



STEPS: Stellar Planet Survey

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STEPS ground-based astrometry at Hale Telescope

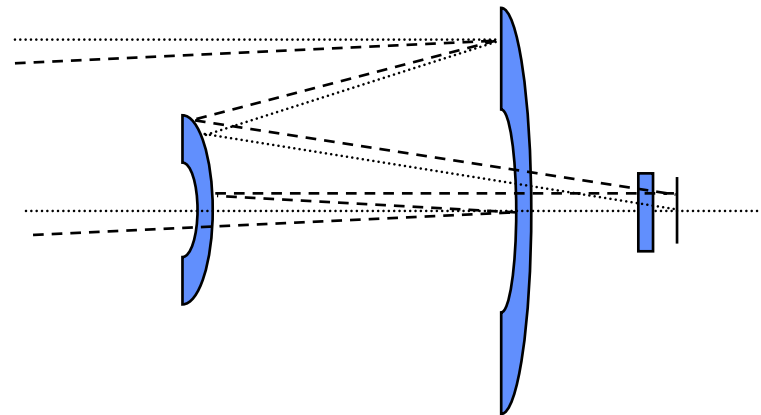


-
- **Started December, 1997. Now in 8th year.**
 - **30 nearby M-dwarf stars, V= 12-16.**
 - **Search for > 1 MJ planets and brown dwarfs**
 - **4k x 4k CCD, 2 arcmin field**
 - **Collaborators: Fritz Benedict (spectroscopy), James Lloyd (AO), Shri Kulkarni (AO), Todd Henry (HST)**
 - **STEPS papers referenced on last page of this presentation**
 - **Discovery of M-dwarf and Brown Dwarf companions to M-dwarf stars.**

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- **4K Loral CCD**
- **LN2 Dewar**
- **SDSU (Leach) Electronics**
 - 4 amplifiers
 - Bin pixels 2x2
 - 200 kpix read rate
- **Binned pixel scale = 78 mas/pix**
- **Mounts at straight-Cass, f/16 on the Palomar 200 in. telescope.**
 - Was also used at Keck II in 1998.
- **Window is high quality lambda/30 p-v surfaces.**
 - Focus term due to vacuum leads to plate scale magnification which is absorbed by the conformal model.



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Targets



- **Targets should not saturate detector too quickly**
 - $V > 12$
- **Need reference stars**
 - Gal. latitude < 30 deg.
- **Need signal > 1 mas with M_J planet in 10 yr orbit**
 - Nearby, low-mass
- **Limited telescope time (~ 8 scheduled nights/yr)**
- **These criteria led to selection of 30 nearby M-dwarfs.**
 - Earlier stars are too bright and their signals are too small.
 - Reference stars are typically $V < 19.5$

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Why the Palomar 200 in. Telescope?



- Large telescopes dramatically increase astrometric efficiency. (Lindgren 1980, Shao and Colavita 1992).
 - r.m.s. motion $\sim \theta/D^{2/3}$, θ = field, D = tel. diam.
- We typically achieve 300-500 micro-arcsec s.e.m. of target relative to reference frame in 20 1-minute exposures.
- Systematic error sources:
 - DCR: correct 10's of mas
 - Dust, window,
 - Electronics???

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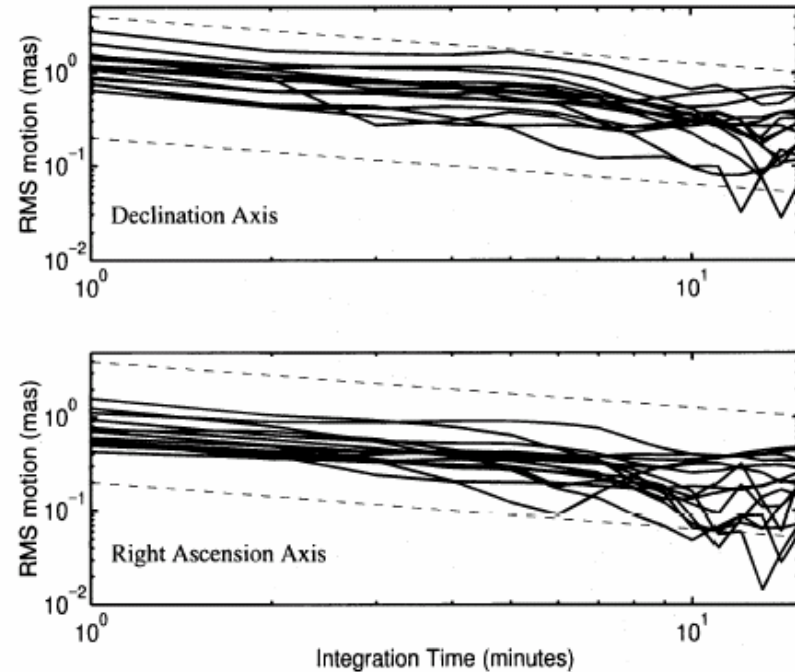


FIG. 2.—The square root of the Allan variance of the positional uncertainty of 15 stars in NGC 2420 observed with the Palomar 5 m. *Top*: Declination. *Bottom*: Right ascension.

Pravdo and Shaklan, 1996 ApJ 465, 264



Observations



- **Typically 20 1-minute exposures per field.**
 - Standard error of mean < 1 mas
- **Try to stay within 1 hr of meridian.**
 - Minimize DCR
- **Repoint from run-to-run to within a few arcsec.**
 - Minimize impact of local CCD and window distortion
- **Dither pointing in square pattern, 1 arcsec steps.**
 - Reduce effect of hot pixels, local gradients....
- **No fine guiding, no AO, just simple imaging.**
 - PSF of all sources across the FOV are nearly identical
- **Typically observe 2 or 3 consecutive nights.**
 - Helps distinguish systematic vs. stochastic noise
- **Compute nightly statistic: mean position and standard error of the mean relative to reference frame.**

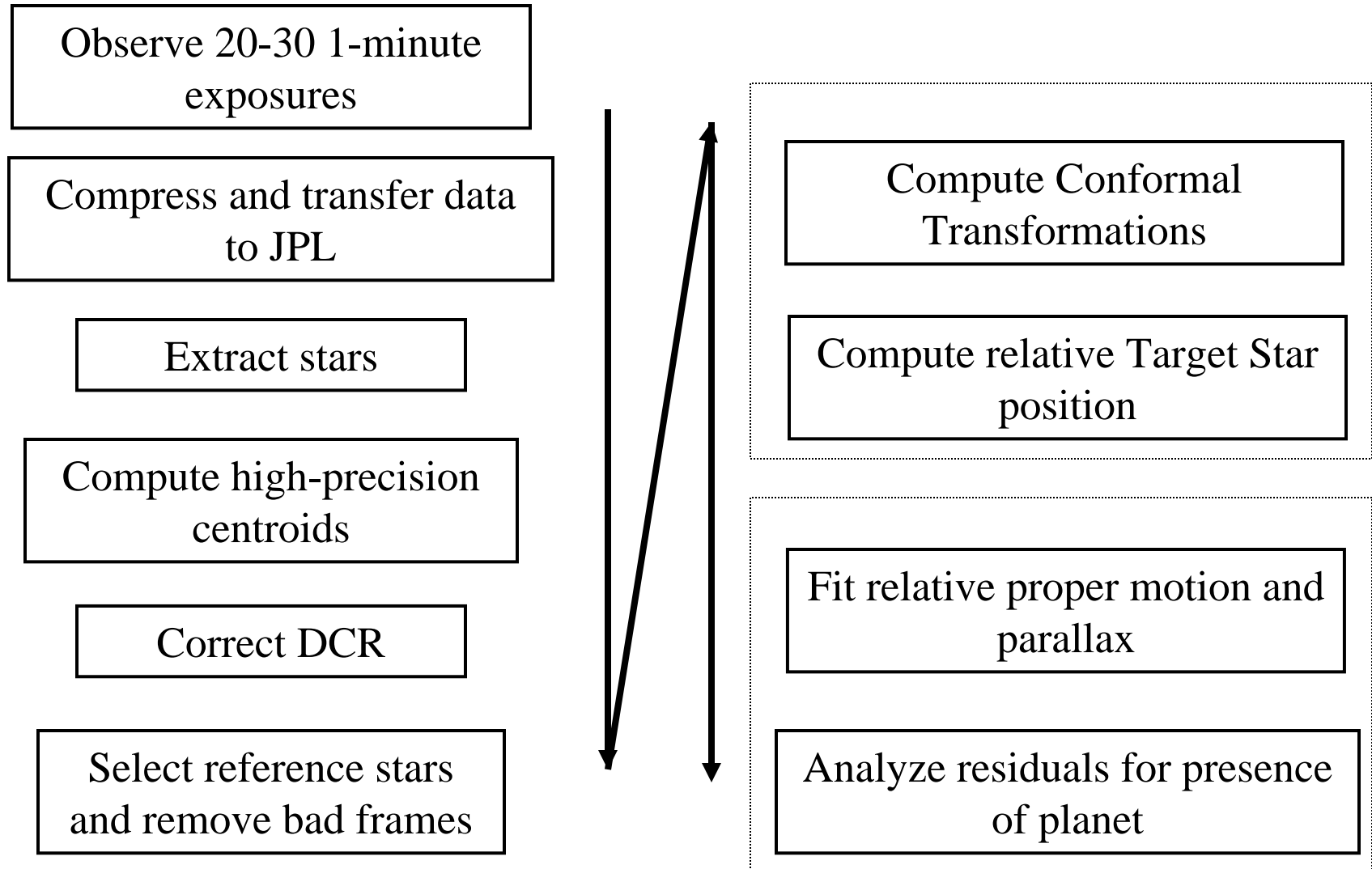
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Data Processing Sequence



