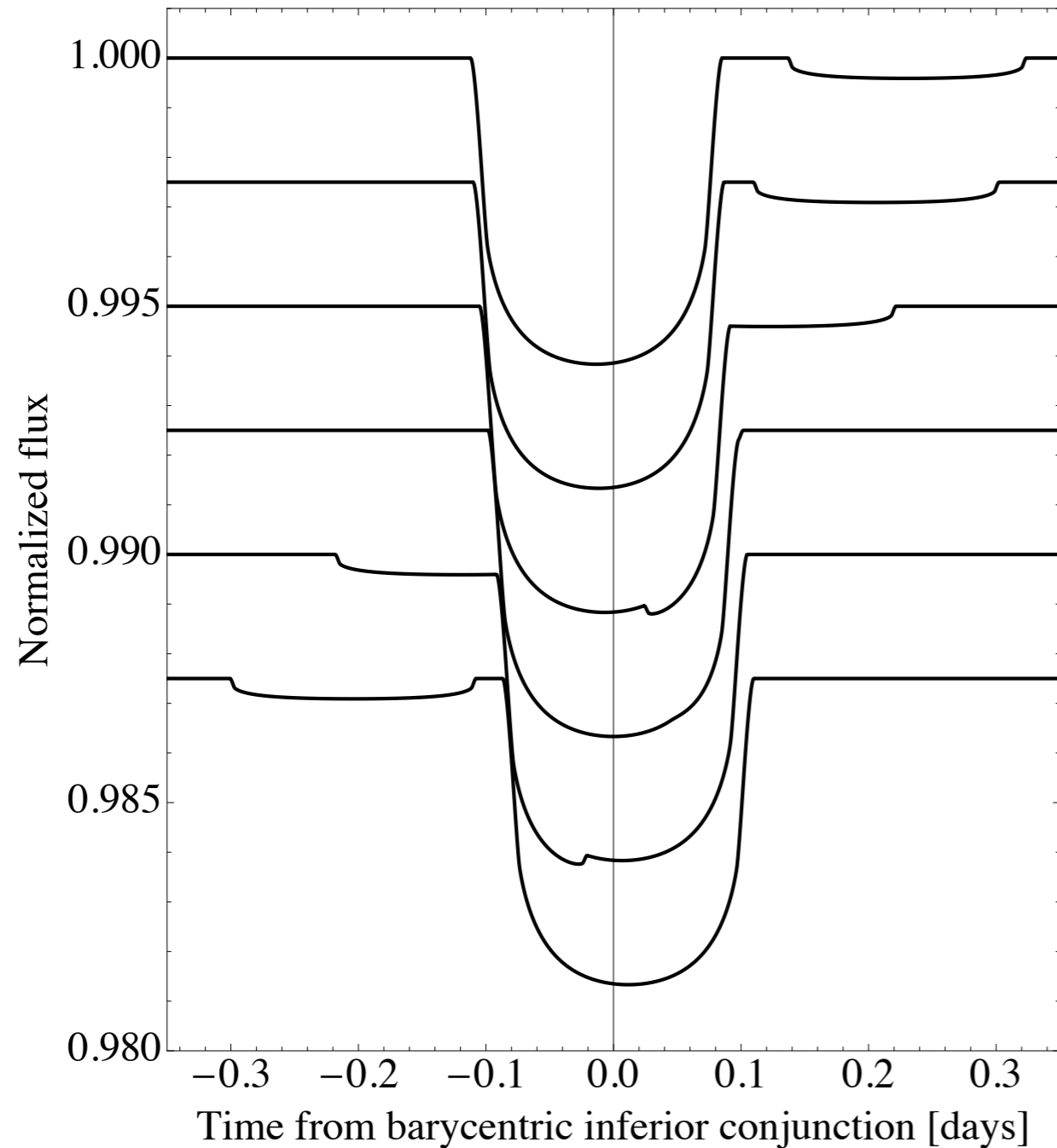
- The most common parameter search algorithm for exoplanetary scientists is MCMC.
- In almost all cases, the Bayesian evidence is not objective and is often ignored. This is because the evidence is not affected by the choice of parameters. The evidence is a function of the data