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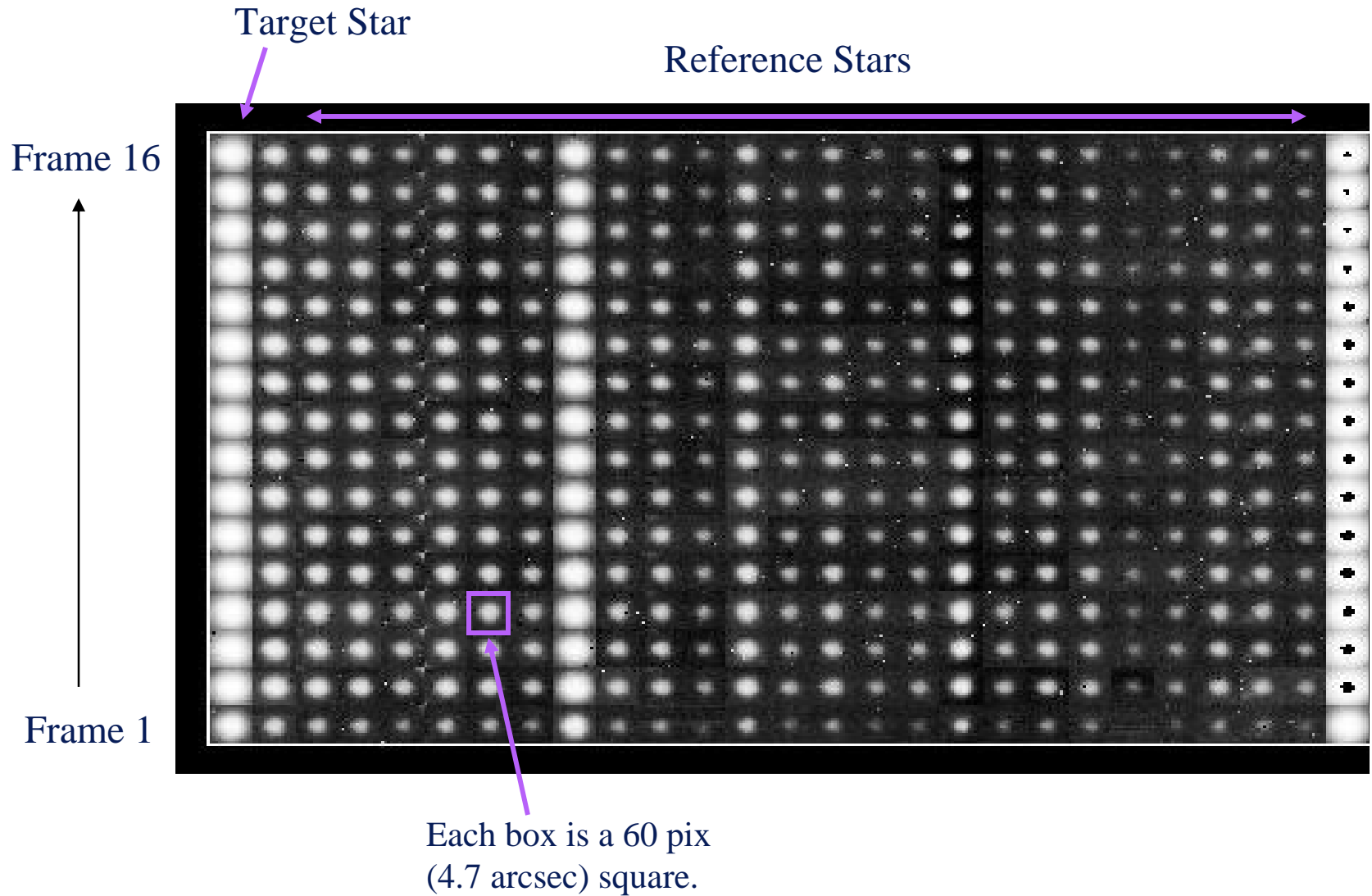


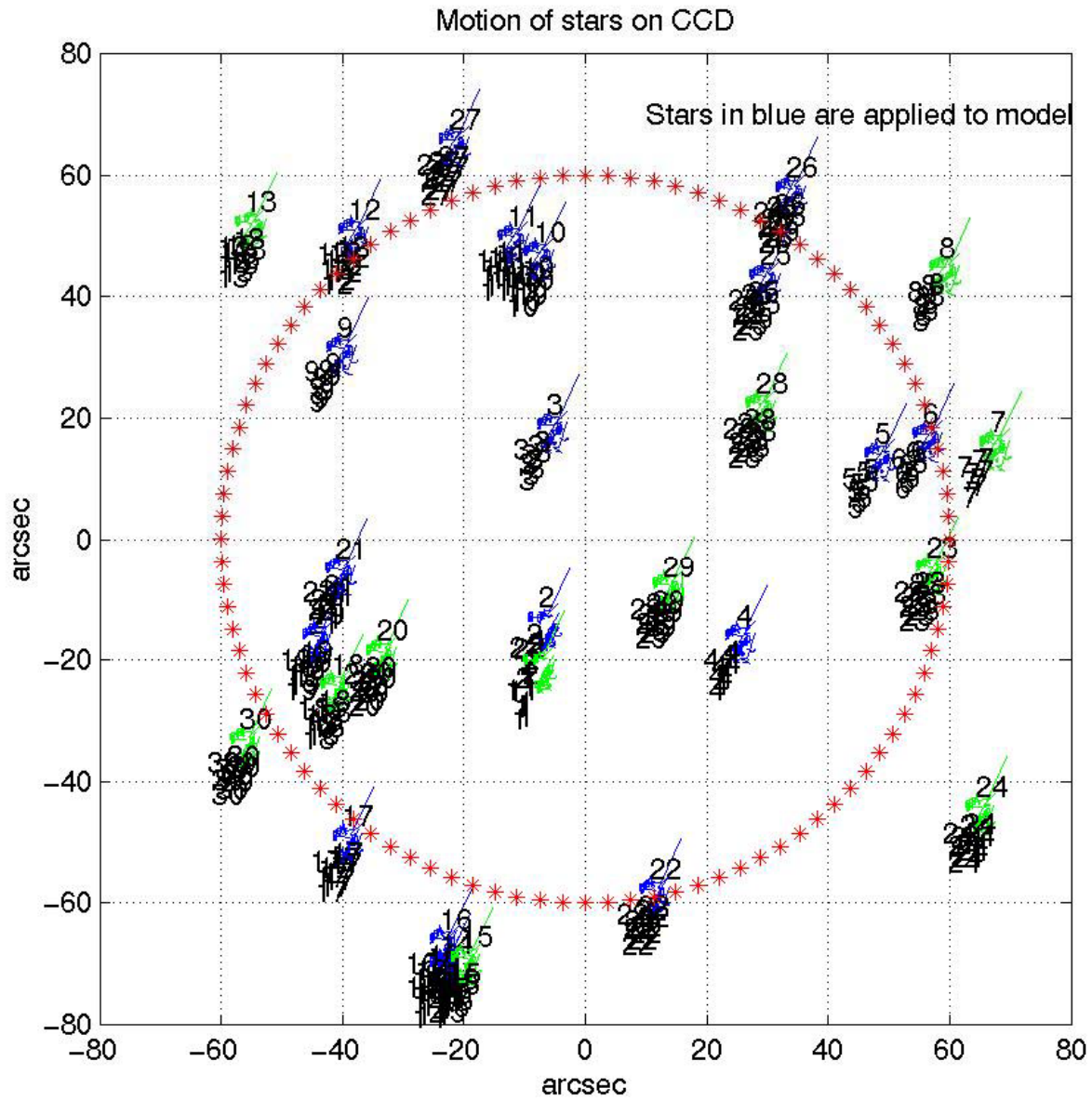


Stars extracted from one night, one field



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Centroid Pre-processing



- **Step 1: Flatfield image**
 - Fit quadratic function in each of the 4 quadrants.
- **Step 2: Find stars, center in 60 pixel (4.7 arcsec) box**
 - Center the star in the box using a standard centroid
 - (This is not the high precision centroid.)
- **Step 3: Remove horizontal artifacts**
 - Occasionally we see noise pick-up during readout, appears as aperiodic horizontal offset.
- **Step 4: Median filter images**
 - Use 7-pixel wide median filter line by line in x (Dec) then in y (RA).
 - Removes hot-pixels, cosmic rays

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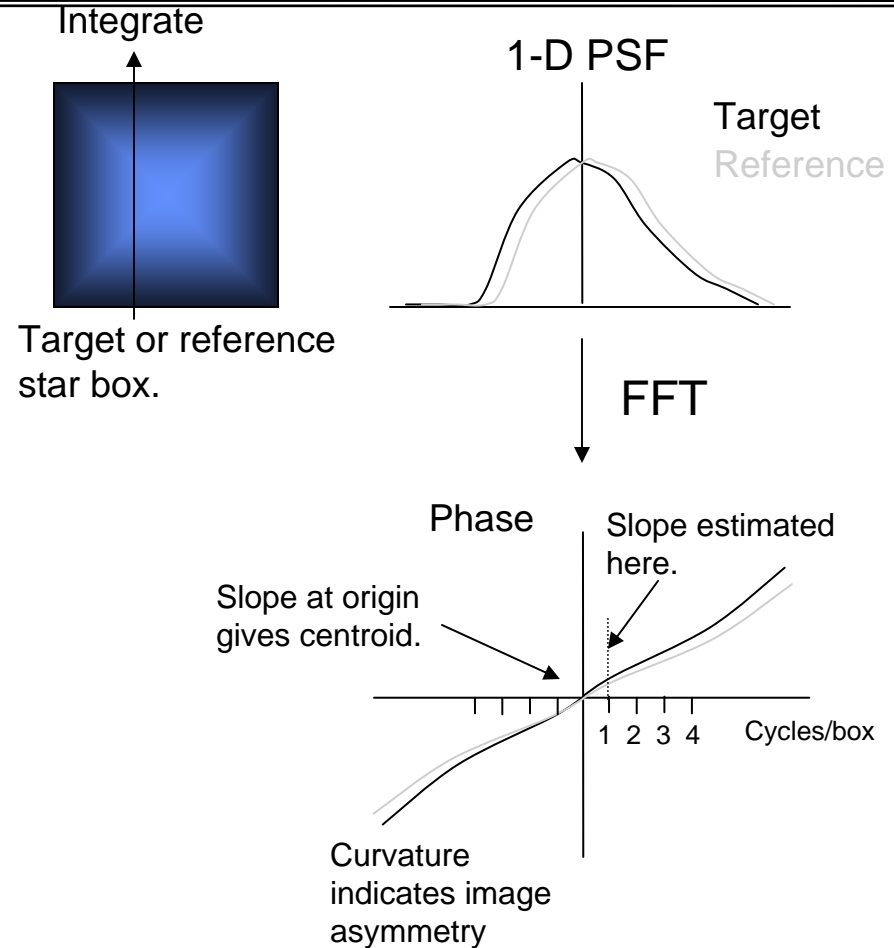


STEPS Cross-Correlation Centroiding



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- **Step 1: Integrate images in 1-dimension.**
 - We will compute x and y centroids in separate steps. We do not do joint (x,y) estimation.
- **Step 2: Compute FFT of 1-D image.**
- **Step 3: Estimate slope at origin using 1st point (1 cycle per box) of FFT.**
- **STEP 4: Compare slope to that of target star.**
 - Slope difference yields relative centroid position.
- **NOTE 1: Slope at origin of FFT is mathematically identical to the centroid.**
 - Our first frequency value is an approximation to the slope.
- **NOTE 2: Constant background bias gives delta-function at origin, but does not change slope.**





Advantages of Cross-Correlation approach



- **Insensitive to background bias**
 - Constant background does not need to be estimated and does not affect position measurement.
- **Good SNR**
 - Most of the energy is in the first spatial frequency.
 - High frequencies can be used and weighted by the FFT amplitude function.
 - We currently do not use these points
- **No separate matched-filtering function to compute**
 - The target star is the image template
- **No resampling required**
 - Image is already sampled well above Nyquist.
- **Fast**
 - 1-D 60 point FFT

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STEPS Conformal Model



- We generally use a 6-term model:

$$RA = a * RA + b * Dec + c$$

$$Dec = d * RA + e * Dec + f$$

- This requires a minimum of 3 reference stars.
- Allows different magnification in two axes
- Cross term (RA*Dec) is needed for ‘keystone’ caused by CCD tilt, system misalignment.
 - Expected to be negligible, ~ 150 uas peak at edge of 1 arcminute radius for 200 um of CCD tilt.
 - Also should be very stable because CCD is hard-mounted.
- Performance is only slightly better than simple rotation/translation model.

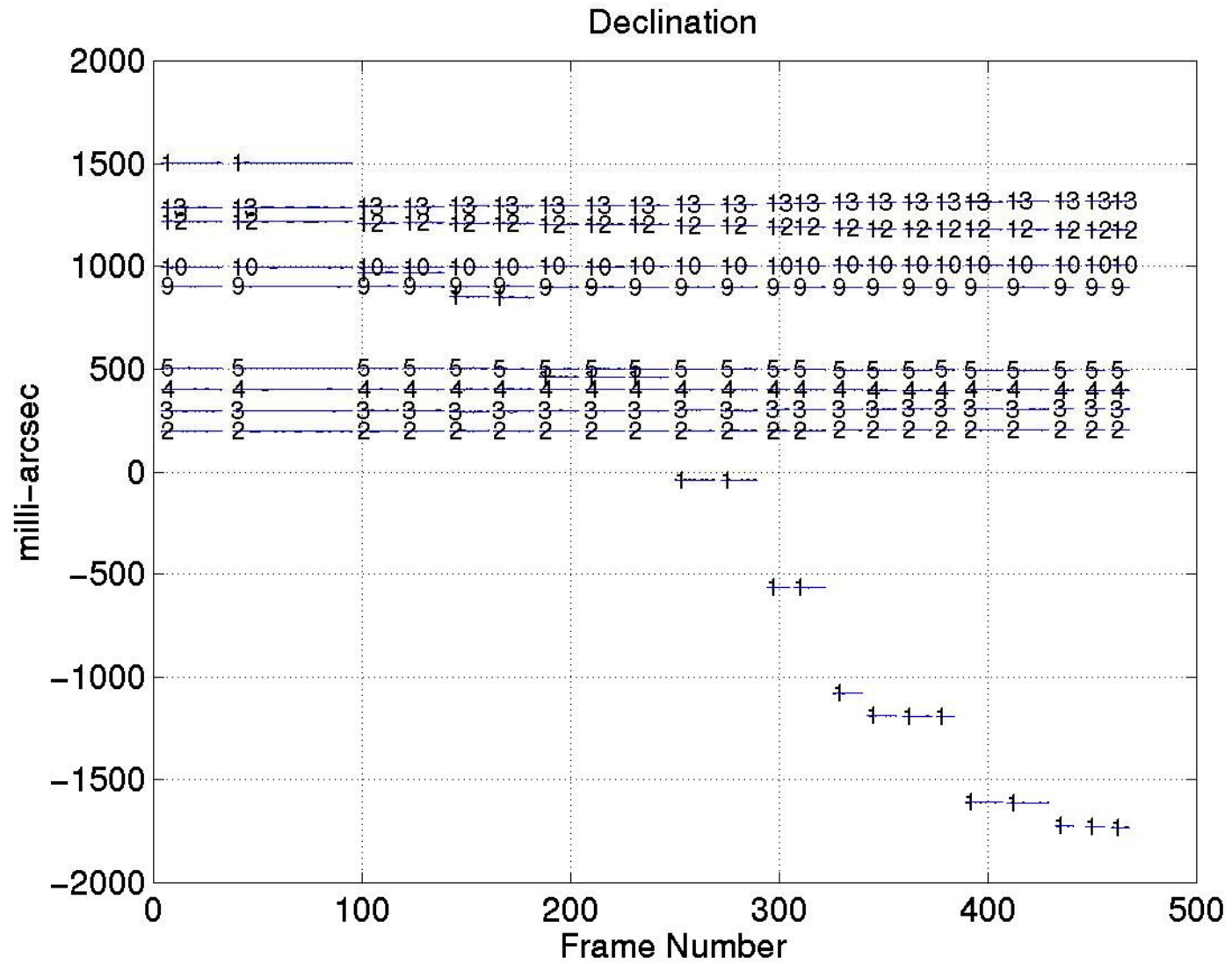
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Frame-by-Frame Astrometry



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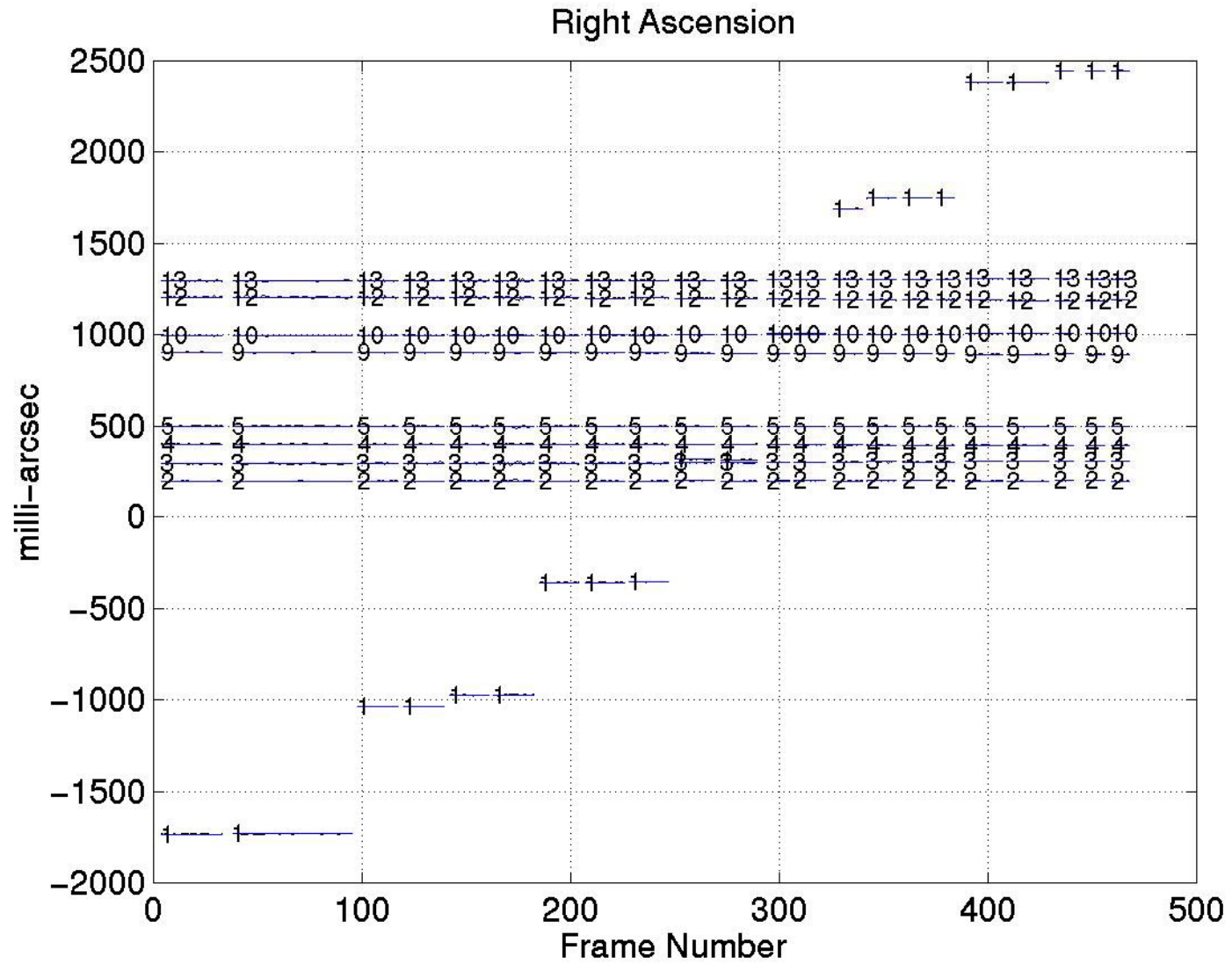