and the model, but not of the parameters. This is why the evidence is often ignored. The evidence is a function of the data and the model, but not of the parameters. This is why the evidence is often ignored.
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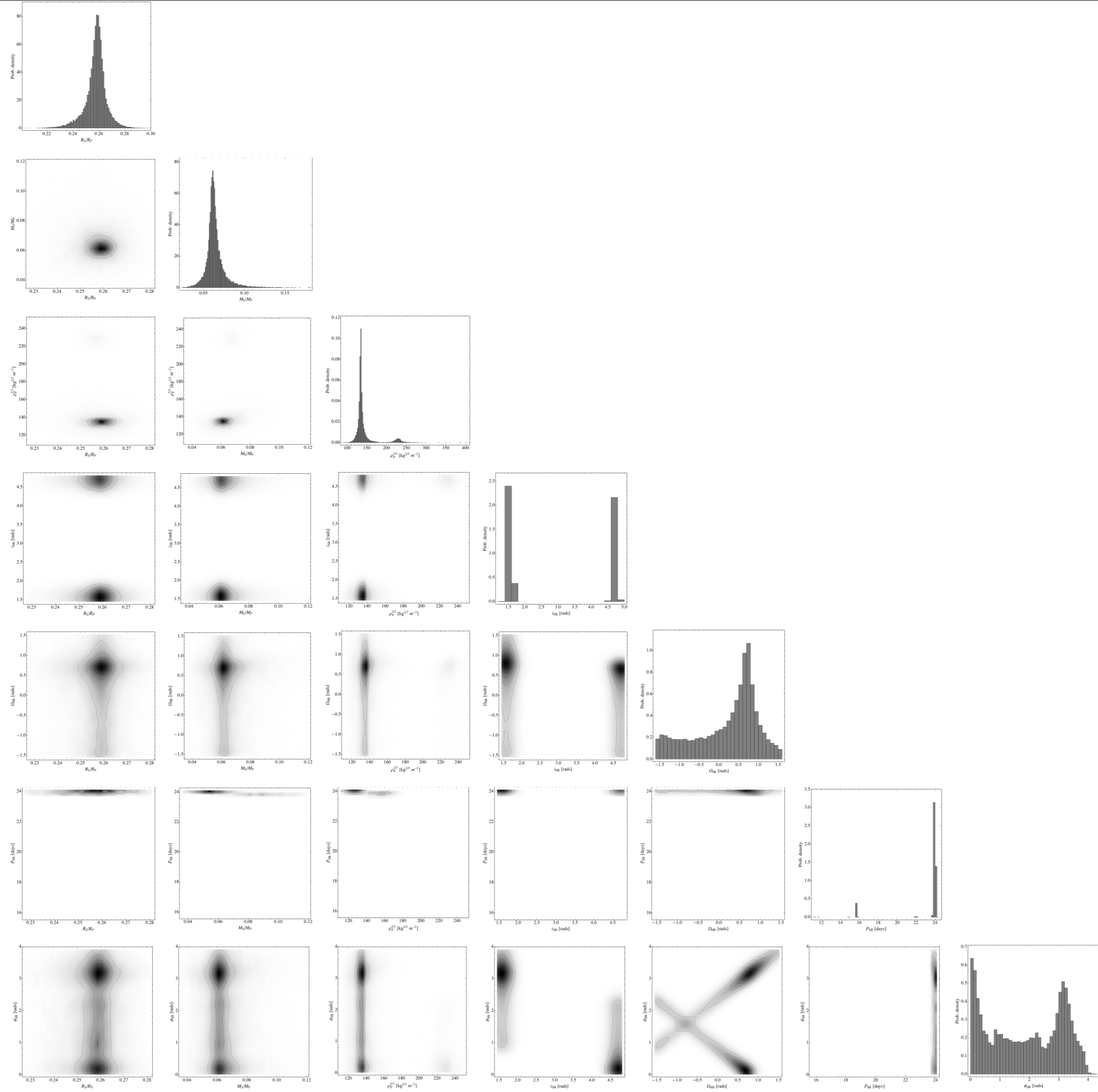
Suggestions...