Frame-by-Frame Astrometry



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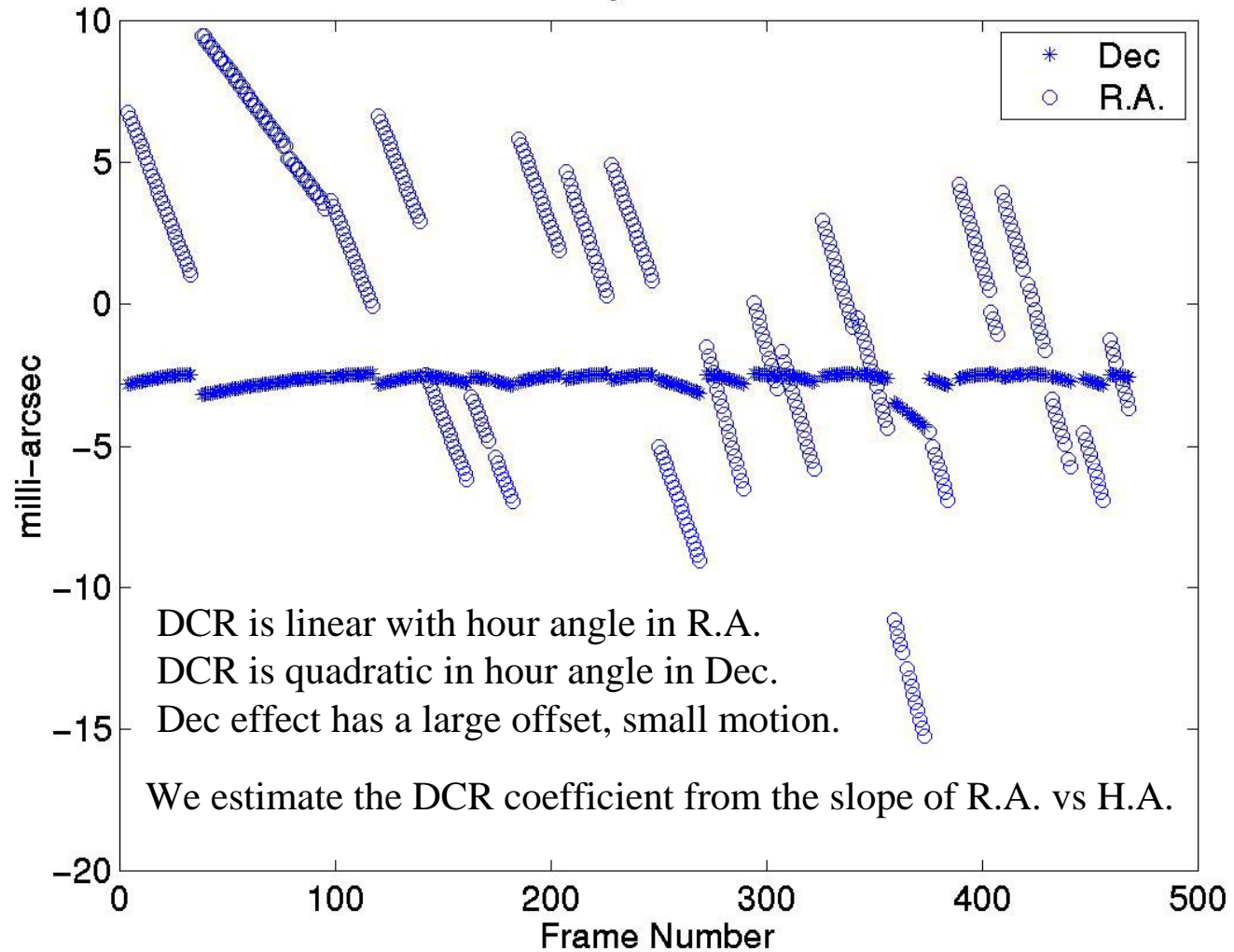




Differential Chromatic Refraction



GL777B: Frame-by-frame DCR Correction



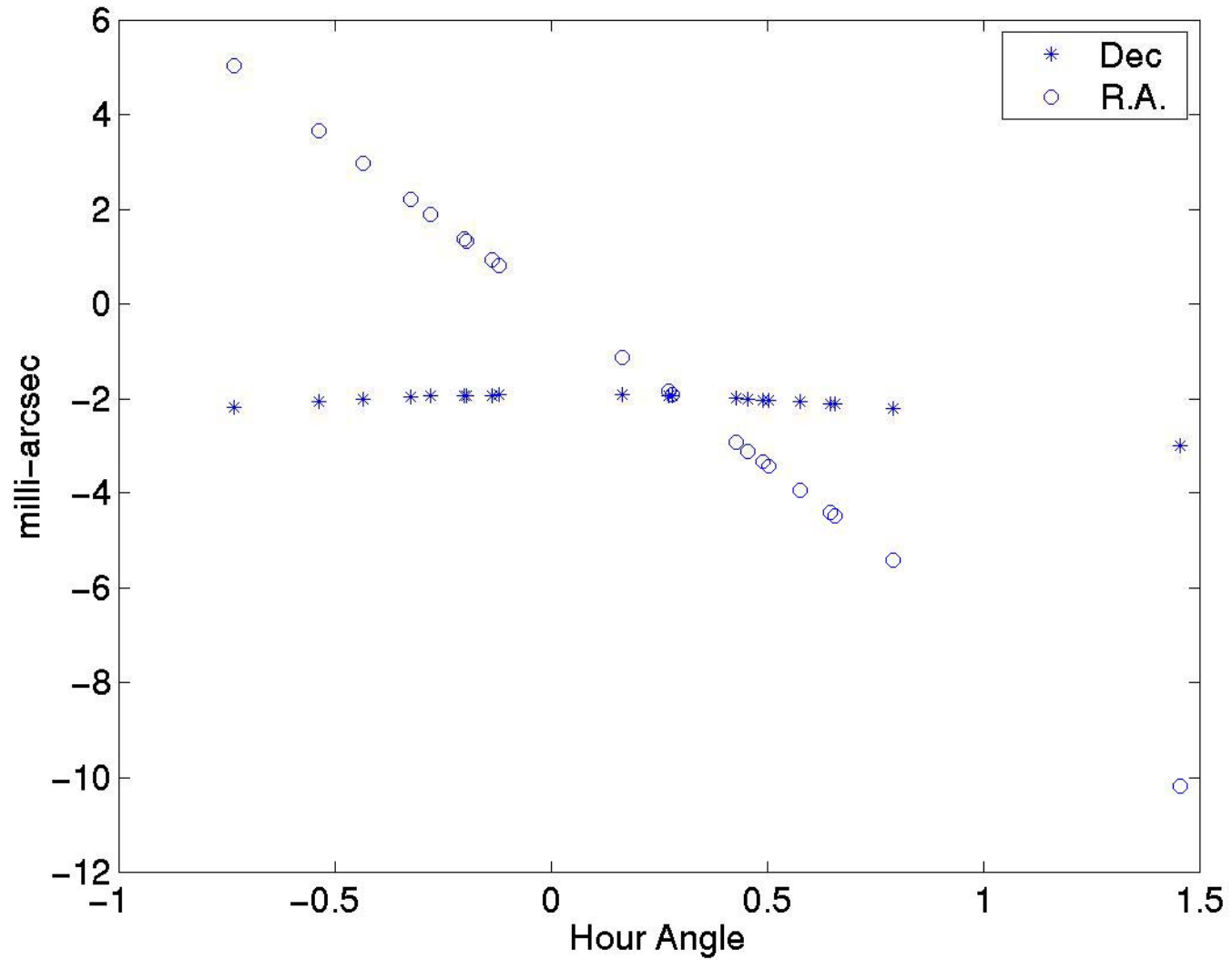
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Relative DCR Correction vs. Hour Angle



GL777B: Relative DCR Correction



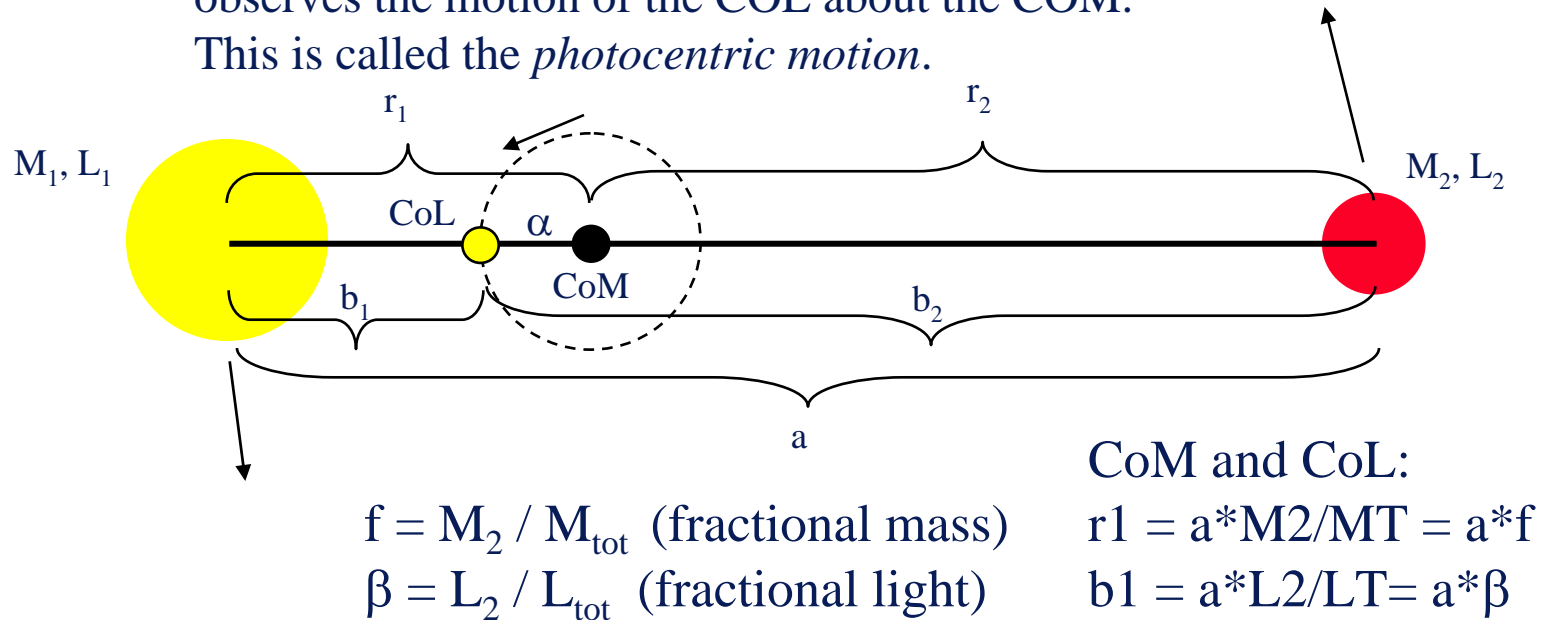
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Motion of Center of Light about Center of Mass: Photocentric Orbit



For unresolved systems (< 1 arcsec separation), STEPS observes the motion of the COL about the COM.
This is called the *photocentric motion*.



STEPS Measures:

$$\alpha = \text{CoL} - \text{CoM} = r_1 - b_1 = a * (f - \beta)$$

$$\alpha / a = \text{ratio of photocentric to Keplerian orbit} = f - \beta$$

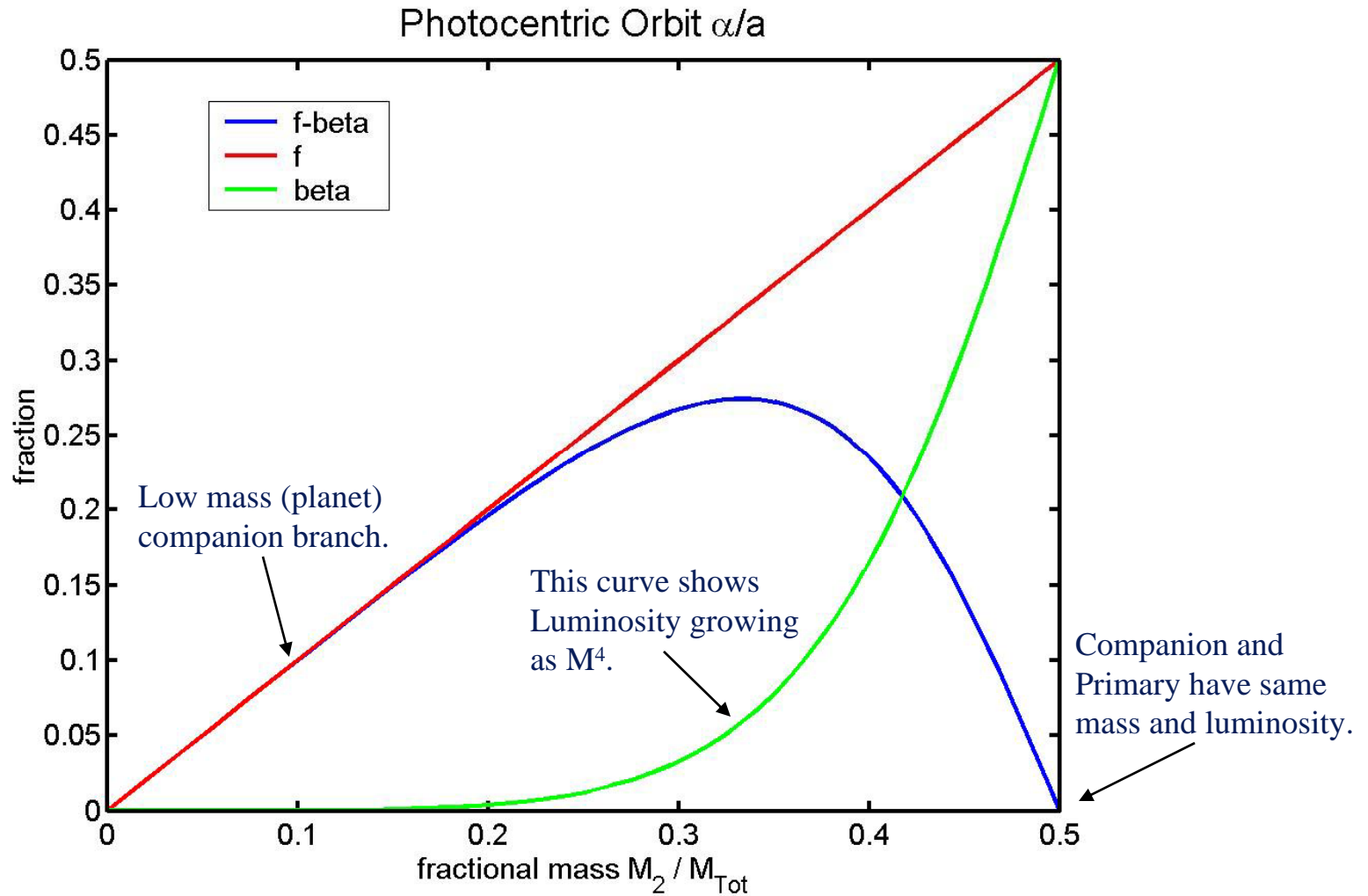
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Photocentric Motion vs. Fractional Mass



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How to determine companion mass



STEPS determines orbital parameters (P, ecc, incl, epoch, orientation) and photocentric motion α .

**A high-resolution image determines the flux ratio (β).
It also determines scale (a) when a companion is visible.**

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Case 1: no light from companion ($\beta = 0$)

STEPS constrains $c=f^3*M_{\text{tot}}$



Mass-Luminosity Relationship provides M_1



M_2 is determined from $M_{\text{tot}} = M_1 + M_2$ and c

Case 2: Image detects a companion

STEPS constrains $c=f^3*M_{\text{tot}}$



Image determines scale (a) and flux ratio (β).