- Multimodal nested sampling
- Thermodynamic integration (very slow)

V. Synthetic Example

Neptune in hab-zone of M2 dwarf with **far-out retrograde** Earth-mass and radius moon



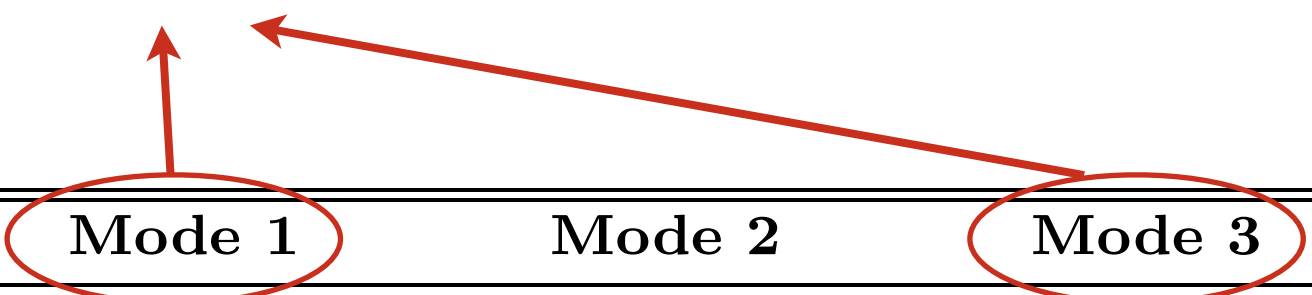


Three Modes

Parameter	Truth	Mode 1	Mode 2	Mode 3	Global
$\log \mathcal{Z}$	-	23552.49 ± 0.36	23523.81 ± 0.99	23551.27 ± 0.45	23552.75 ± 0.27
<i>Moon params.</i>					
R_S/R_P	0.2570	$0.2587^{+0.0053}_{-0.0069}$	$0.2559^{+0.0051}_{-0.0065}$	$0.2587^{+0.0052}_{-0.0070}$	$0.2585^{+0.0053}_{-0.0069}$
M_S/M_P	0.0583	$0.0620^{+0.0086}_{-0.0058}$	$0.0672^{+0.0072}_{-0.0073}$	$0.0622^{+0.0096}_{-0.055}$	$0.0624^{+0.0092}_{-0.0059}$