Mass ratio is determined from $f = \alpha/a + \beta$



M_{tot} is determined from Kepler $M = a^3/P^2$



GJ 777B

Residuals after fitting PM and Parallax



20.1 hr, +29.9°

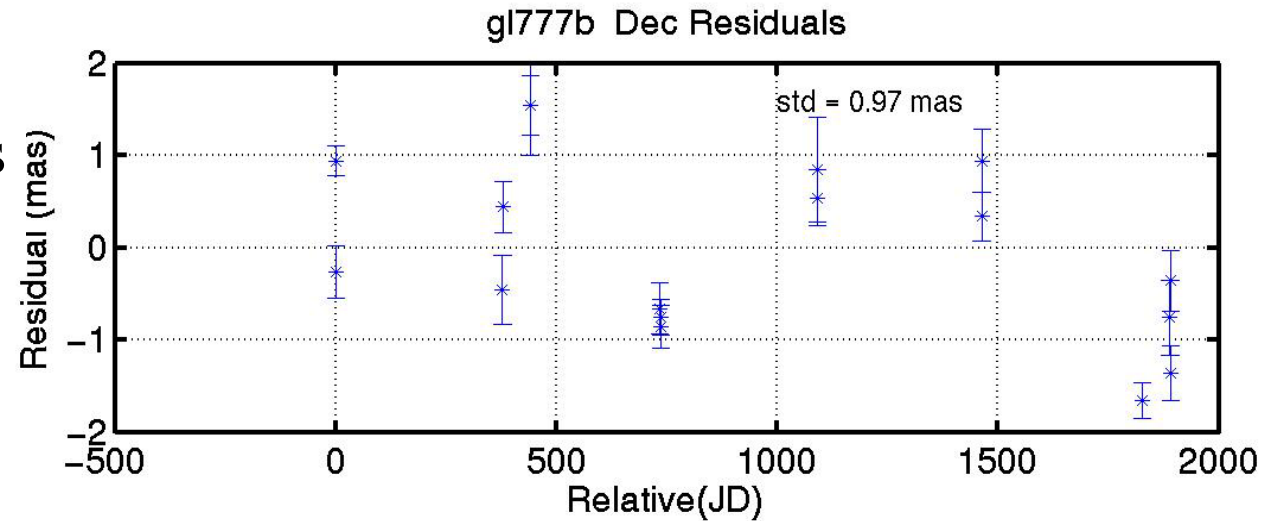
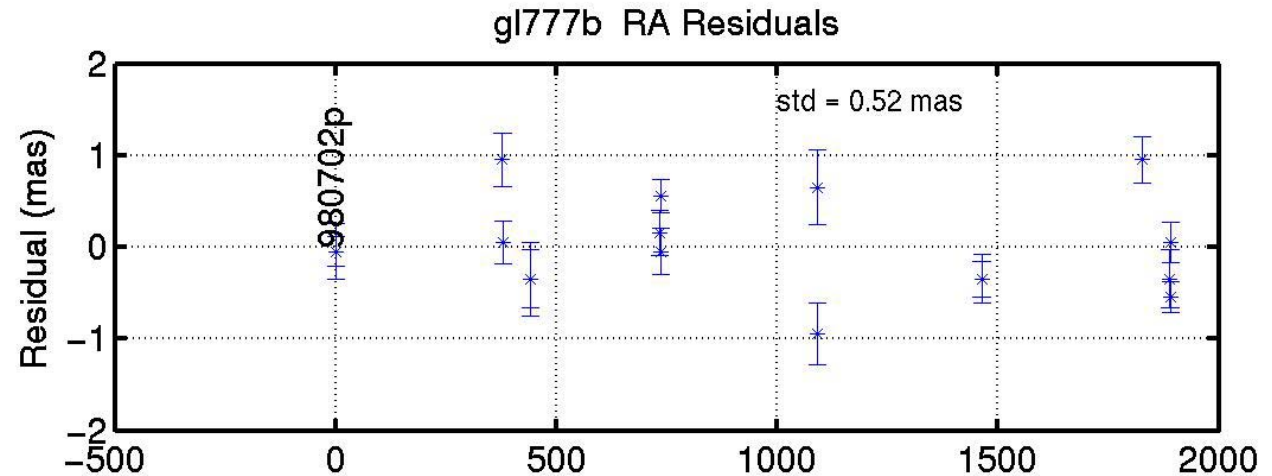
V=14.4

Spec M4.5

Parallax 61 mas

Note: primary is

G6IV, > 3 arcmin



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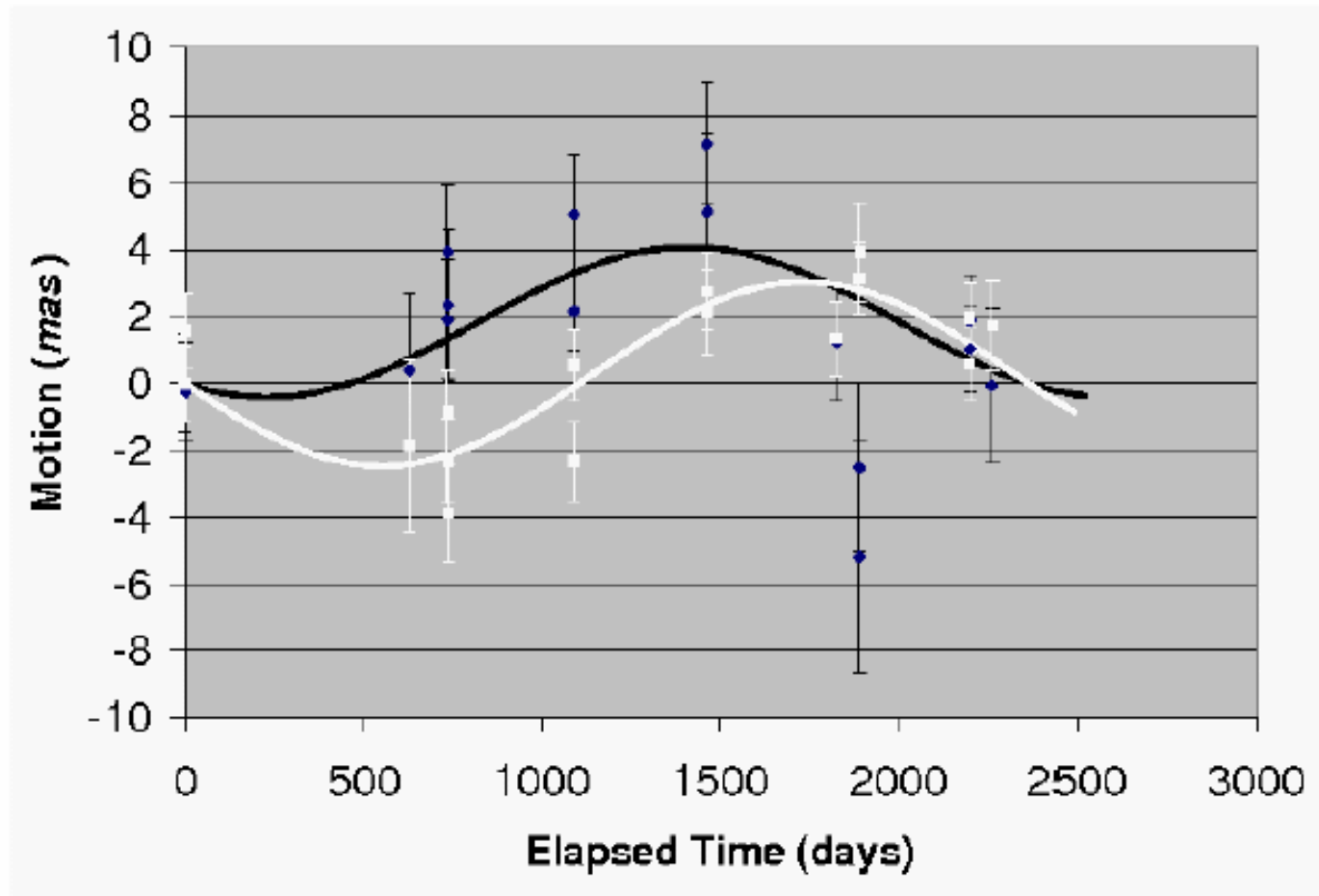
$$\sigma_{\text{RA}} = 0.52 \text{ mas}$$

$$\sigma_{\text{Dec}} = 0.97 \text{ mas}$$



GJ 1210

One possible orbit plotted with the data



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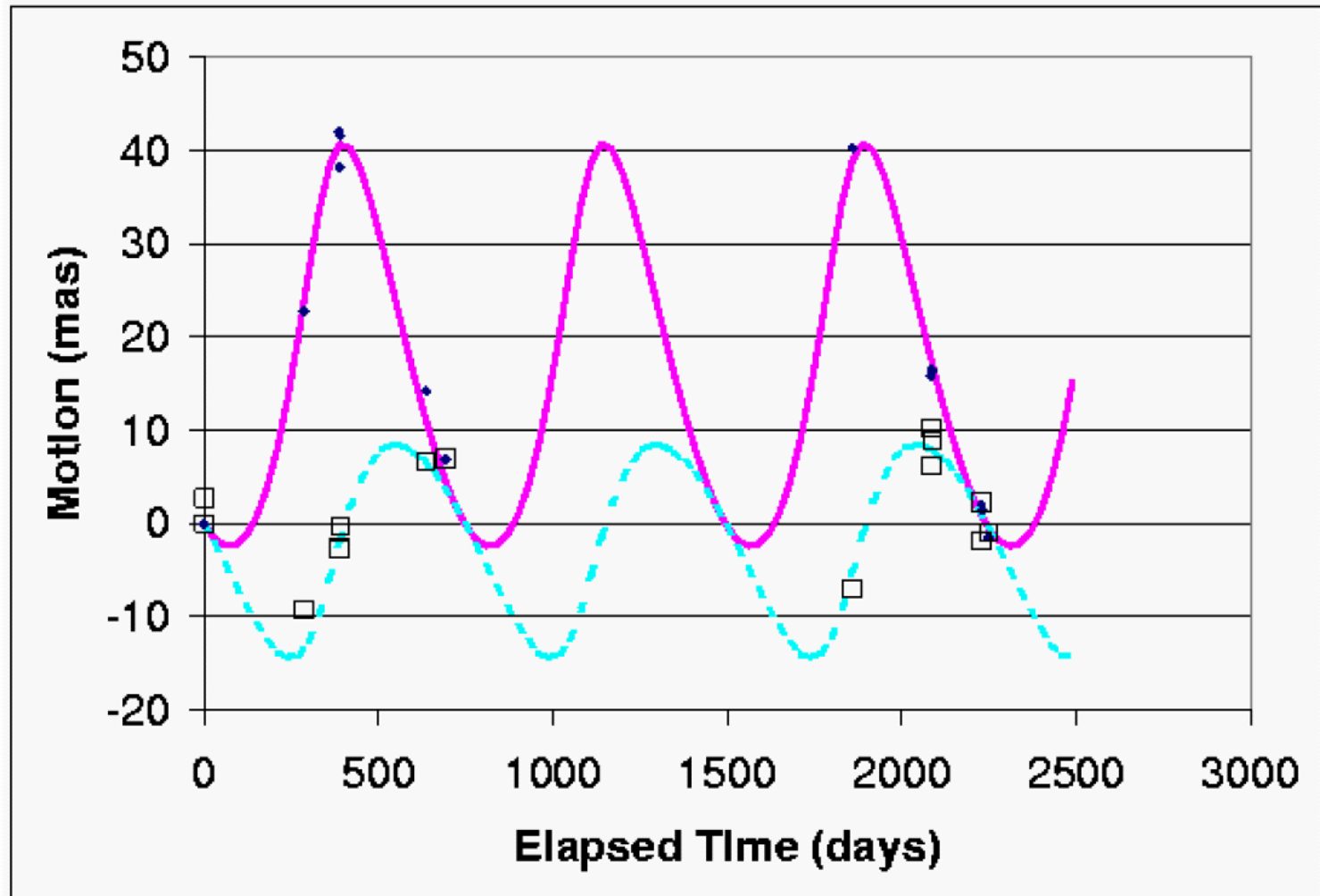


GJ 164

One possible orbit plotted with data



STEPS

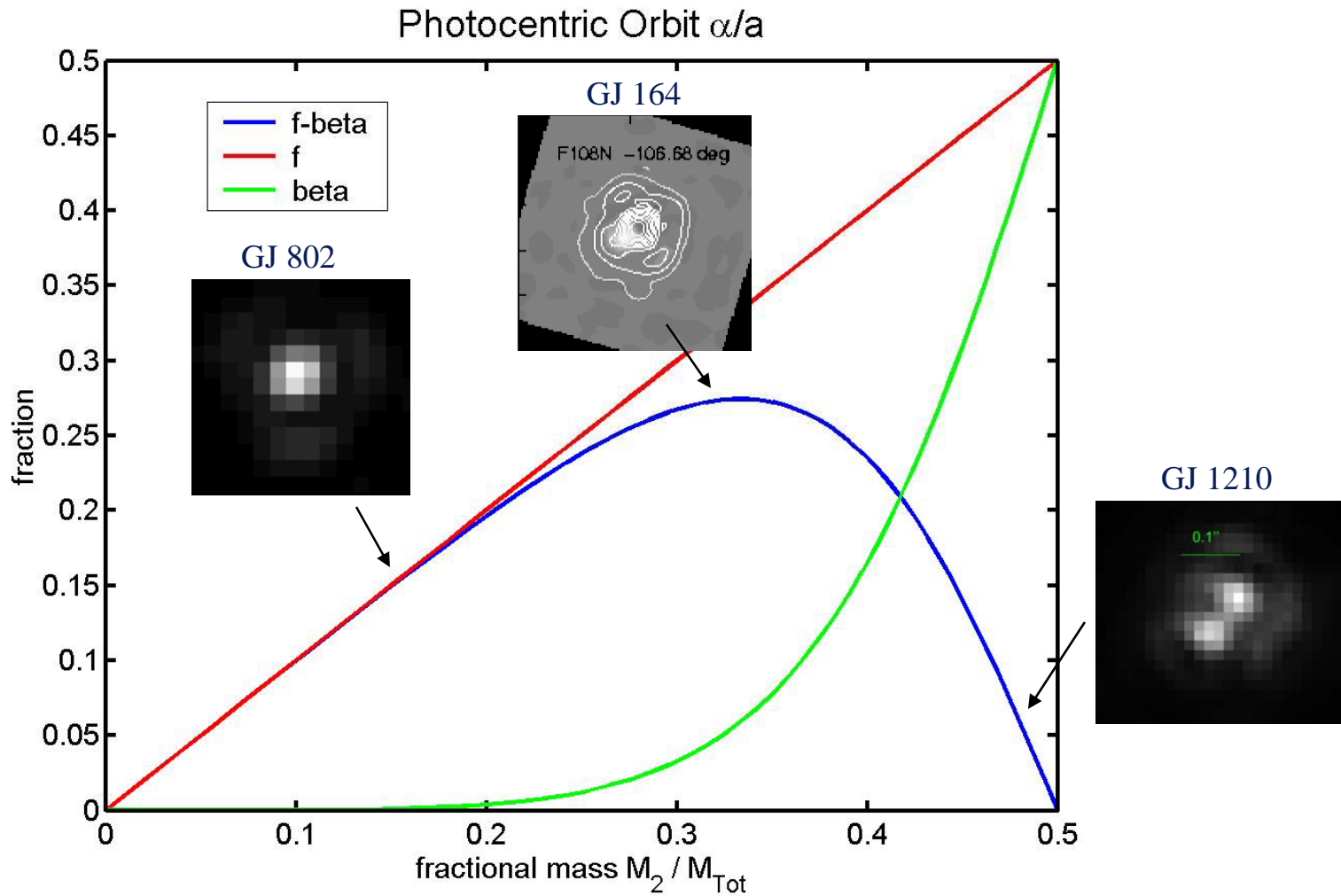




High-Resolution Imaging of STEPS Targets



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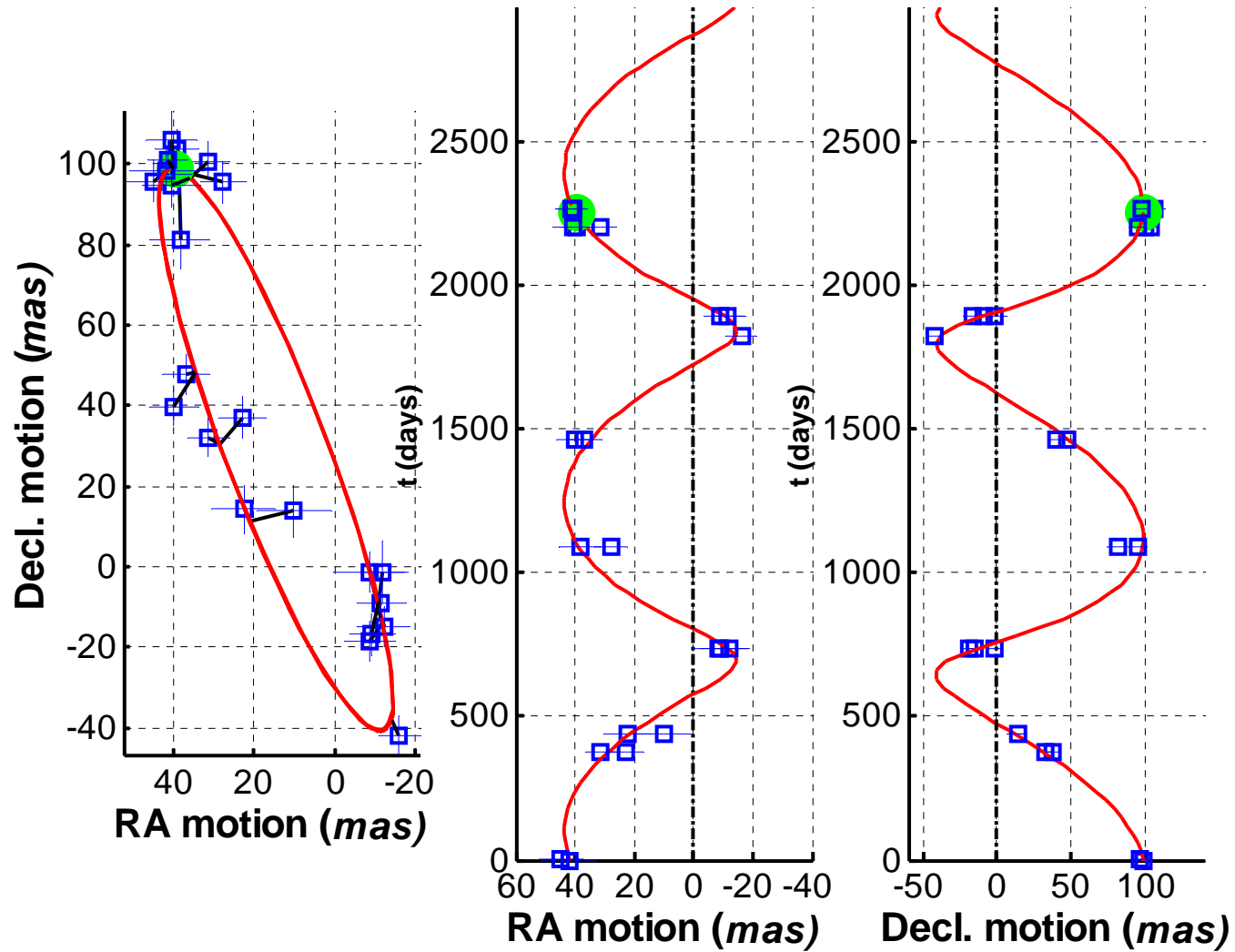