$[\rho_P]^{2/3}$ [kg ^{2/3} m ⁻²]	139.0	$134.5^{+5.8}_{-4.7}$	$229.4^{+10.2}_{-8.9}$	$134.7^{+6.6}_{-4.4}$	$134.9^{+11.0}_{-4.5}$
i_{SB} [°]	267.06	$90.1^{+1.4}_{-1.5}$	$270.20^{+1.20}_{-0.70}$	$270.1^{+1.3}_{-1.2}$	90^{+180}_{-3}
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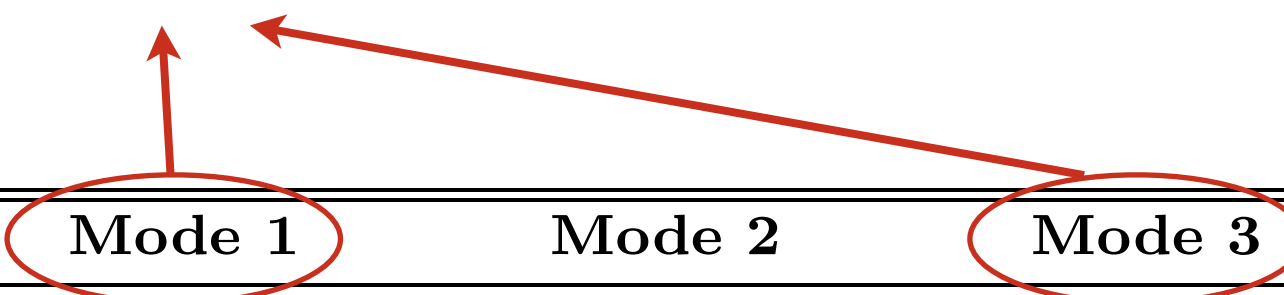
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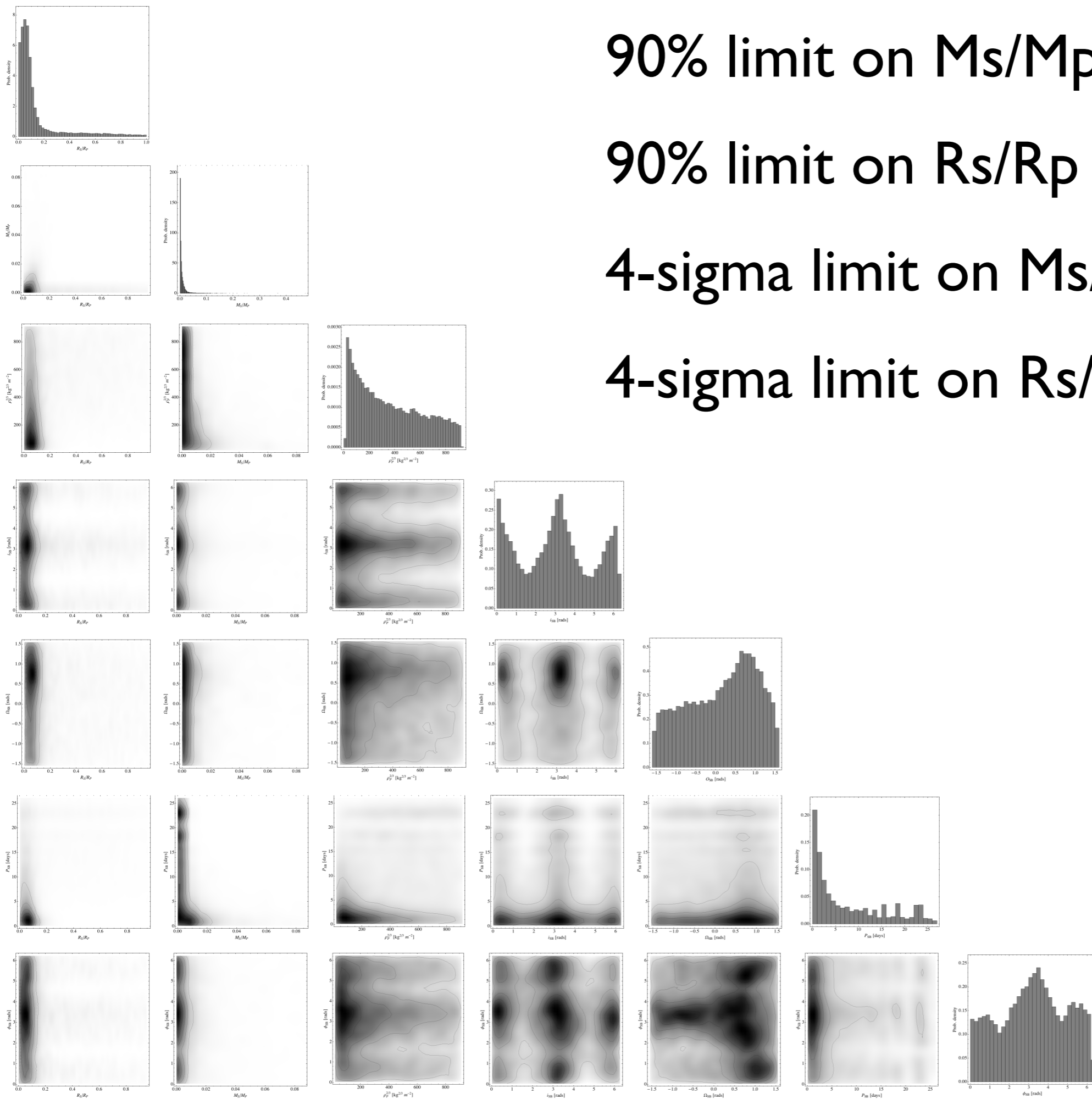
This is the real mode, but we could only get the correct period blindly, not the correct sense of orbital motion

90% limit on $M_s/M_p < 0.018$

90% limit on $R_s/R_p < 0.44$

4-sigma limit on $M_s/M_p < 0.369$

4-sigma limit on $R_s/R_p < 0.999$



Questions?