GJ 802

One possible orbit plotted with data, Keplerian frame

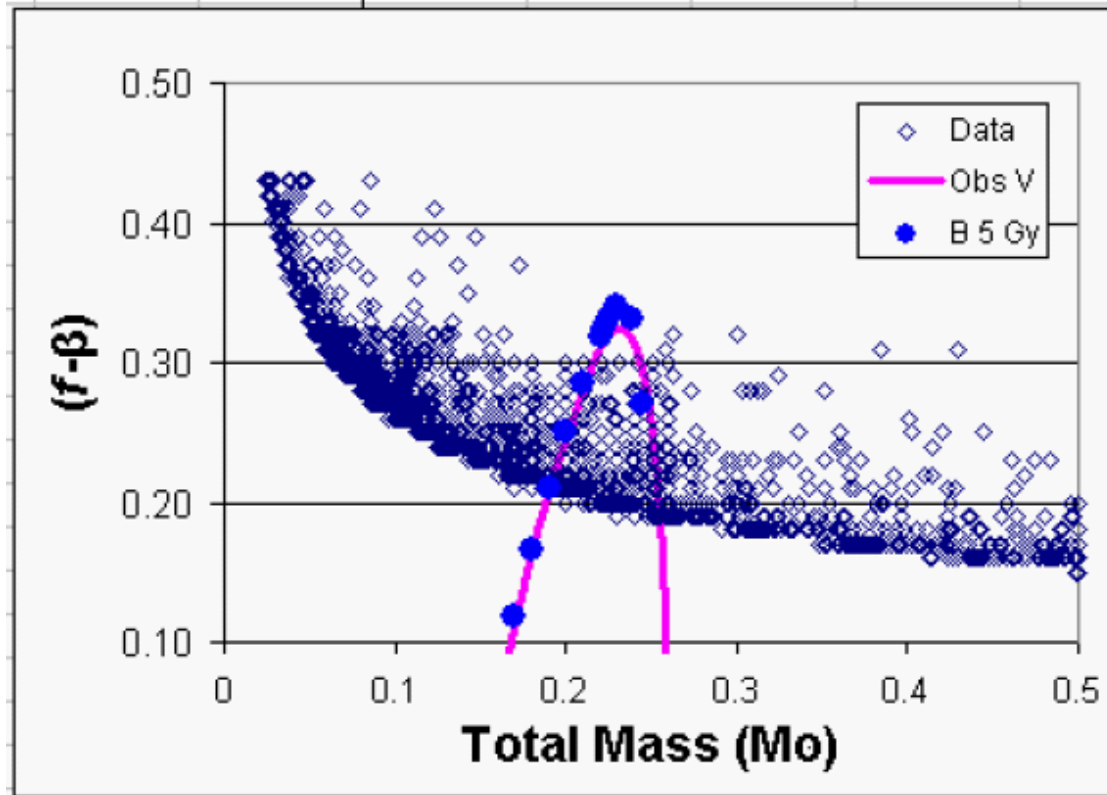


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GJ 802 Photocentric Orbit vs. Mass

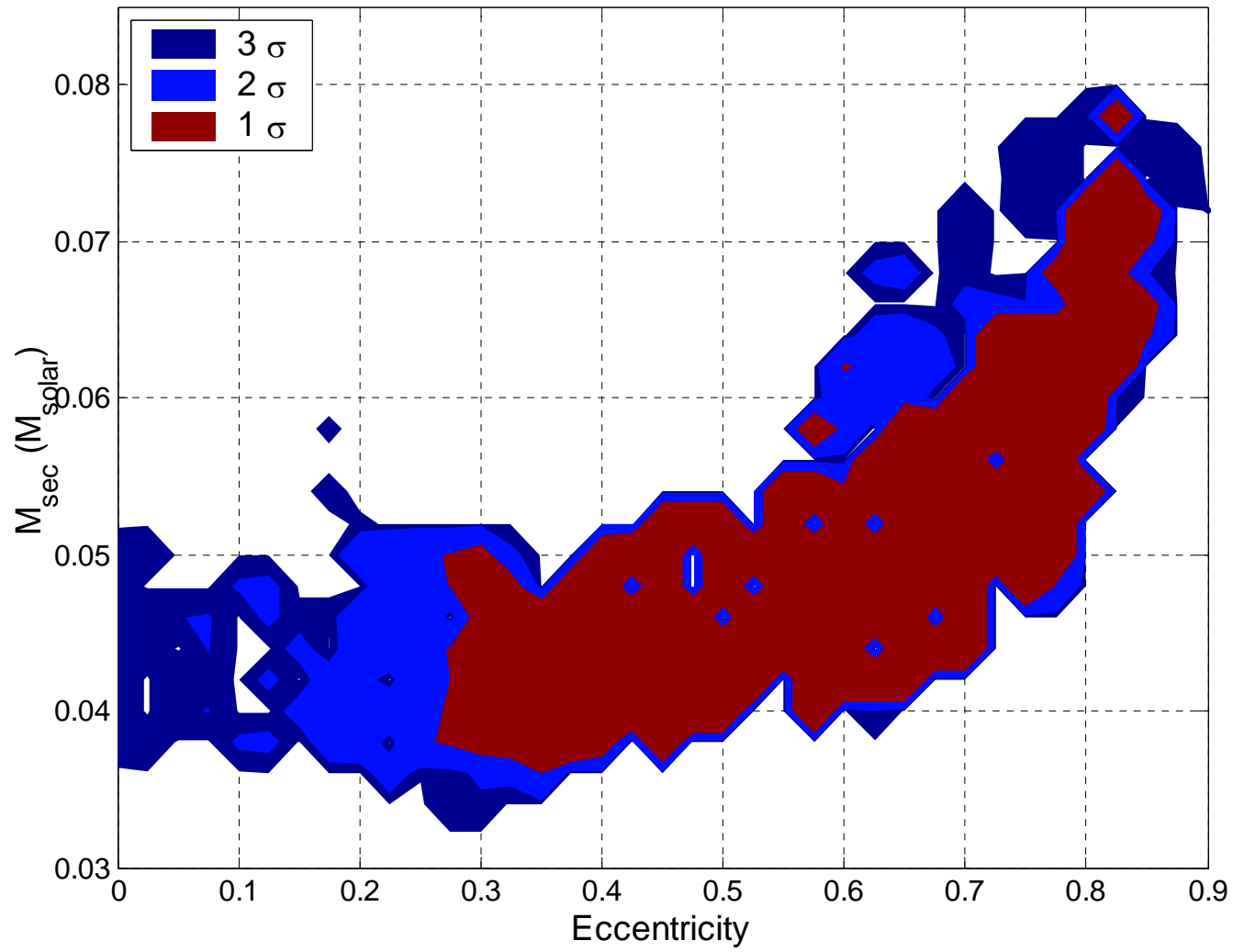


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The points show the results of $\sim 11,000$ Monte Carlo trials for the GJ 802 orbit. We plot $(f-\beta)$ vs. M_{rot} for all models falling within the one-sigma confidence limits. Superimposed on the data are the composite MLR curve in the V-band based upon observations (Henry et al. 1999) and the MLR points from the model of Baraffe et al. (2003).



GJ 802b Mass vs. Eccentricity



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GJ 802 Results



Table 1. GJ 802 Known Properties

RA (2000) ^a	20 43 19.41
Dec (2000) ^a	+55 20 52.0
V^b	14.69
J^c	9.563 ± 0.023
H^c	9.058 ± 0.019
K^c	8.753 ± 0.013
Type	dM5e
Parallax ^d (mas)	63 ± 5.5
Proper Motion ^e (mas y ⁻¹)	1915 ± 13
Position Angle ^e (deg)	27.6 ± 0.6

Table 2. STEPS Astrometric Measurements^a of GJ 802

Relative Parallax (mas)	61 ± 2
Proper Motion (mas y ⁻¹)	1933 ± 1
Position Angle (deg)	27.0 ± 0.1
Period (y)	3.14 ± 0.03
Total Mass (M _⊙)	0.215 ± 0.045
Semi-Major Axis (AU)	1.28 ± 0.10
Eccentricity, e	0.56 ± 0.30
Inclination (deg)	80.5 ± 1.5
Lon. Asc. Node ^b (deg)	17.5 ± 3.5
Primary Mass, M_{pri} (M _⊙)	0.160 ± 0.03
Secondary Mass, M_{sec} (M _⊙)	0.057 ± 0.021

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STEPS progress through December, 2004



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Target	Type	M-Dwarf Companion	BD Companion	Clear Signal	Flatline	TBD	AO Signal	AO Null
1	M5					x		
2	M5				x			
3	M4			x				
4	M4					x		x
5	M3.5					x		
6	M3	x					Unpub	x
7	M4.5	x					GJ 164	x
8	M5					x		
9	M4.5					x		
10	M5			x				
11	M3.5	x					Unpub	x
12	M5			x				
13	M4					x		
14	M5					x		
15	M5					x		
16	>M6					x		
17	M4					x		
18	M3					x		
19	M3					x		
20	M5	x					GJ 1210	x
21	M5					x		
22	M8					x		
23	M5.5				x			
24	M4.5				x			
25	M5				x			
26	M5		x				GJ 802	x
27	M4				x			
28	M4.5					x		x
29	M5			x				x



STEPS Future



-
- **Continued observation at Palomar 200 in.**
 - We are in our 8th year, and have the sensitivity to detect Jupiter mass objects in 10-yr orbits around several stars.
 - **RV and imaging collaborations**
 - Flux ratios for MLR
 - Velocities for improved orbits
 - **Astrometric collaborations**
 - Overlapping target lists to confirm discoveries, improve orbital fits, help distinguish systematic errors from real motions.
 - **Investigate new HAWAII-2RG detectors: higher dynamic range possible**

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STEPS Papers



- **“Astrometric Discovery of GJ802b: In the Brown Dwarf Oasis?”** Pravdo, Shaklan, Lloyd, Accepted ApJ (2005).
- **“Discovering M-dwarf Companions with STEPS,”** Pravdo, Shaklan, Lloyd, Benedict, ASP Conf. Series, Astrometry in the Age of the Next Generation of Large Telescopes (Flagstaff, 2005).
- **“Astrometric Discovery of GJ164B,”** Pravdo, Shaklan, Henry, Benedict, ApJ 617, 1323-1329 (2004).
- **“Stellar Planet Survey,”** Pravdo & Shaklan, Scientific Frontiers in Research on Extrasolar Planets, ASP Conference Series, Vol 294, 107-110 (2003).
- **“Astrometric Detection of Extrasolar Planets: Results of a Feasibility Study with the Palomar 5 Meter Telescope,”** Pravdo & ApJ 465, 264-277 (1996)
- **“High-precision measurement of pixel positions in a charge-coupled device,”** Shaklan, Pravdo, Sharmon, Appl. Opt. 34, 6672-6681 (1995).

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